# FREE TRANSPORT FOR CONVEX POTENTIALS 

Yoann Dabrowski, Alice Guionnet, and Dima Shlyakhtenko<br>(Received 27 March, 2021)


#### Abstract

We construct non-commutative analogs of transport maps among free Gibbs states satisfying a certain convexity condition. Unlike previous constructions, our approach is non-perturbative in nature and thus can be used to construct transport maps between free Gibbs states associated to potentials which are far from quadratic, i.e., states which are far from the semicircle law. An essential technical ingredient in our approach is the extension of free stochastic analysis to non-commutative spaces of functions based on the Haagerup tensor product.


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## 1. Introduction

We would like to dedicate this paper to the memory of Vaughan Jones. It is no exaggeration to say that Vaughan's work in mathematics and mathematical physics has been an inspiration for hundreds of mathematicians worldwide. He was responsible for breakthrough results in a number of subjects, including von Neumann algebras, subfactor theory (a subject he initiated), and low-dimensional topology, to name just a few. For so many of us, he was a personal friend, a mentor and a guide into the wonderful world of amazing mathematics. He is terribly missed by us all.

Vaughan had also the talent to organize inspiring conferences in beautiful places, like Maui and New Zealand. These were places to work hard, but also to enjoy nature and gather together. These were places where often people from very different backgrounds, from physics and mathematics, would meet and communicate, if not during the talks, in the afternoon beach sessions. This was a place for discovery. The second author of the present paper had the chance to give a mini-course at the New Zealand Mathematics Research Institute summer school about random matrices in 2019. This was a very inspiring conference, with many researchers and students from different backgrounds but a common amazing curiosity. Talks were given on very small white boards which had the advantage of limiting the amount of information, but increase its communication. A large part of the afternoons was free, dedicated to hikes, walking on the beach, and to kite surfing for Vaughan and some other participants. Vaughan was very eager to share beautiful mathematics, but also the beauty of his country and the kiwis. Alice and her husband will always be grateful to Vaughan and NZRMI organizers for sharing their piece of paradise.

The subject of this paper is related to Vaughan's work in several ways. In joint work with Vaughan and the second and third-named authors [GJS10], we made a connection between free probability, random matrices, and quantum symmetries that arise in subfactor theory. Vaughan's dream was to understand if phase transitions associated with random matrix models could somehow be connected to subfactors. Our past work on non-commutative transport [GS12] as well as the present paper are small steps in the direction of developing the tools that could describe these phase transitions, and perhaps someday realize some version of Vaughan's dream. On a technical level, several of the Haagerup tensor product constructions, in particular the cyclic Haagerup tensor product, are motivated by subfactor theory and may be of interest in the study of infinite-index subfactors. Finally, a byproduct of our results is the extension of isomorphism results of [GS12] to the non-perturbative regime, identifying the isomorphism classes of Neumann algebras associated to free Gibbs states that are in a certain sense convex.

A transport map between two probability measures is a function pushing the first measure onto the second. Finding transport maps which minimize a certain cost function is the central question in transportation theory. It was formalized by Monge in the eighteenth century, studied by Kantorovich during World War II and has known major advances in the last twenty years, starting with a work of Brenier [Bre91], see also the very inspiring book by Villani [Vil03]. In fact, the mere existence of a transport map is itself not completely trivial and was proved by von Neumann in 1930s, under very weak assumptions, as part of the program to classify measure spaces.

A central question is to find appropriate generalizations of this result to the non-commutative setting, where measures are replaced by non-commutative distributions, that is, tracial states. In this case, there is no notion of density but in certain instances arising in Voiculescu's free probability theory, integration by parts makes sense. It gives the adjoint in $L^{2}$ of Voiculescu's free difference quotient [Voi98], and is often a (cyclic) derivative of a non-commutative function that we call a potential (see [Voi00, Voi02]).

Non commutative laws which are characterized by a free probabilistic integration by parts formula are called free Gibbs laws (see e.g. [Gui06]). In [GS12], two of the authors of this article constructed transport maps between a class of free Gibbs laws. They used ideas going back to Monge and Ampère, based on the remark that transport maps must satisfy an equation given by the change of variables formula. Solving this equation yields a transport map. Unfortunately, this equation was only solved in [GS12] in the case of potentials which are small perturbations of quadratic potentials, i.e., certain small perturbations of Voiculescu's free semicircular law. Already this result yielded isomorphisms between the associated $C^{*}$ and von Neumann algebras in such perturbative situations, solving a number of open questions [Voi06]. In particular, this approach was used to show that the $C^{*}$ and von Neumann algebras of $q$-Gaussian laws [BS91] are isomorphic for sufficiently small values of $q$.

The goal of the present article is to consider non-perturbative situations. We will see that we can tackle situations where the potential is "strictly convex" (in a sense we will make precise later). The idea is once again to use a non-commutative version of the Monge-Ampère equation, but now to solve it by interpolating the potential between the two given laws. This requires solving a Poisson type equation. The latter, in strictly convex situations, can be solved by using the associated (free) semi-group. However, this program meets several difficulties in the noncommutative setting. First, smoothness properties of the semi-group have not been studied so far. Furthermore, the appropriate notion of convexity has not yet been formulated. We detail our framework in Section 2, leaving to the appendix the elaboration of most of its properties. In Section 3, we study the semi-group defined in this framework and derive its properties. Based on this, we finally construct the transport map in Section 4.

In the rest of this section, we detail the classical construction of transport maps from which we took our inspiration, and explain how it generalizes to the case of a single non-commutative variable. We then consider the general non-commutative multi-variable case and state our main theorem.

The key technical underpinning of our paper is the existence of a collection of non-commutative function spaces whose definition and study was initiated by the first-named author in [Dab15] and which are well behaved in several ways. These non-commutative "functions" can be evaluated in $n$-tuples of self-adjoint variables living in the relative commutant of a von Neumann algebra $D$, and depend both on the $n$-tuple and the choice of a conditional expectation on $D$. Such functions can be composed. Moreover, our function spaces describe a kind of $C^{k}$ regularity, so that differential operators from Voiculescu's free probability - non-commutative difference quotients and cyclic derivatives - can each be applied a certain number of times to our functions. The resulting differential calculus makes it possible to formulate and solve non-commutative versions of certain partial differential equations that ultimately yield our transport maps.

In our approach to function spaces, we used a version of the Haagerup tensor product, whose operator space properties and especially behavior under taking conditional expectations make it especially suitable for our construction. To deal with cyclic derivatives and appropriate closures of cyclically invariant polynomials arising in free probability theory, we also describe a cyclic version of the Haagerup tensor product. Its construction is motivated by Jones's subfactor theory, and (although we do not pursue this direction in the present paper) could be of independent interest in that context.

We should mention that in the case $D=\mathbb{C}$, there is an alternative (and also wellbehaved) suite of non-commutative function spaces developed by D. Jekel [J19] after our work first appeared in preprint form. His approach to the definition of these spaces is different from ours, and has the advantage of constructing examples of convex functions more easily. In [JLS21] Jekel, Li and the third-named author have used those function spaces as well as several ideas from the present paper to describe a kind of information geometry "Wasserstein manifold" structure on the space of free Gibbs laws which are close to the semicircle law, as well as to construct transport maps that are associated to more general paths in this manifold (in the present paper we only consider affine interpolations between potentials defining the free Gibbs laws). It would be interesting to elucidate the relationship between the two different approaches to non-commutative function spaces and in particular between the associated notions of convexity - based on contractivity of certain semigroups (as in the present paper) or positivity of the Hessian (as in Jekel's approach).

Our motivation to consider more general $D$ is two-fold. The first is to consider the crossed product $D \rtimes \mathbb{F}_{n}$ of an action of the free group on $D$, as well as its $q$-deformation $[\mathbf{J L U 1 4}, \mathbf{J U 1 9}]$. At this point we did not verify that these deformations correspond to potentials that satisfy our assumptions (for $q$ small enough). The motivation to also consider the algebra $B$ comes from the analysis of the free product $\left(D \rtimes \mathbb{F}_{n}\right) *_{D}\left(W^{*}\left(S_{s}, s \leq t\right) \otimes D\right)$; in this case $B=D \rtimes \mathbb{F}_{n}$. Being able to construct transport maps in this setting would allow us to construct solutions of free SDE's with initial conditions in $B$ as the image by transport maps of some process $S_{t_{1}}, \ldots, S_{t_{n}}$. For instance, one would want to obtain solutions of free SDE's similar to those considered in [Shl09] in the context of crossed product and for non-algebraic cocycles. Building such solutions in free products with amalgamation could enable the use of techniques similar to those in $[\mathbf{D I 1 6}, \mathbf{I o 1 5}]$ and would
lead to the study of algebras $B$ by a free transport approach, for instance to answer questions such as uniqueness of the Cartan decomposition up to unitary conjuguacy for non-trivial actions when $\Gamma$ is a group with positive first $\ell^{2}$ Betti number. Such interesting applications would require consideration of non smooth potentials $V$, something which is still far from our reach. However, we feel that these potential applications outweigh the small additional difficulties involved in considering the more complex setting with non-trivial algebras $B$ and $D$. Thus our article lays the groundwork for future developments in this direction and our main example of relative algebra $B$ is exactly the kind of crossed-product that could be interesting for the above-mentioned applications.
1.1. Classical construction of transport maps. For any suitable real-valued function $U$ from $\mathbb{R}^{d}$ to $\mathbb{R}$ we define the probability measure

$$
\mu_{U}(d x)=\frac{1}{Z_{U}} e^{-U(x)} d x, \quad Z_{U}=\int e^{-U(x)} d x
$$

We let $V$ and $V+W$ be two functions going fast enough to infinity so that $Z_{V}$ and $Z_{V+W}$ are finite. We would like to construct $F: \mathbb{R}^{d} \mapsto \mathbb{R}^{d}$ so that $\mu_{V+W}=F \# \mu_{V}$, i.e., so that for all test functions $h$

$$
\int h(F(y)) d \mu_{V}(y)=\int h(x) d \mu_{W}(x)=\int h(F(y)) \operatorname{Jac}(F)(y) e^{-(V+W)(F(y))} d y / Z_{W}
$$

where $\operatorname{Jac}(F)$ denotes the Jacobian of $F$. We have simply performed the change of variables $x=F(y)$ in the last line, assuming that $F$ is $C^{1}$. We therefore deduce that $F$ should satisfy the transport equation:

$$
\begin{equation*}
V(y)=(V+W)(F(y))-\ln \operatorname{Jac}(F)(y)+C \tag{1}
\end{equation*}
$$

for almost all $y$ where we set $C=\ln Z_{V+W}-\ln Z_{V}$.
If $V-W$ is small we can seek a solution $F$ which is close to identity, so that its Jacobian stays away from zero and therefore does not get close to the singularity of the logarithm. The resulting equation can in turn be solved by the implicit function theorem. Such arguments were extended to the non-commutative setting in [GS12].

To solve the transport equation in a non-perturbative situation, we shall in this article proceed by interpolating the potential. Namely, let us consider potentials $V_{\alpha}=\alpha W+V$ and seek to construct a transport map $F_{\alpha}$ of $\mu_{V}$ onto $\mu_{V_{\alpha}}$. The advantage of smooth interpolation is that transporting $\mu_{V_{\alpha}}$ onto $\mu_{V_{\alpha+\varepsilon}}$ can a priori be solved for $\varepsilon$ small enough by the previous pertubative arguments, and the full transport $F_{1}=F$ of $\mu_{V}$ onto $\mu_{W}$ can then be recovered by integration along the interpolation.

In fact, we shall solve the transport equation (1) under the additional restriction that $F$ evolves according to a gradient flow: $\partial_{\alpha} F_{\alpha}=\nabla g_{\alpha}\left(F_{\alpha}\right)$. It turns out that $g$ must then be a solution of the Poisson equation

$$
\begin{equation*}
L_{V_{\alpha}} g_{\alpha}=W+\partial_{\alpha} \ln Z_{V_{\alpha}} \tag{2}
\end{equation*}
$$

with $L_{V_{\alpha}}=\Delta-\nabla V_{\alpha} . \nabla$ the infinitesimal generator of the diffusion having $\mu_{V_{\alpha}}$ as its stationary measure. Solving the Poisson equation (2) amounts to inverting $L_{V_{\alpha}}$, that is, finding the Green function of the differential operator $L_{V_{\alpha}}$. This is a well known problem which can be solved under various boundary conditions or
growth conditions on $V$ at infinity. To simplify we shall assume that $V_{\alpha}$ (that is $V$ and $V+W)$ are uniformly convex. This insures that the semi-group $P_{s}^{\alpha}=e^{s L_{V_{\alpha}}}$ converges uniformly towards the Gibbs measure $\mu_{V_{\alpha}}$ as $s$ goes to infinity. More precisely, there exists some $c>0$ such that for all Lipschitz functions $f$ with bounded Lipschitz norm $\|f\|_{L}$ we have

$$
\left\|P_{s}^{\alpha} f-\mu_{V_{\alpha}}(f)\right\|_{\infty} \leq 2 e^{-c s}\|f\|_{L}
$$

As a consequence we can solve the Poisson equation (2) by setting

$$
\begin{equation*}
g_{\alpha}(x)=\int_{0}^{\infty} P_{s}^{\alpha}\left(W+\partial_{\alpha} \ln Z_{V_{\alpha}}\right)(x) d s \tag{3}
\end{equation*}
$$

where we noticed that $\mu_{V_{\alpha}}\left(W+\partial_{\alpha} \ln Z_{V_{\alpha}}\right)=0$. Hence we see that in the classical setup (2) can be solved thanks to the associated semi-group. Moreover, by smoothness of $x \mapsto P_{s}^{\alpha}(W)(x)$, we see that $g_{\alpha}$ is smooth if $W$ is. To conclude, all that remains is to solve the transport equation $\partial_{\alpha} F_{\alpha}=\nabla g_{\alpha}\left(F_{\alpha}\right)$. In the rest of this article we generalize this strategy to the free probability framework.

Let us first investigate the free set-up in the one variable case. Typically, one should think about the non-commutative law of one variable as the asymptotic spectral measure of a random matrix, confined by a potential $V$ : the joint law of these eigenvalues is given by

$$
d P_{N}^{V}\left(\lambda_{1}, \ldots, \lambda_{N}\right)=\frac{1}{Z_{N}^{V}} \prod_{1 \leq i \neq j \leq N}\left|\lambda_{i}-\lambda_{j}\right| \exp \left\{-N \sum_{i=1}^{N} V\left(\lambda_{i}\right)\right\} \prod_{1 \leq i \leq N} d \lambda_{i}
$$

It is then well known (see e.g. [AGZ10]) that the spectral measure $L_{N}=$ $\frac{1}{N} \sum_{i=1}^{N} \delta_{\lambda_{i}}$ converges almost surely to the equilibrium measure $\mu_{V}$, which is characterized by the fact that the function

$$
\begin{equation*}
V(x)-2 \int \ln |x-y| d \mu_{V}(y) \tag{4}
\end{equation*}
$$

is equal to a constant $c_{V}$ on the support of $\mu_{V}$ and is greater (or equal) than this constant outside of the support. This equation implies the Schwinger-Dyson equation

$$
\begin{equation*}
2 \text { P.V. } \int \frac{1}{x-y} d \mu_{V}(y)=V^{\prime}(x), \quad \mu_{V} \text { a.s. } \tag{5}
\end{equation*}
$$

where P.V. denotes the principal value. We will call a free Gibbs law with potential $V$ a solution to (5). It may not be unique; in fact, there is a continuum of solutions as soon as solutions have disconnected support: a solution corresponds to any choice of masses of the connected pieces of the support. This is not the case when $V$ is uniformly convex. In this case, there is a unique solution and it has connected support. The interest in the Schwinger-Dyson equation is that it can be interpreted as an integration by parts identity for the non-commutative derivative $\partial f(x, y):=\frac{f(x)-f(y)}{x-y}$ since it implies that

$$
\iint \frac{f(x)-f(y)}{x-y} d \mu_{V}(x) d \mu_{V}(y)=\int f(x) V^{\prime}(x) d \mu_{V}(x)
$$

As there is no notion of density in free probability, integration by parts can be seen as an important way to classify measures. Moreover, as we shall soon describe, there is a natural generalization of free Gibbs laws to the multi-variable setting.

Let now $V, W$ be two potentials. We would like to construct a transport map from the Gibbs law $\mu_{V}$ with potential $V$ to the Gibbs law $\mu_{V+W}$ with potential $V+W$. We can follow the previous scheme and seek $g_{\alpha}$ satisfying : $\partial_{\alpha} F_{\alpha}=g_{\alpha}^{\prime}\left(F_{\alpha}\right)$ and $F_{\alpha} \# \mu_{V}=\mu_{V_{\alpha}}$. By (4), we find that $\mu_{V_{\alpha}}$ almost surely we must have

$$
\begin{equation*}
\Delta_{V_{\alpha}} g_{\alpha}(x):=2 \int \frac{g_{\alpha}^{\prime}(x)-g_{\alpha}^{\prime}(y)}{x-y} d \mu_{V_{\alpha}}(y)-V_{\alpha}^{\prime}(x) g_{\alpha}^{\prime}(x)=W-\partial_{\alpha} c_{V_{\alpha}} . \tag{6}
\end{equation*}
$$

We recognize on the left hand side the infinitesimal generator $\Delta_{V_{\alpha}}$ of the free diffusion driven by a free Brownian motion, [BS98]. More precisely, the infinitesimal generator of the free diffusion is given by

$$
\Delta_{V_{\alpha}} f(x)=2 \mathbb{E}\left[\frac{f^{\prime}(x)-f(X)}{x-X}\right]-V^{\prime}(x) f^{\prime}(x)
$$

if $X$ has the same law as $x$.
The fact that this generator depends on the law of the variable complicates the resulting theory quite a lot. In particular, the operators $e^{s \Delta_{V_{\alpha}}}$ acting on the obvious space of functions do not form a semigroup. To restore the semi-group property, we have to enlarge the set of test functions to be functions of not just the real variable $x$, but also of expectations of this random variable. Our idea here is similar to the one introduced in [Ceb13]. This in turn changes the generator of the diffusion to also involve differentiation under the expectation: we denote $\delta_{V}$ the derivative $\delta_{V} \mathbb{E}[f]=\mathbb{E}\left[\Delta_{V} f\right]$. We can now check that $\left(e^{s\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right)}\right)_{s \geq 0}$ is a semi-group so that we can apply the previous analysis.

Note here that when $x$ follows the invariant measure $\mu_{V_{\alpha}}, \delta_{V_{\alpha}} \mu_{V_{\alpha}}(f)=0$ and therefore the two generators coincide. Thus invariant measures for the semi-group $\left(e^{s\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right)}\right)_{s \geq 0}$ will satisfy (6).

As before, we shall solve (6) in a gradient form. Again, the natural gradient that we shall use also differentiates under expectation. Namely we let $\mathcal{D}$ to be given for any smooth functions $f, f_{i}, i \geq 0$ by

$$
\mathcal{D}\left(f(x) \prod \mathbb{E}\left[f_{j}(x)\right]\right)=f^{\prime}(x) \prod \mathbb{E}\left[f_{j}(x)\right]+\mathbb{E}[f] \sum_{i} f_{i}^{\prime}(x) \prod_{j \neq i} \mathbb{E}\left[f_{j}\right] .
$$

Then, we shall find a function $\mathcal{D} g_{\alpha}$ (of the variable $x$ and the expectation, see Lemma 11), which satisfies a gradient form of (6) (after adding $\delta_{V}$ to the generator and commuting $\mathcal{D}$ with $\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}$ ):

$$
\begin{equation*}
\mathcal{D}(W)=\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right)\left(\mathcal{D} g_{\alpha}\right)+V_{\alpha}^{\prime \prime} \mathcal{D} g_{\alpha} . \tag{7}
\end{equation*}
$$

Having obtained the solution $g_{\alpha}$, we finally solve

$$
\begin{equation*}
\partial_{\alpha} F_{\alpha}=\mathcal{D} g_{\alpha}\left(F_{\alpha}\right) \tag{8}
\end{equation*}
$$

To make things clearer, let us transport the measure $P_{N}^{V}$ onto $P_{N}^{W}$ and only afterwards take the large $N$-limit. Again, we consider the transport of $P_{N}^{V}$ onto $P_{N}^{V_{\alpha}}$. We may expect, by symmetry, the flow $F^{\alpha}=\left(F_{1}^{\alpha}, \ldots, F_{N}^{\alpha}\right)$ for the transport map to be the gradient of a function of the empirical measure $L_{N}=\frac{1}{N} \sum \delta_{\lambda_{i}^{N}}$ :

$$
F_{i}^{\alpha}(\lambda)=N \partial_{\lambda_{i}} G_{\alpha}\left(L_{N}\right)=\mathcal{D} G_{\alpha}\left(\lambda_{i}, L_{N}\right) .
$$

The infinitesimal generator $L_{V}=\Delta-\nabla V . \nabla$ acting on functions of the form $F\left(L_{N}\right)=N \prod \frac{1}{N} \sum_{i=1}^{N} f_{j}\left(\lambda_{i}\right)$ reads

$$
L_{V} F=\sum_{k} \prod_{j \neq k} \frac{1}{N} \sum_{i=1}^{N} f_{j}\left(\lambda_{i}\right) \frac{1}{N} \sum_{i=1}^{N} L_{V} f_{k}\left(\lambda_{i}\right)+O\left(\frac{1}{N}\right)
$$

where the last term comes from differentiation of two different functions and is at most of order $1 / N$. Hence, when $N$ goes to infinity we see that functions of the distribution of the $\lambda_{i}$ should not be taken as constant but also differentiated under the expectation. Taking the gradient in the Poisson equation (2) shows that we seek $G_{\alpha}$ such that for each $i$

$$
\left(L_{V_{\alpha}}+\delta_{V_{\alpha}}\right) \mathcal{D} G_{\alpha}\left(\lambda_{i}\right)=\mathcal{D} W\left(\lambda_{i}\right)+V_{\alpha}^{\prime \prime}\left(\lambda_{i}\right) \mathcal{D} G_{\alpha}\left(\lambda_{i}\right)+O\left(\frac{1}{N}\right)
$$

Hence, taking the large $N$ limit, we expect $G_{\alpha}$ to be given to first order by the solution $g_{\alpha}$ of (7).

The final step to finish our construction of the transport map is to introduce a notion of uniform convexity for $V$ so that the associated semi-group converges uniformly and sufficiently rapidly towards the invariant measure as time goes to infinity (to make sense of the integral over time from 0 to $\infty$ in (3)), and also so that if $f$ is smooth then also $x \mapsto e^{s\left(\Delta_{V_{t}}+\delta_{V_{t}}\right)} f(x)$ is smooth, uniformly in $s$ (to be able to solve the transport equation). Our choice of the notion of uniform convexity of $V$ is designed to guarantee such properties.
1.2. Construction of transport maps in free probability. We now want to explain our approach to the main goal of this article, which is to construct transport maps between non-commutative distributions of $n>1$ non-commutative variables. In free probability theory, laws of non-commutative variables are defined as linear forms $\tau$ on the space $\mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle$ of polynomials in the self-adjoint non-commutative letters $X_{1}, \ldots, X_{n}$ with coefficients in $\mathbb{C}$ which have mass one (so that $\tau(1)=1$ ), and which satisfy the traciality property $(\tau(P Q)=\tau(Q P))$ and the state property $\left(\tau\left(P P^{*}\right) \geq 0\right)$. Here $*$ denotes the usual involution $\left(z X_{i_{1}} \cdots X_{i_{k}}\right)^{*}=$ $\bar{z} X_{i_{k}} \cdots X_{i_{1}}$.

An example one should keep in mind is the asymptotic law of several interacting random matrices with joint law given by

$$
d \mathbb{P}_{N}^{V}\left(X_{1}^{N}, \ldots, X_{n}^{N}\right)=\frac{1}{Z_{N}^{V}} \exp \left\{-N \operatorname{Tr}\left(V\left(X_{1}^{N}, \ldots, X_{n}^{N}\right)\right)\right\} d X_{1}^{N} \cdots d X_{n}^{N}
$$

where $d X^{N}$ is the Lebesgue measure on the space of $N \times N$ Hermitian matrices and $V$ is a self-adjoint polynomial in $\mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle$ so that $Z_{N}^{V}$ is finite. In this case

$$
\tau_{X^{N}}(P)=\frac{1}{N} \operatorname{Tr}\left(P\left(X_{1}^{N}, \ldots, X_{n}^{N}\right)\right)
$$

is a non commutative law for any self-adjoint matrices $X_{1}^{N}, \ldots, X_{n}^{N}$. So is its expectation under $\mathbb{P}_{N}^{V}$ and the limit of these expected value as $N \rightarrow \infty$ (if the limit exists).

Existence of such an (almost sure and $L^{1}\left(\mathbb{P}_{N}^{V}\right)$ ) limit was proven when $V$ is a small perturbation of a quadratic potential [GMS06] and when $V$ satisfies some property of convexity [GS09, Dab16, J18].

The existence and uniqueness of a limit $\tau_{V}$ holds under the assumption that $V$ satisfies our definition of convexity, as well. This includes the case of quartic potentials. By integration by parts, we see that the limit $\tau_{V}$ must satisfy that for any polynomial $P$

$$
\begin{equation*}
\tau_{V} \otimes \tau_{V}\left(\partial_{i} P\right)=\tau_{V}\left(P \mathcal{D}_{i} V\right) \tag{9}
\end{equation*}
$$

where $\partial_{i}$ is the free difference quotient with respect to the $i$ th derivative from $\mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle$ to $\mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle \otimes \mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle$ given by

$$
\partial_{i}(P Q)=\partial_{i}(P) \times 1 \otimes Q+P \otimes 1 \times \partial_{i} Q, \quad \partial_{i} X_{j}=1_{i=j} 1 \otimes 1
$$

and $\mathcal{D}_{i}=m \circ \partial_{i}$ the cyclic derivative, $m(a \times b)=b a$. When $V=\sum_{i=1}^{n} X_{i}^{2}$, $\sigma_{n}:=\tau_{\sum_{i=1}^{n} X_{i}^{2}}$ is uniquely given recursively by (9) and is the law of $n$ free semicircle variables. In general, we say that a non-commutative law $\tau_{V}$ satisfying (9) is a free Gibbs law with potential $V$. Alternatively we say that the conjugate variables $\left(\partial_{i}^{*}(1 \otimes 1)\right)_{1 \leq i \leq n}$ are equal to the cyclic gradient $\left(\mathcal{D}_{i} V\right)_{1 \leq i \leq n}$.

The goal of this paper is to construct non-commutative transport maps between $\tau_{V}$ and $\sigma_{n}$, following the ideas developed in the previous section. In fact, constructing the transport map as the solution of the transport equation (8) where $g_{\alpha}$ is solution of a Poisson equation (7) is a natural analogue thanks to existence of free diffusion and free semi-groups. However, this program meets several issues that have to be addressed.

- One of the key point to construct the solution to Poisson equation was the fast convergence of the semi-group towards the free Gibbs law. In the free context, it is well known that semi-groups with deep double well potentials do not always converge. It is therefore natural to search for the appropriate notion of convexity in the non-commutative setting, which would imply convergence of the semi-group as time goes to infinity, uniformly on the initial condition. In [GS09], the notion of convexity that was used turns out to be too strong to include many examples. It assumed that for all $n$-tuples of self-adjoint variables $(X, Y)$ bounded by some $R$,

$$
\sum_{i=1}^{n}\left(\left(\mathcal{D}_{i} V(X)-\mathcal{D}_{i} V(Y)\right)\left(X_{i}-Y_{i}\right)+\left(X_{i}-Y_{i}\right)\left(\mathcal{D}_{i} V(X)-\mathcal{D}_{i} V(Y)\right)\right)
$$

is non-negative. This is not satisfied by $V(X)=X^{4}$ as can be checked by taking ( $X, Y$ ) to be two $2 \times 2$ matrices given by $X_{11}=1, X_{12}=X_{21}=$ $0, X_{22}=-6, Y_{11}=1, Y_{12}=Y_{21}=\sqrt{11} / 4, Y_{22}=-5$. It would be more natural to assume that the Hessian of $\operatorname{Tr} V\left(X_{1}^{N}, \ldots, X_{n}^{N}\right)$ is bounded below for any $n$-tuple of Hermitian matrices $X_{1}^{N}, \ldots, X_{n}^{N}$. However, this Hessian lives in a tensor product space and saying that it is non-negative depends on the topology with which we equip the tensor product. We shall see that a good topology is given by the extended Haagerup tensor product and prove that our definition includes the case of quartic potentials.

- As in the one variable case, we have to consider functions not only of the variables but also of the expectation and the semi-group must also differentiate under expectation. Hence, we have to develop free stochastic calculus applied to such functions.
- The solution of the Poisson equation is given in terms of the semi-group, and we need to show existence and smoothness of the transport maps which are
the solution of the transport equation driven by this solution. This requires us to show that the semi-group acts smoothly on appropriate spaces of noncommutative functions, and also understand its image under the cyclic gradient.
In Section 2.4 we define several differential operators acting on functions of several non-commutative variables, some of them being well known in free probability, such as the difference quotient and the cyclic gradient. We extend their definition to functions which also depend on expectations, in order to define a proper semi-group on the appropriate function spaces. We then define the notion of $(c, R)$ $h$-convexity of a function in Definition 3. It states that the Hessian of this function is bounded below by $c I$ in the extended Haagerup tensor product, uniformly when evaluated on non-commutative variables bounded by $R$. An important point is that this notion is stable under addition. We then show in Proposition 5 that the free SDE with strictly $h$-convex potential converges as time goes to infinity towards a free Gibbs law. To construct the transport map between $\tau_{V}$ and $\sigma_{n}$, we shall need an additional technical assumption. First, as we proceed by interpolation of the potential, we need to assume that a nice bounded free Gibbs law exists for all potentials $V_{\alpha}=\alpha V+(1-\alpha) \sum_{i=1}^{n} X_{i}^{2}, \alpha \in[0,1]$. This is the content of Assumption 4. We are now in position to state one of our main theorems, see Corollary 13 (with $B=D=\mathbb{C}$ and $\left.W=c \sum_{i=1}^{n} X_{i}^{2}-V\right)$.

Theorem 1. Let $c, R>0$. Assume that $V$ is a six times continuously differentiable $(c, R) h$-convex on the space of variables bounded by $2 R$. Assume that $\left(V, c \sum_{i=1}^{n} X_{i}^{2}-V\right)$ satisfies the technical Assumption 4. Let $V_{\alpha}=V+$ $\alpha\left(c \sum_{i=1}^{n} X_{i}^{2}-V\right)$.

- There exists $\alpha_{0}>0$ and functions $F_{\alpha}, \alpha \in\left[0, \alpha_{0}\right]$ and $G_{\alpha}, \alpha \in\left[0, \alpha_{0}\right]$, so that for all $\alpha \in\left[0, \alpha_{0}\right], \tau_{V}$ (resp. $\tau_{V_{\alpha}}$ ) is the pushforward of $\tau_{V_{\alpha}}\left(\right.$ resp. $\left.\tau_{V}\right)$ by $F_{\alpha}$ (resp. $G_{\alpha}$ ).
- For any $\alpha \in[0,1]$, the von Neumann algebras associated to the free Gibbs law with potential $V_{\alpha}$ are isomorphic; in particular, they are isomorphic to the von Neumann algebra generated by $n$ free semicircular variables.

In the appendix, see Corollary B.48, we show that the following perturbation of quartic potentials $\mathcal{V}$ satisfy all our hypotheses:

$$
\mathcal{V}(X)=V(X)+\varepsilon P\left(\frac{\sqrt{-1}+X_{1}}{\sqrt{-1}-X_{1}}, \cdots, \frac{\sqrt{-1}+X_{n}}{\sqrt{-1}-X_{n}}\right)
$$

with

$$
V(X)=\sum_{j=1}^{k} \mu_{j} v_{j}\left(\sum_{i=1}^{n} \lambda_{i, j} X_{i}\right)+\sum_{i, j=1}^{n} A_{i, j} X_{i} X_{j}
$$

Here $A=\left(A_{i, j}\right) \in M_{n}(\mathbb{R})$ is a positive matrix with $A \geq c I_{n},\left(\lambda_{i, j}\right) \in M_{n, k}(\mathbb{R}), \mu \in$ $\left[0, \infty\left[^{k}, v_{j}(x)=\nu_{j, 2} \frac{X_{1}^{2}}{2}+\nu_{j, 3} \frac{X_{1}^{3}}{3}+\nu_{j, 4} \frac{X_{1}^{4}}{4} \in \mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle\right.\right.$ for $\nu_{j, 4}>0, \nu_{j, 3}^{2} \leq$ $8 \nu_{j, 2} \nu_{j, 4} / 3$. Furthermore, $P$ is a self-adjoint polynomial and $\varepsilon$ is small enough.

This is the first potential which is not a perturbation of a quadratic case for which isomorphism between the von Neumann algebras associated with its free Gibbs law and that of free semi-circle variables is proven.

In the rest of the article we will consider a more general framework. We fix a unital inclusion of two von Neumann algebras $D \subset B$ and consider the set of polynomials in $X_{1}, \ldots, X_{n}$ and elements in $B$ where $X_{1}, \ldots, X_{n}$ commute with $D$. Our set of test functions will be converging series in such monomials, or closures of this space arising from certain non-commutative versions of $C^{p}$-norms. We shall consider the extended Haagerup tensor product of such spaces, as well as a cyclic variant which allows the action of cyclic permutations. This is needed to define the action of the cyclic gradient. This gradient appears in the right hand side of the Dyson-Schwinger equation (9) and the non-commutative version of the transport equation (8), and is therefore key to our analysis. Our main result in this general situation is stated in Corollary 13.

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## 2. Definitions and Framework

2.1. Spaces of analytic functions. We denote by $M\left(X_{1}, \ldots, X_{n}\right)$ the set of monomials in $X_{1}, \ldots, X_{n}$. Throughout this paper, $B$ will denote a finite von Neumann algebra, and $D$ a unital von Neumann subalgebra.

The extended Haagerup tensor product relative to $D$ is denoted by $\underset{D}{\stackrel{\text { eh }}{\otimes}}$. We denote by $B^{\stackrel{\text { eh }}{\otimes, c} n}$ a version of the $n$-th extended Haagerup tensor power of $B$ that carries the action of the cyclic group of order $n$.

For $R>0$, we define formally

$$
B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle:=B \oplus_{D}^{1} \ell_{D}^{1}\left(R^{|m|} B^{\stackrel{\text { eh }}{\otimes}}(|m|+1) ; m \in M\left(X_{1}, \ldots, X_{n}\right),|m| \geq 1\right)
$$

Here $R^{|m|} E$ means the space $E$ with standard norm multiplied by $R^{|m|}$. This space can be regarded as the space of power series in $X_{1}, \ldots, X_{n}$ with coefficients in $B$ and radius of convergence at least $R$ by identifying a monomial $b_{0} X_{i_{1}} b_{1} \cdots X_{i_{p}} b_{p}$ with the copy of the tensor $b_{0} \otimes \cdots \otimes b_{p}$ in $\ell_{D}^{1}$ index by $m=X_{i_{1}} \cdots X_{i_{p}}$. The definition of the Haagerup tensor product $\stackrel{\text { eh }}{\otimes}$ is discussed in section 1.2 and Lemma 5 of [Dab15] (see also [ $\mathbf{P}$, chapter 5], [M97, M05] for the general module case). We direct sum of $D$-modules in the definition above in order the resulting space is a $D$-module, so that $B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle \stackrel{\text { eh }}{\otimes} B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$ be well defined. Modulo this (important) property, we could have more simply considered the (ordinary operator space) $\ell^{1}=\ell_{\mathbb{C}}^{1}$ direct sum (cf. [ $\mathbf{P}$, section 2.6]); we will denote by $B\left\langle X_{1}, \ldots, X_{n}\right.$ : $D, R, \mathbb{C}\rangle$ the corresponding smaller space. We will only use version in the cyclic case.

The cyclic variant $B_{c}\left\langle X_{1}, \ldots, X_{n}: D, R, \mathbb{C}\right\rangle$ is given by:

$$
\left(D^{\prime} \cap B\right) \oplus^{1} \ell^{1}\left(R^{|m|} B^{\substack{\mathrm{eh} \\ D, c}}(|m|+1), ~ ; m \in M\left(X_{1}, \ldots, X_{n}\right),|m| \geq 1\right)
$$

where $D^{\prime}$ is the commutant of $D$ and $\underset{D, c}{\stackrel{\text { eh }}{\otimes}}$ stands for the cyclic version of Haagerup tensor product defined in subsection A.3. This space can be regarded as the space of power series in $X_{1}, \ldots, X_{n}$ with coefficients in $B$ and radius of convergence at least $R$, and such that variables $X_{j}$ commute with $D$. As before, a monomial $b_{0} X_{i_{1}} b_{1} \cdots X_{i_{p}} b_{p}$ is identified with the copy of the tensor $b_{0} \otimes \cdots \otimes b_{p}$ indexed by the monomial $m=X_{i_{1}} \cdots X_{i_{p}}$. The use of the Haagerup tensor product $\underset{D, c}{\stackrel{\text { eh }}{\otimes}}$ ensures the possibility of cyclic permutation of various terms in the power series. We denote by $\mathfrak{C}_{p+1}$ the group of cyclic permutations acting on the cyclic tensor product generated by $\rho\left(b_{0} \otimes \cdots \otimes b_{p}\right)=b_{p} \otimes b_{0} \cdots \otimes b_{p-1}$. The cyclic gradient (very roughly, a map on this space) will be defined in subsection B.1.
$B_{c}\left\langle X_{1}, \ldots, X_{n}: D, R, \mathbb{C}\right\rangle$ and $B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$ are Banach algebras, see [Dab15, Theorem 39] and subsection B.1.

We let for $n, m>0, i \in\{1, \ldots, n-1\}, \#_{i}: A^{\substack{\mathrm{eh} \\ \stackrel{\otimes}{D} n}} \times\left(D^{\prime} \cap A^{\stackrel{\mathrm{eh}}{\otimes, m}}\right) \rightarrow A^{\stackrel{\mathrm{eh}}{\otimes, n+m-2}}$ the canonical extension of the map given on elementary tensors by

$$
\left(a_{1} \otimes \cdots a_{n}\right) \#_{i}\left(b_{1} \otimes \cdots b_{m}\right)=a_{1} \otimes \cdots \otimes a_{i-1} \otimes a_{i} b_{1} \otimes b_{2} \cdots \otimes b_{m} a_{i+1} \otimes \cdots \otimes a_{n}
$$

Having those operadic compositions, which will be crucial for non-commutative calculus, is another reason for using variants of Haagerup tensor products.

By definition $A^{\stackrel{\mathrm{eh}}{\otimes, c} m} \subset\left(D^{\prime} \cap A^{\stackrel{\mathrm{eh}}{\otimes} m}\right)$; this leads to to cyclic variants of $\#_{i}$ as
 We may also write for instance $\cdot \#(\cdot, \cdot): A^{\stackrel{\mathrm{eh}}{\mathrm{D}, c} 3} \times A^{\stackrel{\mathrm{eh}}{\mathrm{D}, c} n} \times A^{\stackrel{\mathrm{eh}}{\mathrm{D}, c} m} \rightarrow A^{\stackrel{\mathrm{eh}}{\mathrm{D}, c} m+n-1}$ for $U \#(V, W)=\left(U \#{ }_{1} V\right) \# W=\left(U \#{ }_{2} W\right) \# V$ and similarly $U \#\left(V_{1}, \cdots, V_{k}\right)$.

We endow $A^{\substack{\text { eh } \\ D, c}}$
$(a \# b)^{*}=b^{*} \# a^{*}$, so that $\left(A^{\substack{\mathrm{eh} \\ \mathrm{D}, c}}, *\right)$ is a $*$-algebra.
2.2. Spaces of analytic functions with expectations. We will need a generalization of analytic functions which also depend on a expectation $E_{D}$ valued in $D$. For example, we would like to consider functions of the type

$$
\begin{aligned}
& b_{0} X_{i_{1}} b_{1} \cdots X_{i_{p}} b_{p} E_{D}\left[b_{p+1} X_{i_{p+2}} \cdots b_{p+k} E_{D}\left[b_{p+k+1} X_{i_{p+k+2}} \cdots b_{p+k+m}\right]\right] \\
& \quad \times E_{D}\left[b_{p+k+m} X_{i_{p+k+m+1}} \cdots b_{p+k+m+\ell}\right] b_{p+k+m+\ell+1} X_{i_{p+k+m+\ell+2}} \cdots b_{p+k+m+\ell+r}
\end{aligned}
$$

As the order in which conditional expectations are applied matters, we will label such a monomial by inserting an additional letter $Y$ for each closing and opening parenthesis of the map. The matching between the closing and opening parenthesis then defines a non-crossing pair partitions of the set of positions of the letter $Y$. Conversely, given a non-commuting monomial in letters $X_{1}, \ldots, X_{n}$ and $Y$ having
even degree $2 k$ in $Y$, and a non-crossing pair partition of the positions of the letter $Y$, we can define a unique expression of the type above. Thus, formally we set

$$
\begin{aligned}
& B_{k}\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}:=\ell_{D}^{1}\left(R^{|m|_{X}} B_{D}^{\stackrel{\text { eh }}{\otimes}(|m|+1)} ;\right. \\
& \left.m \in M_{2 k}\left(X_{1}, \ldots, X_{n}, Y\right), \pi \in N C_{2}(2 k),|m| \geq 1\right), \quad k \geq 1
\end{aligned}
$$

where $M_{2 k}\left(X_{1}, \ldots, X_{n}, Y\right)$ is the set of non-commuting monomial in letters $X_{1}, \ldots, X_{n}$ and $Y$ having even degree $2 k$ in $Y,|m|_{X}$ denotes the degree in the letter $X_{1}, \ldots, X_{n}$ of $m$ and $|m|=|m|_{X}+2 k$. We call $B_{k}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}$ the corresponding space with (non-module) operator space $\ell^{1}$ sums (in the sense of [ $\mathbf{P}$, section 2.6]). Similarly, we define

$$
\begin{aligned}
& B_{c, k}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}:=\ell^{1}\left(R^{|m|_{X}} B^{\substack{\text { eh } \\
\otimes, c, c}}(|m|+1)\right. \\
& \left.m \in M_{2 k}\left(X_{1}, \ldots, X_{n}, Y\right), \pi \in N C_{2}(2 k),|m| \geq 1\right) .
\end{aligned}
$$

We set $B_{c, 0}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}=B_{c}\left\langle X_{1}, \ldots, X_{n}: D, R, \mathbb{C}\right\rangle$ and $B_{0}\left\{X_{1}, \ldots, X_{n}\right.$ : $\left.E_{D}, R\right\}=B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$.

Finally we define:

$$
\begin{aligned}
B_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\} & :=\ell^{1}\left(B_{c, k}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}, k \in \mathbb{N}\right) \\
B\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\} & :=\ell^{1}\left(B_{k}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}, k \in \mathbb{N}\right) \\
B\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\} & :=\ell_{D}^{1}\left(B_{k}\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}, k \in \mathbb{N}\right)
\end{aligned}
$$

Above, $E_{D}$ should be considered as a variable taken in the space of $D$-bilinear completely bounded maps.

For $P \in B_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}$ and $E: B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle \rightarrow D$ unital $D$-bilinear completely-bounded map, we can define the map $P \mapsto P(E)$ taking $B_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}$ to $B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$ by recursively replacing each sub-monomial $E_{D}(Q), Q \in B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$ inside $P$ by $E(Q)$. A formal definition is given in subsection B. 2 where all the technical lemmas we will need about those analytic functions are proved.
2.3. Spaces of differentiable functions. Let $A$ be a finite von Neumann algebra containing $B$ as a unital von Neumann subalgebra. Set

$$
A_{R}^{n}:=\left\{\left(X_{1}, \ldots, X_{n}\right) \in\left(D^{\prime} \cap A\right)^{n}: X_{i}=X_{i}^{*} \in A ;\left\|X_{i}\right\|<R\right\}
$$

Let $U \subset A_{R}^{n}$ be a closed subset of $A_{R}^{n}$. For convenience, we will first embed the algebra $B_{c}\left\langle X_{1}, \ldots, X_{n}: D, R, \mathbb{C}\right\rangle$ into a much larger algebra $\cap_{S>R} C_{b}^{0}\left(U, B_{c}\left\langle X_{1}, \ldots, X_{n}\right.\right.$ : $D, S, \mathbb{C}\rangle)$, where $C_{b}^{0}(U, B)$ stands for the space of bounded continuous functions on $U$ with values in a Banach space $B$. On this space we define the norm

$$
\|P\|_{A, U}=\sup \left\{\left\|P\left(X_{1}, \ldots, X_{n}\right)\right\|_{A}:\left(X_{1}, \ldots, X_{n}\right) \in U\right\}
$$

where by $P\left(X_{1}, \ldots, X_{n}\right)$ we mean the value of $P$ evaluated at $\left(X_{1}, \ldots, X_{n}\right) \in U$, itself evaluated as a power series in $\left(X_{1}, \ldots, X_{n}\right)$ (see Proposition B. 25 for some details on those evaluations). We call the corresponding completion $C_{u}^{*}(A, U: B, D)$ and $C_{u}^{*}(A, R: B, D)$ when $U=A_{R}^{n}$.

For $P \in \cap_{S>R} C_{b}^{1}\left(A_{R}^{n}, B_{c}\left\langle X_{1}, \ldots, X_{n}: D, S, \mathbb{C}\right\rangle\right) \subset \cap_{S>R} C_{b}^{0}\left(A_{R}^{n}, B_{c}\left\langle X_{1}, \ldots, X_{n}:\right.\right.$ $D, S, \mathbb{C}\rangle$ ) the set of continuously differentiable functions on $A_{R}^{n}$ with bounded first derivative, one can consider the differential

$$
d P \in \cap_{S>R} C_{b}^{0}\left(A_{R}^{n}, L\left(D^{\prime} \cap A_{s a}^{n}, B_{c}\left\langle X_{1}, \ldots, X_{n}: D, S, \mathbb{C}\right\rangle\right)\right)
$$

where $L\left(G, G^{\prime}\right)$ is the set of bounded linear maps from $G$ into $G^{\prime}$. Here, $D^{\prime} \cap A_{s a}^{n}$ should be thought of as a tangent space of $A_{R}^{n}$. As usual, one writes for $X \in A_{R}^{n}$ and $H \in D^{\prime} \cap A_{s a}^{n}$,

$$
D_{H} P(X)=d P(X) \cdot H
$$

and we see that $\left.\left(D_{H} P: X \mapsto d P(X) \cdot H\right) \in \cap_{S>R} C_{b}^{0}\left(A_{R}^{n}, B_{c}\left\langle X_{1}, \ldots, X_{n}: D, S, \mathbb{C}\right\rangle\right)\right)$. Likewise for
$P \in \cap_{S>R} C_{b}^{k}\left(A_{R}^{n}, B_{c}\left\langle X_{1}, \ldots, X_{n}: D, S, \mathbb{C}\right\rangle\right) \subset \cap_{S>R} C_{b}^{0}\left(A_{R}^{n}, B_{c}\left\langle X_{1}, \ldots, X_{n}: D, S, \mathbb{C}\right\rangle\right)$
an element of the set of $k$ times coefficientwise continuously differentiable functions on $A_{R}^{n}$ with bounded first $k$-th order differentials, one can consider the $k$-th order differential

$$
d^{k} P \in C_{b}^{0}\left(A_{R}^{n}, B\left(\left(D^{\prime} \cap\left(A_{s a}^{n}\right)\right)^{\hat{\otimes} k}, B_{c}\left\langle X_{1}, \ldots, X_{n}: D, S, \mathbb{C}\right\rangle\right)\right)
$$

where $\hat{\otimes}$ denotes the projective tensor product.
In this case $D_{K} D_{H}^{k-1} P(X)=d^{k} P(X) \cdot(K, H, \ldots, H)$ and

$$
D_{K} D_{H}^{k-1} P: X \mapsto D_{K} D_{H}^{k-1} P(X) \in \cap_{S>R} C_{b}^{0}\left(A_{R}^{n}, B_{c}\left\langle X_{1}, \ldots, X_{n}: D, S, \mathbb{C}\right\rangle\right)
$$

We show in Proposition B. 26 that $B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$ carries a canonical derivations

$$
\partial_{i}: B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle \rightarrow B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle \stackrel{\mathrm{D}}{\otimes} B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle
$$

called the $i$-th free difference quotient, $i=1, \ldots, n$. These satisfy $\partial_{i}\left(X_{j}\right)=\delta_{i=j} 1 \otimes$ $1, \partial_{i}(b)=0$. They can be extended to $B\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}$ by putting $\partial_{i} \circ E_{D}=0$.

We denote in short

$$
\partial_{\left(i_{1}, \ldots, i_{k}\right)}^{k}: B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle \rightarrow B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle_{D}^{\substack{\text { eh } \\ D \\(k+1)}}
$$

the map

$$
\partial_{\left(i_{1}, \ldots, i_{k}\right)}^{k}=\left(\partial_{i_{1}} \otimes 1^{\otimes k}\right) \circ\left(\partial_{i_{2}} \otimes 1^{\otimes(k-1)}\right) \circ \ldots \circ \partial_{i_{k}}
$$

Recall that $D_{H}$ stands for the directional derivative of a function in $C_{u}^{1}(A, U$ : $\left.B, E_{D}\right)$, viewed as a function from $U$ to the space of power series $B_{c}\left\langle X_{1}, \ldots, X_{n}\right.$ : $D, R, \mathbb{C}\rangle$. However, this won't be the most convenient differential, since the noncommutative power series part will always be evaluated at the same $X \in U$ and we will instead need the full differential which uses also the free difference quotient on the powers series part.

On the space of continuous differentiable functions $C^{1}(U, A)$ from $U$ to $A$, denote by $D_{H}^{X}$ the derivative in the direction $H \in A^{n}$. Consider the map $\eta: C_{u}^{1,1}(A, U$ : $\left.B, E_{D}\right) \rightarrow C^{1}(U, A)$ given for $P \in \cap_{S>R} C_{b}^{1}\left(A_{R}^{n}, B_{c}\left\langle X_{1}, \ldots, X_{n}: D, S, \mathbb{C}\right\rangle\right)$ by $\eta(P)=$ $(P(X))(X)$. Then one has

$$
\begin{equation*}
\left.D_{H}^{X}(\eta(P))=\eta\left(D_{H}(P)\right)+\eta\left(\sum_{j=1}^{k}\left(\partial_{j}(P)\right) \# H_{j}\right)\right) \tag{10}
\end{equation*}
$$

We let $d_{X}$ be the differential associated with $D_{H}^{X}$. We will also write:

$$
\begin{aligned}
d_{X}^{p} P(X) \cdot H & =\left(D_{H}^{X}\right)^{p} \eta(P)=d^{p}[X \mapsto P(X)(X)](X) \cdot(H, \ldots, H) \\
& =\sum_{j=0}^{p} \sum_{i \in[1, n]^{j}}\left(d^{p-j}\left[\partial_{i}^{j} P(X)\right] \cdot(H, \ldots, H)\right) \#\left(H_{i_{1}}, \ldots, H_{i_{j}}\right)
\end{aligned}
$$

For $P \in \cap_{S>R} C_{b}^{0}\left(A_{R}^{n}, A\left\langle X_{1}, \ldots, X_{n}: D, S, \mathbb{C}\right\rangle\right), X \in A_{R}^{n}$, we set

$$
\|P\|_{k, X}=\left(\|P(X)\|_{A}+\sum_{p=1}^{k} \sum_{i \in[1, n]^{p}}\left\|\partial_{i}^{p}(P)(X)\right\| \underset{\substack{\text { eh } \\ A_{D}^{D}(p+1)}}{\substack{D^{(p)}}}\right) .
$$

We will consider the (separation) completion of

$$
\bigcap_{S>R} C_{b}^{l+1}\left(A_{R}^{n}, B\left\langle X_{1}, \ldots, X_{n}: D, S, \mathbb{C}\right\rangle\right)
$$

with respect to the seminorms for $(k, l) \in \mathbb{N}^{2}$ given by

$$
\left.\begin{array}{r}
\|P\|_{k, l, U}=\sup _{X \in U}\|P\|_{k, X}+\sum_{p=1}^{l}\left\{\operatorname { s u p } _ { \substack { X \in U \\
H \in A _ { 1 } ^ { n } } } \left(\left\|\left(D_{H}^{X}\right)^{p} \eta(P)(X)\right\|_{A}\right.\right. \\
+\sum_{\substack{i \in[1, n]^{m} \\
m \leq k}}\left\|\left(D_{H}^{X}\right)^{p} \partial_{i}^{m}(\eta(P))(X)\right\| \substack{\text { eh } \\
A D(m+1)}
\end{array}\right\}
$$

This seminorm controls $k$ free difference quotients and $l$ full differentials.
We will denote these (separation) completions by $C_{u}^{k, l}(A, U: B, D)$, and $C_{u}^{k, l}(A, R: B, D)$ when $U=A_{R}^{n}$. Note that for $p \leq l$ the above map $D_{H}^{p}$ extends continuously to a map $C_{u}^{k, l}(A, R: B, D) \rightarrow C_{u}^{k-p, l-p}(A, R: B, D)$.

When in the definition of $\|\cdot\|_{k, X}$ we replace $\|\cdot\|_{\substack{\text { oh } \\ A^{\infty}(l+1)}}$ by $\|\cdot\|_{\substack{\text { eh } \\ A^{D}, c^{(l+1)}}}$, we distinguish the corresponding seminorms by a subscript $c$, yielding the norm $\|$. $\|_{k, l, U, c}$ and the spaces $C_{c}^{k, l}(A, U: B, D), C_{c}^{k}(A, U: B, D)$.

Note that this require a supplementary assumption that $U \subset A_{R, U l t r a A p p}^{n}$ where $A_{R, U l t r a A p p}^{n}$ is defined before Proposition B.28: this assumption is necessary to define evaluation into cyclic tensor products. This is crucial to see that the image of cyclic analytic functions by the free difference quotient belongs to the cyclic Haagerup tensor product, see also Proposition B.26. More precisely we define $A_{R, U l t r a A p p}^{n}$ the set of $X_{1}, \ldots, X_{n} \in A, X_{i}=X_{i}^{*},\left[X_{i}, D\right]=0,\left\|X_{i}\right\| \leq R$ and such that $B, X_{1}, \ldots, X_{n}$ is the limit in $E_{D}$-law (for the $*$-strong convergence of $D$ ) of variables in $B_{c}\left\langle X_{1}, \ldots X_{m}: D, 2, \mathbb{C}\right\rangle\left(S_{1}, \ldots, S_{m}\right)$ with $S_{i}$ free semicircular variables over $D$. We will thus always assume $U \subset A_{R, U l t r a A p p}^{n}$ when we deal with spaces with index $c$. Note that consistently, we will write $C_{c}^{k}(A, R: B, D)$ when $U=$ $A_{R, U l t r a A p p}^{n}$.

For convenience later in writing estimates valid when there is at least one derivative, we also introduce a seminorm

$$
\begin{aligned}
\|P\|_{k, l, U, \geq 1}= & \sup _{X \in U}\left(\sum_{p=1}^{k} \sum_{i \in[1, n]^{p}}\left\|\partial_{i}^{p}(P)(X)\right\| \begin{array}{c}
\text { eh } \\
A D D(p+1) \\
\otimes
\end{array}\right)+\sum_{p=1}^{l} \sup _{\substack{X \in U \\
H \in A_{1}^{n}}}\left(\left\|\left(D_{H}^{X}\right)^{p} \eta(P)(X)\right\|_{A}\right. \\
& \left.+\sum_{\substack{i \in[1, n]^{m} \\
m \leq k}}\left\|\left(D_{H}^{X}\right)^{p} \partial_{i}^{m}(\eta(P))(X)\right\|_{\substack{\text { eh } \\
A D_{D}(m+1)}}\right) .
\end{aligned}
$$

We next define differentiable functions depending on conditional expectations.
Using the conditional expectation $E_{D}: A \rightarrow D$, we can define a completely bounded map $E_{D, X}: B\left\langle X_{1}, \ldots, X_{n}: D, S\right\rangle \rightarrow D$ by sending $P$ to $E_{D}\left(P\left(X_{1}, \ldots, X_{n}\right)\right)$, for any $S>R$.

Consider the map $\omega$ taking $P \in B_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, R^{+}, \mathbb{C}\right\} \quad:=$ $\cap_{S>R} B_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, S, \mathbb{C}\right\}$ to the function
$\omega(P): X \mapsto P\left(E_{D, X}\right) \in B_{c}\left\langle X_{1}, \ldots, X_{n}: E_{D}, R^{+}, \mathbb{C}\right\rangle:=\cap_{S>R} B_{c}\left\langle X_{1}, \ldots, X_{n}: E_{D}, S, \mathbb{C}\right\rangle$.
We denote by $C_{b, t r}^{0}\left(U, B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle\right)$ the image of this map.
The spaces $C_{t r}^{k, l}\left(A, U: B, E_{D}\right)$ (resp. $C_{t r}^{*}\left(A, U: B, E_{D}\right), C_{t r, c}^{*}\left(A, U: B, E_{D}\right)$ and $\left.C_{t r, c}^{k, l}\left(A, U: B, E_{D}\right)\right)$ are defined as the closures of the space $C_{b, t r}^{0}\left(U, B\left\langle X_{1}, \ldots, X_{n}\right.\right.$ : $D, S\rangle$ ) inside $C^{k, l}(A, U: B, D)$ (respectively, $C_{u}^{*}(A, U: B, D), C_{c}^{*}(A, U: B, D)$, $C_{c}^{k, l}(A, U: B, D)$ ). When $U=A_{R}^{n}$, we replace in the notations $U$ by $R$.

We denote by $C^{k, l}(A, U: B, D)$ the closed subspace of $C_{t r}^{k, l}(A, U: B, D)$ generated by the image under $\omega$ of $B\left\langle X_{1}, \ldots, X_{n}: D, S\right\rangle, S>R$. We denote in short $C^{k}(A, R: B, D)$ for $C^{k, k}(A, U: B, D)$.

Let $H \in A^{n}$. Recall that $D_{H}$ stands for the directional derivative of a function in $C_{u}^{1}\left(A, U: B, E_{D}\right)$, viewed as a function from $U$ to the space of power series $B_{c}\left\langle X_{1}, \ldots, X_{n}: D, R, \mathbb{C}\right\rangle$. Given $P \in B_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}$ a monomial involving $E_{D}$, we note that $D_{H}(\omega(P)$ amounts to replacing each sub-monomial of the form $E_{D}(Q)$ with $Q \in B_{c}\left\langle X_{1}, \ldots, X_{n}: D, R, \mathbb{C}\right\rangle$ by $E_{D}\left(\sum_{j} \partial_{j} Q \# H_{j}\right)$. For example if $H=\left(H_{1}, H_{2}\right)$, then

$$
\begin{aligned}
& D_{H}\left(\omega\left(X_{1} X_{2} E_{D}\left(X_{1}^{2}\left(E_{D}\left(X_{1}\right)\right) E_{D}\left(X_{2}\right)\right)\right)\left(Y_{1}, Y_{2}\right)\right. \\
& \left.\left.=X_{1} X_{2} E_{D}\left(H_{1} Y_{1}\left(E_{D}\left(Y_{1}\right)\right) E_{D}\left(Y_{2}\right)\right)\right)+X_{1} X_{2} E_{D}\left(Y_{1} H_{1}\left(E_{D}\left(Y_{1}\right)\right) E_{D}\left(Y_{2}\right)\right)\right) \\
& \left.\left.+X_{1} X_{2} E_{D}\left(Y_{1}^{2}\left(E_{D}\left(H_{1}\right)\right) E_{D}\left(Y_{2}\right)\right)\right)+X_{1} X_{2} E_{D}\left(Y_{1}^{2}\left(E_{D}\left(Y_{1}\right)\right) E_{D}\left(H_{2}\right)\right)\right)
\end{aligned}
$$

In other words, $D_{H}$ corresponds to "differentiation under $E_{D}$ ".
2.4. Differential operators. For $p, P \in B_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, S, \mathbb{C}\right\}$, we define recursively the cyclic gradient $\left(\mathscr{D}_{i, p}(P), 1 \leq i \leq n\right)$ by $\mathscr{D}_{i, p}\left(X_{j}\right)=1_{j=i} p$,

$$
\begin{equation*}
\mathscr{D}_{i, p}(P Q)=\mathscr{D}_{i, Q p}(P)+\mathscr{D}_{i, p P}(Q), \quad \mathscr{D}_{i, p}\left(E_{D}(P)\right)=\mathscr{D}_{i, E_{D}(p)}(P) . \tag{11}
\end{equation*}
$$

For instance, one computes $\mathscr{D}_{1, p}\left(X_{2} E_{D}\left(X_{1} b X_{2}\right) X_{1}\right)=p X_{2} E_{D}\left(X_{1} b X_{2}\right)+$ $b X_{2} E_{D}\left(X_{1} p X_{2}\right)$. Moreover, observe that for polynomials $P$ in $\left\{X_{1}, \ldots, X_{n}\right\}$,

$$
\begin{equation*}
\rho\left(\partial_{i} P\right) \# Q=\mathscr{D}_{i, Q}(P) \tag{12}
\end{equation*}
$$

We denote in short $\mathscr{D}_{i}=\mathscr{D}_{i, 1}$. Its restriction to polynomials in $\left\{X_{1}, \ldots, X_{n}\right\}$ corresponds to the usual cyclic derivative. We consider a "flat Laplacian" defined for $P \in B\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}$ by

$$
\Delta(P)=2 \sum_{i} m \circ\left(1 \otimes E_{D} \otimes 1\right) \partial_{i} \otimes 1 \partial_{i}(P) .
$$

We define $\delta_{\Delta}$ a derivation on $B\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}$ by requiring that it vanishes on $B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$ and satisfies

$$
\delta_{\Delta}(P)=0, \quad \delta_{\Delta}\left(E_{D}(Q)\right)=E_{D}\left(\left(\Delta+\delta_{\Delta}\right)(Q)\right)
$$

Likewise, for any $V \in B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$, the map

$$
\begin{equation*}
\Delta_{V}=\Delta-\sum_{i} \partial_{i}(.) \# \mathscr{D}_{i} V \tag{13}
\end{equation*}
$$

produces a map $\delta_{V}$ such that $\delta_{V}(P)=0$, for $P \in B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$. Moreover, $\delta_{V}$ is a derivation and for $Q$ monomial in $B\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}$,

$$
\delta_{V}\left(E_{D}(Q)\right)=E_{D}\left(\left(\Delta_{V}+\delta_{V}\right)(Q)\right)
$$

$\delta_{V}$ extends to $B\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}$ (see Proposition B.31). Moreover, we have for any $g \in B_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}$,

$$
\begin{equation*}
\mathscr{D}_{i}\left(\Delta_{V}+\delta_{V}\right)(g)=\left(\Delta_{V}+\delta_{V}\right) \mathscr{D}_{i}(g)-\sum_{j=1}^{n} \mathscr{D}_{i, \mathscr{D}_{j} g} \mathscr{D}_{j} V \tag{14}
\end{equation*}
$$

We extend $\Delta_{V}$ and $\delta_{V}$ to $V \in C_{c}^{3}\left(A, 2 R: B, E_{D}\right)$ by adding the variables $Z_{i}$ to be evaluated at $\mathscr{D}_{i} V(X)$, letting $V_{0}(Z)=\frac{1}{2} \sum Z_{i}^{2}$ and setting for $P \in B\left\{X_{1}, \ldots, X_{n}\right.$ : $\left.E_{D}, R\right\}$

$$
\begin{equation*}
\Delta_{V}(P)\left(E_{D, X}\right)(X):=\left(\Delta_{V_{0}(Z)}(P)\right)\left(E_{D, X, \mathscr{D} V(X)}\right)(X, \mathscr{D} V(X)) \tag{15}
\end{equation*}
$$

$\Delta_{V}(P)$ belongs to $C_{t r}^{*}(A, U)$. The extension of $\delta_{V}$ is similar. We define, $C_{t r, V}^{k, l}\left(A, U: B, E_{D}\right), k \in\{*\} \cup \mathbb{N}^{*}, k \geq l$ as the separation-completion of $B_{c}\left\{X_{1}, \ldots, X_{n} ; E_{D}, R^{+}\right\}:=\cap_{S>R} B_{c}\left\{X_{1}, \ldots, X_{n} ; E_{D}, R\right\}$ for the semi-norm (with $\left.\omega(P)=\left(X \mapsto P\left(E_{X, D}\right)\right)\right):$

$$
\begin{aligned}
\|P\|_{C_{t r, V}^{k, l}\left(A, U: B, E_{D}\right)} & =\|\omega(P)\|_{k, l, U}+1_{k \geq 2}\left\|\left(\Delta_{V}+\delta_{V}\right)(P)\right\|_{C_{t r}^{*}(A, U)} \\
& +\sum_{p=0}^{l-1} \sum_{i=1}^{n} \sup _{Q \in\left(C_{t r}^{k, p}\left(A, U^{m-1}: B, E_{D}\right)\right)_{1}}^{m \geq 2}
\end{aligned}\left\|\mathscr{D}_{i, Q\left(X^{\prime}\right)}(P)\right\|_{k, p, U^{m}},
$$

where $(X)_{1}$ denotes the unit ball around 0 of the normed space $X$. We also define a first order part seminorm $\|P\|_{C_{t r, V}^{k, l}\left(A, U: B, E_{D}\right), \geq 1}$ by replacing the first term in the sum with $\|\omega(P)\|_{k, l, U \geq 1}$. We also define the space $C_{t r, V, c}^{k, l}\left(A, U: B, E_{D}\right)$ in the same way as before but considering everywhere cyclic extended-Haagerup tensor products.

To sum up we have introduced the following spaces

where $\subset$ means the existence of a canonical injective mapping, whereas $\rightarrow$ means the existence of a canonical map (with conditions written in index). We shall not discuss these mappings as we will not use them and leave the reader check them.
2.5. Free brownian motion. $\left(S_{t}^{i}, t \geq 0,1 \leq i \leq n\right)$ will denote $n$ free Brownian motions. Let $U \subset A_{R}^{n}$. We denote by $*_{D}$ the free product with amalgamation over $D$ : see [VDN92] for a definition as well as for a definition of freeness with amalgamation over $D$. Let $\mathscr{A}=A *_{D}\left(D \otimes W^{*}\left(S_{t}^{(i)}, i=1, \ldots, n, t \geq 0\right)\right)$ and assume that $A$ is big enough so that $\mathscr{A}$ is isomorphic to $A$. Set $U_{A}=\left\{X \in \mathscr{A}_{R}^{n}, X \in U\right\} \subset$ $A_{R}^{n}$ and $\mathscr{B}=B *_{D}\left(D \otimes W^{*}\left(S_{t}^{(i)}, i=1, \ldots, n, t \geq 0\right)\right)$.

Define

$$
C_{t r, V}^{k, l}\left(A, U: \mathscr{B}, E_{D}:\left\{S_{t}^{(i)}, i=1, \ldots, n, t \geq 0\right\}\right) \subset C_{t r, V}^{k, l}\left(\mathscr{A}, U_{A}: \mathscr{B}, E_{D}\right)
$$

as the closure of

$$
\begin{array}{r}
\bigcup_{0 \leq t_{1} \leq \ldots \leq t_{m}} \eta_{S}\left(B _ { c } \left\{X_{1}, \ldots, X_{n}, S_{t_{1}}, \ldots, S_{t_{m}}-S_{t_{m-1}}\right.\right. \\
\left.\left.E_{D}, \max \left[R, \max _{i=2, n} 2\left(t_{i}-t_{i-1}\right)\right] \mathbb{C}\right\}\right)
\end{array}
$$

where $\eta_{S}$ is the partial evaluation of the analytic functions in $X$ 's and $S$ 's at $S_{t_{1}}$, $S_{t_{2}}-S_{t_{1}}, \ldots, S_{t_{m}}-S_{t_{m-1}}$, hence obtaining functions in $\mathscr{B}_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}$. In other words, this is the union of partial evaluation maps at the free brownian motions of analytic functions with expectations. Write in short $\mathscr{S}=\left\{S_{t}^{(i)}, i=\right.$ $1, \ldots, n, t \geq 0))\}, \quad$ and similarly for $u>0, \mathscr{S}_{u}=\left\{S_{t}^{(i)}, i=1, \ldots, n, u \geq t \geq\right.$ $\left.\left.0))\}, \mathscr{S}_{\geq u}=\left\{S_{t}^{(i)}-S_{u}^{(i)}, i=1, \ldots, n, t \geq u\right)\right)\right\}$

We call accordingly, for $U \subset A_{R, U l t r a A p p}^{n}, C_{c}^{k}(A, U: \mathscr{B}, D: \mathscr{S}) \subset C_{t r, V}^{k, k}(A, U$ : $\left.\mathscr{B}, E_{D}: \mathscr{S}\right) \cap C_{c}^{k}\left(\mathscr{A}, U_{A}: \mathscr{B}, D\right)$ the space generated by analytic functions (without expectations) with norm $\|\cdot\|_{k, l, U}$. We also have analogously $C_{c}^{k}\left(A, U: \mathscr{B}, D: \mathscr{S}_{u}\right) \subset$ $C_{t r, V}^{k, k}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}_{u}\right)$ (imposing above $\left.t_{m} \leq u\right)$. Fix a trace preserving *homomorphism $\theta_{u}: \mathscr{A} \rightarrow \mathscr{A}$ by $\theta_{u}(a)=a, a \in A, \theta_{u}\left(S_{s}\right)=S_{s+u}-S_{u}$ with obvious induced maps

$$
\theta_{u}^{\prime}: C_{t r, V}^{k, l}(A, U: \mathscr{B}, D: \mathscr{S}) \rightarrow C_{t r, V}^{k, l}\left(A, U: \mathscr{B}, D: \mathscr{S}_{\geq u}\right)
$$

and similarly $\theta_{u}^{\prime}: C_{t r}^{k, l}(A, U: \mathscr{B}, D: \mathscr{S}) \rightarrow C_{t r}^{k, l}\left(A, U: \mathscr{B}, D: \mathscr{S}_{\geq u}\right)$.
For $u \geq 0$, we denote by $\mathscr{A}_{u}=A *_{D}\left(D \otimes W^{*}\left(S_{t}^{(i)}, i=1, \ldots, n, t \in[0, u]\right)\right)$ and $E_{u}$ the associated conditional expectation. We observe that when restricted to polynomial function, the conditional expectations take their values in polynomials. Under certain conditions on $U$, see Proposition B.38, we can extend $E_{u}$ as an application $C_{t r, V}^{k, l}(A, U: \mathscr{B}, D: \mathscr{S}) \rightarrow C_{t r, V}^{k, l}\left(A, U: \mathscr{B}, D: \mathscr{S}_{u}\right)$.

## 3. Semi-groups and SDE's Associated with a Convex Potential

3.1. Convex potentials. With obvious notations, $M_{n}\left(A^{\stackrel{\mathrm{eh}}{\otimes, c} 2}\right.$. $)$ denotes the space of $n \times n$ matrices with entries in $A^{\stackrel{\mathrm{eh}}{\otimes, c} 2}$. For $M \in M_{n}\left(A^{\stackrel{\text { eh }}{\otimes} 2} 2,\left(M^{*}\right)_{i j}:=\left(M_{j i}\right)^{*}\right.$ with for $b \in A^{\stackrel{\mathrm{eh}}{\otimes, c} 2}, b^{*}$ defined in Theorem A.19.(1e). We don't equip this space with the
norm induced by its natural operator space structure as Haagerup tensor product.
We rather see $M_{n}\left(A^{\stackrel{\mathrm{eh}}{\mathrm{D}, c} 2}\right)$ as follows

We equip it with the matrix like \# multiplication map defined for $M=\left[M_{i j}\right] \in$ $M_{n}\left(A^{\stackrel{\mathrm{eh}}{\mathrm{D}, c} 2}\right), X \in \ell^{2}\left(\llbracket 1, n \rrbracket, A^{\stackrel{\mathrm{eh}}{\mathrm{D}, c} 2}\right)=\left(M^{\stackrel{\mathrm{eh}}{\mathrm{D}, c} m}\right)^{n}$ by

$$
(A \# X)_{i}=\sum_{j=1}^{n} A_{i j} \# X_{j}
$$

and with the norm

By definition $\|M\|_{\substack{\text { eh } \\ M_{n}\left(A^{D, c}\right)}}=\left\|M^{*}\right\|_{M_{n}\left(A^{D, c}\right)}^{\text {eh }_{D}^{D}, 2}$, and

We first recall a consequence of Hille-Yosida Theorem.
Proposition 2. The following are equivalent.
(1) $Q=Q^{*} \in M_{n}\binom{\mathrm{eh}}{A^{D, c} 2}$ has a semigroup of contraction $e^{-t Q}$,
(2) $Q=Q^{*} \in M_{n}\left(A^{\substack{\text { eh } \\ \otimes, c}}\right)$ has a resolvent family for all $\alpha>0, \alpha+Q$ is invertible in $M_{n}\left(A^{\substack{\text { eh } \\ \otimes, c}}\right)$ and $\left\|\frac{\alpha}{\alpha+Q}\right\|_{\substack{\text { eh } \\ M_{n}\left(A^{D, c}\right)}} \leq 1$.
In this case we say $Q \geq 0$.
Proof. We apply Hille-Yosida Theorem e.g. in the form of Theorem 1.12 in [MR], to each Banach space $\ell^{2}\left(\llbracket 1, n \rrbracket,\left(A^{\stackrel{\text { eh }}{\otimes, c} m} m^{m}\right)\right)$ in the definition of the norm of $M_{n}\left(A^{\stackrel{\text { eh }}{\otimes, c} 2}\right)$.

Note that the set of non-negative $Q=Q^{*} \in M_{n}\left(A^{\stackrel{\text { eh }}{\otimes, c}{ }^{2}}\right)$ is a cone. Indeed, if $\alpha \geq 0$ and $Q \geq 0$, clearly $\alpha Q_{\tilde{Q}} \geq 0$. Moreover, $Q \geq 0$ and $\tilde{Q} \geq 0$ implies that $Q+\tilde{Q} \geq 0$. Indeed, as $Q$ and $\tilde{Q}$ are bounded, they are defined everywhere as well as $Q+\tilde{Q}$, and one can use [T59] to see that

$$
e^{-t(Q+\tilde{Q})}=\lim _{k \rightarrow \infty}\left(e^{-\frac{t}{k} Q} \cdot e^{-\frac{t}{k} \tilde{Q}}\right)^{k}
$$

is a contraction as the right hand side is. Moreover, this set is closed as follows easily from the characterization (2) (notice here that the set $Q=Q^{*} \in M_{n}\left(A^{\stackrel{\mathrm{eh}}{\mathrm{D}, c} 2}\right.$ ) is closed).

Observe that if $V=V^{*} \in C_{c}^{2}(A, R: B, D), X \in A_{R}^{n},\left(\partial_{i} \mathscr{D}_{j} V(X)\right)_{1 \leq i, j \leq n} \in$ $M_{n}\left(A^{\stackrel{\text { eh }}{\otimes, c} 2}\right)$ is self-adjoint.
Definition 3. Let $c, R>0 . V=V^{*} \in C_{c}^{2}(A, R: B, D)$ is said $(c, R)$ h-convex if $\left(\partial_{i} \mathscr{D}_{j} V(X)\right)_{1 \leq i, j \leq n}-c \mathrm{Id} \geq 0$ for any $X \in A_{R, \text { UltraApp }}^{n}$.

We show below that $(c, R)$ h-convex potentials give rise to linear ODE with well-behaved solutions.
Lemma 4. Assume $V$ is $(c, R) h$-convex. Consider a continuous self-adjoint process $\left(X_{t}\right)_{t \geq 0},\left\|X_{t}\right\| \leq R, X_{t} \in D^{\prime}$.
(a) Let $Y \in\left(A^{\substack{\mathrm{eh} \\ D, c}}\right)^{n}$ be such that $Y_{j}^{*}=Y_{j}\left(\right.$ here $\left.\left(a_{1} \otimes \ldots \otimes a_{m}\right)^{*}=a_{m}^{*} \otimes \ldots \otimes a_{1}^{*}\right)$.

Then, there exists a unique solution $\phi_{s, t}(Y, X) \in\left(A^{\stackrel{\text { eh }}{\otimes, c} m}\right)^{n}$ of the following linear $O D E$ for $t \geq s$ :

$$
\begin{equation*}
\phi_{s, t}(Y, X)_{j}=Y_{j}-\frac{1}{2} \int_{s}^{t} d u \sum_{k}\left(\partial_{k} \mathscr{D}_{j} V\right)\left(X_{u}\right) \# \phi_{s, u}(Y, X)_{k} \tag{16}
\end{equation*}
$$

It satisfies $\phi_{s, t}(Y, X)_{j}^{*}=\phi_{s, t}(Y, X)_{j}$. Moreover, for any $\sigma \in \mathfrak{C}_{n}$, the solution $\sigma .\left(\phi_{s, t}(Y, X)_{j}\right)$ of the equation transformed by $\sigma$ (that is the equation obtained by applying a cyclic permutation of the tensor indices) satisfies:

$$
\begin{equation*}
\left\|\sigma \cdot\left(\phi_{s, t}(Y, X)\right)\right\| \underset{\left(A^{D^{m}}\right)^{n}}{\mathrm{eh}^{n}} \leq e^{-(t-s) c / 2}\|Y\| \underset{\substack{\text { eh } \\\left(A^{D, c}\right)^{n}}}{ } . \tag{17}
\end{equation*}
$$

(b) Let $Y_{s}$ be a $C^{1}$ process with values in $\left(A^{\substack{\mathrm{eh} \\ \mathrm{D}, c}}\right)^{n}$ such that $Y_{s}(t)_{j}^{*}=Y_{s}(t)_{j}$ (with $\left.\left(a_{1} \otimes \ldots \otimes a_{n}\right)^{*}=a_{n}^{*} \otimes \ldots \otimes a_{1}^{*}\right)$. The (unique) solution $\Phi_{s, t}(Y, X)$ of the following linear $O D E$ for $t \geq s$ :

$$
\begin{equation*}
\Phi_{s, t}(Y, X)_{j}=Y_{s}(t)_{j}-\frac{1}{2} \int_{s}^{t} d u \sum_{k}\left(\partial_{k} \mathscr{D}_{j} V\right)\left(X_{u}\right) \# \Phi_{s, u}(Y, X)_{k} \tag{18}
\end{equation*}
$$

satisfies $\Phi_{s, t}(Y, X)_{j}^{*}=\Phi_{s, t}(Y, X)_{j}$ and

$$
\left\|\Phi_{s, t}(Y, X)\right\| \underset{\substack{\text { eh } \\\left(A^{D, c}{ }^{D}\right)^{n}}}{ } \leq e^{-(t-s) c / 2}\| \| Y\| \| \|_{s, t}
$$

with

$$
\|\|Y\|\|_{s, t}=\left(\sum_{j}\left\|\left(Y_{s}(s)\right)_{j}\right\|_{\substack{\text { eh } \\ A^{D}, c}}^{2}\right)^{1 / 2}+\int_{s}^{t} e^{-c(s-u) / 2}\left(\sum_{j}\left\|\partial_{u} Y_{s}(u)_{j}\right\|_{\substack{\text { eh } \\ A^{D}, c_{m}}}\right)^{1 / 2} d u .
$$

Proof. Part (a): Let $X$ be a continuous self-adjoint process. The semigroup $\Theta^{X}$ associated to $Q=\frac{1}{2}\left(\partial_{k} \mathscr{D}_{j} V(X)\right)_{k j}$ gives a solution $\left(\Theta_{s, t}^{X}(Y)\right)_{t \geq 0}$ to

$$
Y_{j}(t)=Y_{j}-\frac{1}{2} \int_{s}^{t} \sum_{k=1}^{n} \partial_{k} \mathscr{D}_{j} V(X) \# Y_{k}(s) d s
$$

Therefore we can define the solution to

$$
\phi_{s, t}^{p}(Y, X)_{j}=Y_{j}-\frac{1}{2} \int_{s}^{t} d u \sum_{k}\left(\partial_{k} \mathscr{D}_{j} V\right)\left(X_{\frac{\lfloor u p\rfloor}{p}}\right) \# \phi_{s, u}^{p}(Y, X)_{k}
$$

in $\left(A^{\stackrel{\text { eh }}{\otimes, c} m}\right)^{n}$ by putting

$$
\begin{equation*}
\phi_{s, t+s}^{p}(Y, X)=\Theta_{\frac{\lfloor\lfloor p t\rfloor}{p}+s, t+s}^{\frac{\lfloor\lfloor t p\rfloor}{p}+s} \circ \Theta_{\frac{\lfloor(p t-1)\rfloor}{p}+s, \frac{\lfloor p t\rfloor}{p}+s}^{\frac{\lfloor\lfloor t p-1\rfloor}{p}} \circ \cdots \circ \Theta_{s, \frac{1}{p}+s}^{X_{s}}(Y) . \tag{19}
\end{equation*}
$$

By assumption of $(c, R)$ h-convexity, the semigroup $e^{-t\left(Q-\frac{c}{2} \mathrm{Id}\right)}=e^{\frac{c}{2} t} e^{-t Q}$ is contractive, which gives the bound

$$
\left\|\phi_{s, t}^{p}(Y, X)\right\| \underset{\substack{\text { eh } \\\left(A^{D, c} c^{D}\right)^{n}}}{ } \leq e^{-(t-s) c / 2}\|Y\| \|_{\substack{\text { eh } \\\left(A^{D, c} m \\ D^{n}\right.}} .
$$

In particular, this sequence is bounded uniformly. By continuity of $X$, we can similarly prove that this sequence is Cauchy, and hence converges towards the solution of (16); the limit then clearly satisfies the bound (17). Uniqueness can be proved by the Gronwall Lemma, as $\left(\partial_{k} \mathscr{D}_{j} V\right)(X$. ) is uniformly bounded.

Selfadjointness of $\phi_{s, t}(Y, X)_{j}$ follows from the uniqueness of the solution to the linear ODE since $\left((a \otimes c) \#\left(b_{1} \otimes \ldots \otimes b_{n}\right)\right)^{\star}=\left(c^{\star} \otimes a^{\star}\right) \#\left(b_{1} \otimes \ldots \otimes b_{n}\right)^{\star}$ and $\left(\left(\partial_{k} \mathscr{D}_{j} V\left(X_{s}\right)\right)^{\star}\right)_{k j}=\left(\partial_{k}\left(\mathscr{D}_{j} V^{*}\right)\left(X_{s}^{*}\right)\right)_{k j}=\left(\partial_{k}\left(\mathscr{D}_{j} V\right)\left(X_{s}\right)\right)_{k j}$ because $V=V^{*}$ and $X_{s}^{*}=X_{s}$.
Part (b). Using the notation of (a), define :

$$
\Phi_{s, t}(Y, X)=\phi_{s, t}\left(Y_{s}(s), X\right)+\int_{s}^{t} d u \phi_{u, t}\left(\partial_{u} Y_{s}(u), X\right) .
$$

Differentiating in $t$ shows that $\Phi_{s, t}$ is a solution of (18). The bounds follows readily from (a). Again, uniqueness follows from Gronwall's Lemma.

### 3.2. Free stochastic differential equation.

Proposition 5. Assume $V \in C_{c}^{2}(A, R: B, D)$ is $(c, R) h$-convex.
(a) There exists $T>0$ so that for any $X_{0} \in A_{R, U l t r a A p p}^{n}$, there exists a unique solution to

$$
X_{t}\left(X_{0}\right)=X_{0}+S_{t}-\frac{1}{2} \int_{0}^{t} \mathscr{D} V\left(X_{u}\left(X_{0}\right)\right) d u
$$

which is defined for all times $t<T$. Moreover, for all $X_{0}, \tilde{X}_{0} \in A_{R, U l t r a A p p}^{n}$ and $t \geq 0$

$$
\begin{equation*}
\left\|X_{t}\left(X_{0}\right)-X_{t}\left(\tilde{X}_{0}\right)\right\| \leq e^{-c t / 2}\left\|X_{0}-\tilde{X}_{0}\right\| . \tag{20}
\end{equation*}
$$

(b) Assume that there exists $X^{V}=\left(X_{1}^{V}, \ldots, X_{n}^{V}\right) \in A_{R / 3, U l t r a A p p}^{n}$ for which the conjugate variables are equal to $\mathscr{D}_{j} V$. Then part (a) holds with $T=\infty$ for any solution starting at $X_{0} \in A_{R / 3, U l t r a A p p}^{n}$. As a consequence, there is at most one free Gibbs law with potential $V$ uniformly in $A_{R / 3, U l t r a A p p}^{n}$.
Proof. Existence of $X_{t}\left(X_{0}\right)$ for all times $t<T$ for which $\sup _{s<T}\left\|X_{s}\left(X_{0}\right)\right\|<R$ follows from the Picard iteration argument in [BS01]. The existence of $T>0$ (depending only on the Lipschitz constant of $\mathscr{D} V$ ) is also shown there.

Applying the same argument as in the proof of Lemma 4 by writing $X_{t}^{1}=$ $X_{t}\left(\tilde{X}_{0}\right), X_{t}^{0}=X_{t}\left(X_{0}\right)$,

$$
X_{t}^{1}-X_{t}^{0}=\tilde{X}_{0}-X_{0}-\frac{1}{2} \int_{0}^{t} \int_{0}^{1} \partial \mathscr{D} V\left(\theta X_{u}^{0}+(1-\theta) X_{u}^{1}\right) \#\left(X_{u}^{1}-X_{u}^{0}\right) d \theta d u
$$

and arguing that $\int_{0}^{1} \partial \mathscr{D} V\left(\theta X_{u}^{1}+(1-\theta) X_{u}^{0}\right) d \theta-c \mathrm{Id} \geq 0$ as the set of non-negative ${ }^{\text {eh }} 2$
elements of $M_{n}\left(A^{\otimes, c}{ }^{2}\right)$ is a closed cone, the estimate (20) follows from (17).
Using the hypothesis of part (b), we see that the solution $X_{t}\left(X_{V}\right)$ is stationary; in particular, its norm is constant. Part (a) and the estimate (20) then imply that any other solution starting at an element of $A_{R / 3}^{n}$ stays in $A_{R}^{n}$, which means that $T$ can be chosen to be infinite. Also, if there were two free Gibbs law with potential $V$, they would be stationary laws for the dynamics and (20) would imply that they are equal.
Throughout this paper we assume that
Assumption 1. Let $V, W \in C_{c}^{3}\left(A, 2 R: B, E_{D}\right)$ be two non-commutative functions such that $V$ and $V+W$ are $(c, 2 R)$ h-convex for some $c>0$. We assume that for any $\alpha \in[0,1]$, there exists a solution $\left(X_{1}^{V+\alpha W}, \ldots, X_{n}^{V+\alpha W}\right) \in A_{R / 3, U l t r a A p p}^{n}$ with conjugate variables $\left(\mathscr{D}_{i}(V+\alpha W)\right)_{1 \leq i \leq n}$.

In subsection B. 9 we describe a class of quartic potentials satisfying this assumption. The existence of a solution to the Schwinger-Dyson equation will be obtained from a random matrix model in the case $B=\mathbb{C}$ and the convexity will be obtained by operator spaces techniques.

Assumption 1 ensures that

$$
V_{\alpha}=V+\alpha W
$$

is $(c, 2 R)$ convex for all $\alpha \in[0,1]$.
We consider the SDE

$$
\begin{equation*}
X_{t}^{\alpha}=X_{0}+S_{t}-\frac{1}{2} \int_{0}^{t} \mathscr{D} V_{\alpha}\left(X_{s}^{\alpha}\right) d s \tag{21}
\end{equation*}
$$

where $S$ is the free Brownian motion relative to $D$ (with covariance map $i d_{D}$ ). By Proposition 5, we deduce that there exists a unique solution $X_{t}$ satisfying $\left\|X_{t}\right\|<R$ for any $X_{0} \in A_{R / 3}^{n}$. We denote it by $X_{t}^{\alpha}\left(X_{0},\left\{S_{s}, s \in[0, t]\right\}\right), t \geq 0$, and $X_{t}^{\alpha}$ in short. We set for $U \subset A_{R}^{n}, U_{\alpha}$ be the subset of its elements stable under the flow:

$$
U_{\alpha}=\left\{X_{0} \in U: \forall t, \quad X_{t}^{\alpha} \in U\right\}
$$

Lemma 6. Let $U \subset A_{R, \text { UltraApp }}^{n}$. Under Assumption 1, the map

$$
X_{0} \in U_{\alpha} \mapsto X_{t}^{\alpha}\left(X_{0},\left\{S_{s}, s \in[0, t]\right\}\right)
$$

comes from an element in $C_{t r, V, c}^{1,0}\left(A, U_{\alpha}: \mathscr{B}, E_{D}: \mathscr{S}\right)$, and we have for any $\tau<t$ the relation

$$
\begin{equation*}
X_{t}^{\alpha}\left(.,\left\{S_{s}, s \in[0, t]\right\}\right)=\theta_{\tau}^{\prime}\left[X_{t-\tau}^{\alpha}\left(.,,\left\{S_{s}, s \in[0, t-\tau]\right\}\right)\right] \circ_{\tau} X_{\tau}^{\alpha}\left(.,\left\{S_{s}, s \in[0, \tau]\right\}\right) \tag{22}
\end{equation*}
$$

where $\theta_{u}^{\prime}: C_{t r, V, c}^{k, l}\left(A, U_{\alpha}: \mathscr{B}, E_{D}: \mathscr{S}\right) \rightarrow C_{t r, V, c}^{k, l}\left(A, U_{\alpha}: \mathscr{B}, E_{D}: \mathscr{S}_{\geq u}\right)$ is the map induced by the shift $\theta_{u}\left(S_{s}\right)=S_{s+u}-S_{u}$. Moreover, if we also assume $V, W \in C_{c}^{k+l+2}(A, 2 R: \mathscr{B}, D)$, then $X_{0} \mapsto X_{t}^{\alpha}\left(X_{0},\left\{S_{s}, s \in[0, t]\right\}\right) \in C_{c}^{k+l}\left(A, U_{\alpha}:\right.$ $\mathscr{B}, D: \mathscr{S}) \rightarrow C_{t r, V, c}^{k, l}\left(A, U_{\alpha}: \mathscr{B}, E_{D}: \mathscr{S}\right)$. Furthermore, in each case $t \mapsto X_{t}^{\alpha}$ is continuous.

Finally there exists a finite constant $C_{k+l}$ such that, for $k+l \geq 1$ :

$$
\begin{equation*}
\left\|X_{t}^{\alpha}\right\|_{k+l, 0, U_{\alpha}, c, \geq 1} \leq C_{k+l} e^{-c t / 2} \tag{23}
\end{equation*}
$$

Note that $X_{t}^{\alpha}\left(X_{0},\left\{S_{s}, s \in[0, t]\right\}\right)$ above is a non-commutative function without expectation, but can be thought of as an element of this larger space of functions, hence the reference to $l$. Note that most of the results only depend on $k+l$.

Proof. Let $k \geq 1, l \geq 0$ so that $V, W \in C_{c}^{k+l+2}(A, 2 R: \mathscr{B}, D)$. We prove that $X^{\alpha}$ can be seen as a smooth function of $X_{0}, S$, in the sense that it is an element of $C_{c}^{k+l}\left(A, U_{\alpha}: \mathscr{B}, D: \mathscr{S}\right)$. Fix $T$ small enough, $2 \sqrt{T}+T \sup _{X \in A_{2 R}^{n}, i}\left\|\mathscr{D}_{i} V_{\alpha}(X)\right\|_{A} \leq$ $R$. We can construct the associated process on $[0, T]$ by Picard iteration as follows. We let $X^{[0, m]}$ be defined recursively by $X^{[0,0]}=X_{0}$ and for $m \geq 1$,

$$
X_{t}^{[0, m]}=S_{t}-\frac{1}{2} \int_{0}^{t} \mathscr{D} V_{\alpha}\left(X_{u}^{[0, m-1]}\right) d u+X_{0}, t \in[0, T]
$$

Because $\left\|X_{0}\right\| \leq R$, one checks by induction on $m$ that $\left\|X_{t}^{[0, m]}\right\| \leq 2 R$, and so the processes are well defined for all $m$ as a $C_{t r, V, c}^{k, l}$ functions. Since $X_{t}^{[0, m]}$ is obtained from $X_{t}^{[0, m-1]}$ by operations of integration over a subset of $[0, T]$ and composition with $\mathscr{D} V$, we may use Corollary B. 34 and $\mathscr{D} V \in C_{c}^{k+l+1}(A, 2 R: \mathscr{B}, D)^{n}$ to prove that the Picard iteration procedure is first bounded (for $T$ small) and then converges in the norm $\|\cdot\|_{k+l, 0, U_{\alpha}, c}$ (for $T$ even smaller so that the equation is locally lipschitz on the a priori bound obtained before in $\left.\|\cdot\|_{k+l, 0, U_{\alpha}, c}\right)$. We let $X_{s}, s \leq T$ be the limit : it belongs to $C_{c}^{k+l}(A, U: \mathscr{B}, D: \mathscr{S})$ and is the unique solution of (21). By the definition of $U_{\alpha}$, for $X_{0} \in U_{\alpha}, X_{s} \in U_{\alpha}$, in particular $\left\|X_{s}\right\| \leq R$. Hence, we can iterate the process by considering for $s \in[0, T]$ the sequence defined recursively by $X_{t}^{[s, 0]}=X_{s}, t \leq T$ and for $m \geq 1$

$$
X_{t}^{[s, m]}=S_{t}-S_{s}-\frac{1}{2} \int_{s}^{t} \mathscr{D} V_{\alpha}\left(X_{u}^{[s, m-1]}\right) d u+X_{s}, t \in[s, s+T]
$$

Again this sequence converges in the norm $\|\cdot\|_{k+l, 0, U_{\alpha}, c}$ to a limit $X^{[s, \infty]}$. As $V$ is $C_{c}^{k+l+2}(A, 2 R: \mathscr{B}, D)$, such construction has a unique solution so that $X_{t}^{[s, \infty]}=$ $X_{t}^{\left[s^{\prime}, \infty\right]}$ for all $s, s^{\prime} \leq t$. We denote this solution $X^{\alpha}$. It satisfies (22). We continue by induction to construct $X^{\alpha} \in C_{c}^{k+l}\left(A, U_{\alpha}: \mathscr{B}, D: \mathscr{S}\right)$ for all time. The continuity of $t \rightarrow X_{t}$ is clear, as a uniform limit of continuous functions.

We finally show (23). We apply formula (47) from the proof of Lemma B. 33 in the Appendix to the equation on Picard iterates and then take the limit $m \rightarrow \infty$. One gets for $k \geq 1$ :

$$
\begin{equation*}
\partial_{\left(j_{1}, \ldots, j_{k}\right)}^{k} X_{t}^{(i)}=-\frac{1}{2} \int_{s}^{t} d u \sum_{j} \partial_{j} \mathscr{D}_{i} V_{\alpha}\left(X_{u}\right) \# \partial_{\left(j_{1}, \ldots, j_{k}\right)}^{k} X_{u}^{(j)}+\text { l.o.t }+\partial_{\left(j_{1}, \ldots, j_{k}\right)}^{k} X_{s} \tag{24}
\end{equation*}
$$

where the lower order terms (l.o.t.) are with respect to the degree $k$ of differentiation of $X_{u}$. Evaluating the differentials and using Lemma 4.(b), one gets the exponentially decreasing bound on their norms by induction over $k$ (note that all the other lower order terms are non-linear in derivatives of $X_{t}$ and thus bring more than one exponentially decreasing term, compensating the increase via time integrals).

Lemma 7 (Itô's formula). Under Assumption 1, for $P \in B\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}$ we have

$$
\begin{gathered}
\left.P\left(E_{D, X_{t}^{\alpha}}\right)\left(X_{t}^{\alpha}\right)=P\left(E_{D, X_{0}^{\alpha}}\right)\left(X_{0}^{\alpha}\right)+\frac{1}{2} \int_{0}^{t}\left[\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) P\right]\left(E_{D, X_{s}^{\alpha}}\right)\left(X_{s}^{\alpha}\right) d \xi 25\right) \\
+\int_{0}^{t} \partial\left[P\left(E_{D, X_{s}^{\alpha}}\right)\left(X_{s}^{\alpha}\right)\right] \# d S_{s}
\end{gathered}
$$

Proof. For $P$ (later called polynomial) in the algebra generated by $B, X_{1}, \ldots, X_{n}$ inside $B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$, this is the standard Itô's formula, see [BS98, BS01]. By the norm continuity of all operations appearing, the extensions to $\ell^{1}$ direct sums are obvious, so that it suffices to extend the formula to a monomial $P \in B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$ having only one term in the direct sum. Finally, using the standard decomposition of elements in the extended Haagerup tensor products [M97] we note that $P \in B^{\stackrel{\mathrm{eh}}{\otimes n} n}$ can be written $P=x_{1} \otimes_{D} \ldots \otimes_{D} x_{n}$ with $x_{1} \in M_{1, I_{1}}(D), x_{i} \in M_{I_{i-1}, I_{i}}(D)$ with $I_{j}$ infinite indexing sets but $I_{n}=1$. We can truncate these infinite matrices by finite matrices, giving a net of approximation $P_{n}$ of $P$. All the terms in Itô's formula, once evaluated at a given time, will then converge in $L^{2}(M)$ (while staying bounded in $M$ ). Unfortunately, to get convergence of the time integrals we have to be a bit more careful. Considering evaluations into $L^{\infty}([0, T], A)$ it is only possible to get a bounded net $P_{n}$ of polynomials such that $P_{n}\left(X_{t}^{\alpha}\right), P_{n}\left(X_{0}^{\alpha}\right)$ converges weak-* to $P\left(X_{t}^{\alpha}\right), P\left(X_{0}^{\alpha}\right)$, in $A, \partial\left[P_{n}\left(X_{s}^{\alpha}\right)\right]$ converges weak-* to $\partial\left[P\left(X_{s}^{\alpha}\right)\right]$ in $A \stackrel{\text { eh }}{\otimes} A$. For every $s \in[0, t], s \mapsto\left[\Delta_{V_{\alpha}} P_{n}\right]\left(X_{s}^{\alpha}\right)$ converges weak-* to $s \mapsto\left[\Delta_{V_{\alpha}} P\right]\left(X_{s}^{\alpha}\right)$ in $L^{\infty}([0, t], A)$. Then considering constant functions with value in $L^{1}(A)$, we deduce the first line in the right hand side of Itô formula for $P_{n}$ weak-* converges to the one for $P$ in $A$. To check the same result for the stochastic integral term, note that by the free analog of the Clarck-Ocone formula (see Proposition 5.3.12 in [BS98]) and a priori boundedness of all the stochastic integrals, it suffices to check that for an adapted bounded $U_{s}$, we have convergence to 0 of the pairing

$$
\left\langle\int_{0}^{t} \partial\left[\left(P_{n}-P\right)\left(X_{s}^{\alpha}\right)\right] \# d S_{s}, \int_{0}^{t} U_{s} \# d S_{s}\right\rangle=\int_{0}^{t}\left\langle\partial\left[\left(P_{n}-P\right)\left(X_{s}^{\alpha}\right)\right], U_{s}\right\rangle d s
$$

Since $\left(P_{n}-P\right)$ is a bounded net in $B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle, r=\sup _{s \in[0, t]}\left\|X_{s}^{\alpha}\right\|<R$ and $X_{s}^{\alpha}$ is continuous, for $p$ large enough $\sup _{s \in[0, t]}\left\|X_{s}^{\alpha}-X_{\lfloor p s\rfloor / p}^{\alpha}\right\|$ is so small that $\left.\left.\| \partial\left[\left(P_{n}-P\right)\left(X_{s}^{\alpha}\right)\right)\right]-\partial\left[\left(P_{n}-P\right)\left(X_{\lfloor p s\rfloor / p}^{\alpha}\right)\right)\right] \| \leq \epsilon$ uniformly in $n$ for an arbitrary $\epsilon>0$.

Finally $U \in L^{2}\left([0, t], L^{2}(A) \otimes_{D} L^{2}(A)\right)$ so that approximating it by a process with finitely many values and using weak-* convergence of the finitely many values of $\partial\left[\left(P_{n}-P\right)\left(X_{\lfloor p s\rfloor / p}^{\alpha}\right)\right]$, one gets $\int_{0}^{t}\left\langle\partial\left[\left(P_{n}-P\right)\left(X_{\lfloor p s\rfloor / p}^{\alpha}\right)\right], U_{s}\right\rangle d s \rightarrow 0$. This completes the proof of the formula for $P \in B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$.

For $P$ in the algebra generated by $B, X_{1}, \ldots, X_{n}$, notice that the previous computations show that

$$
E_{D}\left[P\left(X_{t}^{\alpha}\right)\right]=E_{D}\left[P\left(X_{0}\right)\right]+\frac{1}{2} \int_{0}^{t} E_{D}\left[\Delta_{V_{\alpha}} P\left(X_{s}^{\alpha}\right)\right] d s
$$

so that by induction over the number of conditional expectations, if $P$ belongs to the algebra generated by $B, X_{1}, \ldots, X_{n}, E_{D}$,

$$
E_{D}\left[P\left(X_{t}^{\alpha}\right)\right]=E_{D}\left[P\left(X_{0}\right)\right]+\frac{1}{2} \int_{0}^{t} \delta_{V_{\alpha}}\left(E_{D}(P)\right)\left(X_{s}^{\alpha}\right) d s
$$

Formula (25) follows for $P$ polynomial in the algebra generated by $B, X_{1}, \ldots, X_{n}, E_{D}$.

The reduction from $P \in B\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}$ to an element of the algebra generated by $B, X_{1}, \ldots, X_{n}, E_{D}$ is similar. Indeed, we can canonically embed $\iota$ : $B\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\} \rightarrow B\left\langle X_{1}, \ldots, X_{n}, S_{j}, j \in \mathbb{N}: D, R\right\rangle$ where the $S_{i}$ are free semi-circle, free with amalgamation over $D$. Each term in $E_{D}$ corresponds to a different set of $S_{i}$ and

$$
P\left(E_{D, X}\right)(X)=E_{W^{*}\left(X_{1}, \ldots, X_{n}, B\right)}\left[\iota(P)\left(X_{1}, \ldots, X_{n}, S_{i}, i \in \mathbb{N}\right)\right] .
$$

The result now follow from weak-* continuity of $E_{W^{*}\left(X_{1}, \ldots, X_{n}, B\right)}$.
3.3. Semigroup. Hereafter, we will often need a second technical assumption on $D \subset B$ to apply Theorem A.20.(3) and Proposition A.24.(2) in the appendix. The appropriate definitions are given in the appendix in subsection A.3.

## Assumption 2. Assume

- either that there exists a $D$-basis of $L^{2}(B)$ as a right $D$ module $\left(f_{i}\right)_{i \in I}$ which is also a $D$-basis of $L^{2}(B)$ as a left $D$ module
- or that $D$ is a $I I_{1}$ factor and that $L^{2}(B)$ is an extremal $D-D$ bimodule.

As discussed in the appendix, the easiest non-trivial example of a pair $(B, D)$ satisfying this assumption is $B=D \rtimes \Gamma$, a crossed product by a countable (or finite) discrete group $\Gamma$. In particular, when $B=D$ this assumption is obviously satisfied.

If $D=\mathbb{C}$ we set $A_{R, A p p}^{n}=A_{R, \text { UltraApp }}^{n}$. Otherwise, we denote by $A_{R, A p p}^{n} \subset$ $A_{R, \text { UltraApp }}^{n}$ the subset requiring additionally that $M=W^{*}\left(B, X_{1}, \ldots, X_{n}\right) \subset$ $W^{*}\left(B, S_{1}, \ldots S_{m}\right)=B *_{D}\left(D \otimes W^{*}\left(S_{1}, \ldots, S_{m}\right)\right)$, i.e., that $M$ is included into the algebra generated by $m$ semicircular variables over $D$ (with $m$ finite or infinite). This will be crucial when applying Theorem A.20.(3) as then the conclusion of this theorem and Proposition A.24.(2) will be available for $M$, i.e. it will follow that $\left\langle e_{D}, \not \# e_{D}\right\rangle$ is a trace on $D^{\prime} \cap M \stackrel{\mathrm{D}}{\stackrel{\mathrm{eh}}{\otimes}} M$.

We define:

$$
A_{R, \alpha}^{n}=\left(A_{R, A p p}^{n}\right)_{\alpha}
$$

Proposition 5 implies that $A_{R / 3, A p p}^{n} \subset A_{R, \alpha}^{n}$. Let

$$
A_{R, \alpha, c o n j}^{n}=\left\{X \in A_{R, \alpha}^{n}, \partial_{i}^{*}(1 \otimes 1) \in W^{*}(X, B), i=1, \ldots, n\right\}
$$

Using [Dab10b, Theorem 27] (first for $V$ polynomial and then for all $V$ by density), one gets that for any $X \in A_{R, \alpha}^{n}, X_{t}^{\alpha} \in A_{R, \alpha, c o n j}^{n}$ for any $t>0$. Hereafter we thus assume that $X_{0} \in A_{R, \alpha, c o n j}^{n}$.

We write $A_{R, \alpha, c o n j 1}^{n}=A_{R, \alpha, c o n j}^{n}, A_{R, \alpha, c o n j 0}^{n}=A_{R, \alpha}^{n}$. Hereafter, we will consider only functions of $X$ and $E_{D, X}$, we therefore drop the dependency in $E_{D, X}$ in the notations. Because we will need later to apply the cyclic gradient to the image of
the semi-group, we will need the following ad'hoc space $C_{t r}^{k, l ;-1}\left(A, A_{R, \alpha, \text { conj }}^{n}\right)$ which is the completion of $B_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}$ for

$$
\|P\|_{C_{t r}^{k, l ;-1}\left(A, U: B, E_{D}\right)}=\|\iota(P)\|_{k, l, U}+1_{k \geq 1} \sum_{p=1}^{l} \sum_{i=1}^{n}\left\|\mathscr{D}_{i}(P)\right\|_{k, p, U}
$$

Generalizations of this norm are discussed in the appendix (44).
Proposition 8. Suppose Assumptions 1 and 2 hold. Let $k \in\{2,3\}, l \geq 0$ be given and assume $V, W \in C_{c}^{k+l+2}(A, 2 R: B, D)$. The process $X_{t}^{\alpha}$ of Lemma 6 defines a strongly continuous semigroup $\varphi_{t}^{\alpha}$ on $C_{t r}^{k, l}\left(A, A_{R, \alpha, \text { conj }}^{n}: B, E_{D}\right)$. If moreover $V, W \in C_{c}^{k+l+3}(A, 2 R: B, D)$, the semigroup $\varphi_{t}^{\alpha}$ is also defined on $C_{t r}^{k, l ;-1}\left(A, A_{R, \alpha, \text { conj }}^{n}: B, E_{D}\right)$. In both cases the semigroup is given by the formula

$$
\varphi_{t}^{\alpha}(P)=E_{0}\left(P\left(X_{t}^{\alpha}\right)\right)
$$

and satisfies the exponential bounds:

$$
\left\|\varphi_{t}^{\alpha}(P)\right\|_{k, l, A_{R, \alpha, c o n j}^{n} \geq 1} \leq C_{k, l}\|P\|_{k, l, A_{R, \alpha, c o n j}^{n} \geq 1} e^{-c t / 2}
$$

Moreover, when restricted to $C_{c}^{k+l}\left(A, A_{R, \alpha, \text { conj }}^{n}: B, E_{D}\right)$, we get strongly continuous one parameter families of maps

$$
\varphi_{t}^{\alpha \prime}: C_{c}^{k+l}\left(A, A_{R, \alpha, c o n j}^{n}: B, E_{D}\right) \rightarrow C_{t r, V_{\alpha}}^{k, l}\left(A, A_{R, \alpha, c o n j}^{n}: B, E_{D}\right)
$$

where $\varphi_{t}^{\alpha}=\iota \varphi_{t}^{\alpha \prime}$ is the canonical map $\iota: C_{t r, V_{\alpha}}^{k, l}\left(A, A_{R, \alpha, c o n j}^{n}: B, E_{D}\right) \rightarrow$ $C_{t r}^{k, l}\left(A, A_{R, \alpha, \text { conj }}^{n}: B, E_{D}\right)$. It satisfies

$$
\left\|\varphi_{t}^{\alpha \prime}(P)\right\|_{C_{t r, V_{\alpha}}^{k, l}\left(A, A_{R, \alpha, c o n j}^{n}\right), \geq 1} \leq C_{k}\|P\|_{k, l, A_{R, \alpha, c o n j}^{n} \geq 1} e^{-c t / 2}
$$

Proof. $\varphi_{t}^{\alpha}$ is well defined in all cases by composing the maps $X_{t}^{\alpha}$ from Lemma 6 , the composition $\left(P, X_{t}\right) \rightarrow P\left(X_{t}\right)$, see Lemma B.33, and expectations $E_{B}$ from Proposition B.38. To get a semigroup we apply composition on $\tilde{U}=U=A_{R, \alpha, c o n j}^{n}$, so we have to check the consistency condition for composition, i.e. for any $X_{0} \in U$, we have to check that $X_{t}^{\alpha}\left(X_{0},\left\{S_{s}, s \in[0, t]\right\}\right)$ has one conjugate variable. This is proved in Proposition B. 42 in the appendix. Note this is where we need Assumption 2 and the condition $A_{R, \alpha}^{n} \subset A_{R, A p p}^{n}$ in order to apply Proposition A. 24 to get $M=W^{*}\left(B, X_{0}\right) *_{D}\left(D \otimes W^{*}\left(S_{t}, t>0\right), \tau=\left\langle e_{D}, \cdot \# e_{D}\right\rangle\right.$ is a trace on $D^{\prime} \cap M \stackrel{\text { eh }}{\otimes} M$. The construction of $\varphi_{t}^{\alpha \prime}$ and the consistency follow similarly.

Let us check the semigroup property. It follows from the following formal computation:

$$
\begin{aligned}
\varphi_{u}^{\alpha}\left(\varphi_{t-u}^{\alpha}(P)\right) & =E_{0}\left(\varphi_{t-u}^{\alpha}(P) \circ X_{u}\left(.,\left\{S_{s}, s \in[0, u]\right\}\right)\right) \\
& =E_{0}\left(\left[E_{0}\left(P \circ X_{t-u}\left(.,\left\{S_{s}, s \in[0, t-u]\right\}\right)\right)\right] \circ X_{u}\left(.,\left\{S_{s}, s \in[0, u]\right\}\right)\right) \\
& =E_{0}\left(E_{u}\left(\theta_{u}^{\prime}\left[\left(P \circ X_{t-u}\left(.,\left\{S_{s}, s \in[0, t-u]\right\}\right)\right] \circ_{u} X_{u}\left(.,\left\{S_{s}, s \in[0, u]\right\}\right)\right)\right)\right. \\
& =E_{0}\left(E_{u}\left(P \circ\left[\theta_{u}^{\prime}\left[\left(X_{t-u}\left(.,\left\{S_{s}, s \in[0, t-u]\right\}\right)\right] \circ_{u} X_{u}\left(.,\left\{S_{s}, s \in[0, u]\right\}\right)\right]\right)\right)\right. \\
& =E_{0}\left(E_{u}\left(P \circ X_{t}\left(.,\left\{S_{s}, s \in[0, t]\right\}\right)\right)\right) \\
& =E_{0}\left(P \circ X_{t}\left(.,\left\{S_{s}, s \in[0, t]\right\}\right)\right) \\
& =\varphi_{t}^{\alpha}(P)
\end{aligned}
$$

where $\circ_{u}$ is the composition defined in Proposition B.38. To justify this computation, the two first and last equations are the definitions of the "semigroup", third, fourth and next-to-last lines come from Proposition B. 38 and the fifth line from Lemma 6 . We thus have the semigroup relation. Strong continuity on both spaces comes from continuity in $u$ of $X_{u}^{\alpha}$ (see Lemma 6) and continuity of various compositions and $E_{0}$ (see Proposition B.38).

Using the variant of (48) with $U=V=A_{R, \alpha, c o n j}^{n}$, in the context of Proposition B.38, that is adding the Brownian motion filtration, we get

$$
\begin{aligned}
& \left\|P\left(X_{t}\right)\right\|_{k, l, U \geq 1} \\
& \leq C(k, l, n)\|P\|_{k, l, V \geq 1}\left(1+\max _{i=1, \ldots, n}\left\|X_{t}^{i}\right\|_{k, l, U \geq 1}\right)^{k+l-1} \max _{i=1, \ldots, n}\left\|X_{t}^{i}\right\|_{k, l, U \geq 1}
\end{aligned}
$$

Using contractivity of expectations in Proposition B. 38 and bounds in Lemmas B. 32 and 6, one gets the exponential bounds as claimed. The bounds for the seminorm $\left\|P\left(X_{t}\right)\right\|_{k, l, U \geq 1}$ follow similarly.

Moreover, we get similar results for $\varphi^{\alpha \prime}$ by noticing that if $P \in$ $C_{c}^{k+l}\left(A, A_{R, \alpha, c o n j}^{n}, B, E_{D}\right)$, then $P\left(X_{t}^{\alpha}\right) \in C_{c}^{k+l}\left(A, A_{R, \alpha, c o n j}^{n}, B, E_{D}: \mathscr{S}\right)$. The seminorm on this space is equivalent to $\left\|P\left(X_{t}\right)\right\|_{k, l, U \geq 1}$ which we already estimated. Continuity of conditional expectation, see Proposition B.38, gives the exponential bounds for $\varphi^{\alpha \prime}$.

We next find the generator for the semi-group $\varphi_{t}^{\alpha \prime}$ : it is given by $L_{\alpha}=\frac{1}{2}\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right)$ and in the next Lemma we describe some dense domains of this generator (without looking for the maximal one).

Proposition 9. Under Assumptions 1 and 2 let $k \in\{2,3\}, l \geq 2$, be given, and assume that $V, W \in C_{c}^{k+l+2}(A, 2 R: B, D)$ as before. Let $\iota^{\prime}$ be the canonical map

$$
\iota^{\prime}: C_{t r, V_{\alpha}}^{k, l}\left(A, A_{R, \alpha, c o n j}^{n}: B, E_{D}\right) \rightarrow C_{t r}^{k-2,0 ;-1}\left(A, A_{R, \alpha, c o n j}^{n}: B, E_{D}\right)
$$

Then for any $P \in C_{c}^{k+l}\left(A, A_{R, \alpha, c o n j}^{n}: B, E_{D}\right), k \geq 2, t \mapsto \iota^{\prime}\left(\varphi_{t}^{\alpha \prime}(P)\right)$ is $C^{1}$ and

$$
\frac{\partial}{\partial t} \iota^{\prime}\left(\varphi_{t}^{\alpha \prime}(P)\right)=L_{\alpha}\left(\varphi_{t}^{\alpha \prime}(P)\right)
$$

where $L_{\alpha}: C_{t r, V_{\alpha}}^{k, l}\left(A, A_{R, \alpha, \text { con } j}^{n}: B, E_{D}\right) \rightarrow C_{t r}^{k-2,0 ;-1}\left(A, A_{R, \alpha, \text { con } j}^{n}: B, E_{D}\right)$ is given by $L_{\alpha}=\frac{1}{2}\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right)$.
Proof. To compute the generator we start with the Itô formula (25). Taking a conditional expectation, we deduce for $P \in B_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}$,
$\varphi_{t}^{\alpha}(P)\left(X_{0}\right)-P\left(X_{0}\right)-\frac{t}{2}\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) P\left(X_{0}\right)=\frac{1}{2} \int_{0}^{t}\left(\varphi_{s}^{\alpha}-\varphi_{0}^{\alpha}\right)\left[\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) P\right]\left(X_{0}\right) d s$.
We now want to check the same relation under a full cyclic gradient $\mathscr{D}$. We need to check that all the terms above are in $C_{t r}^{k, 1 ;-1}\left(A, R: B, E_{D}\right)$ for our chosen $P$. But we won't check that the relation (26) is valid in this space, we will only show this relation holds after application of the cyclic gradient in each representation. Indeed, we do not know if the full cyclic gradient $\mathscr{D}$ is closable, in contrast to the free difference quotient.

From the definition of $\left[\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) P\right]$ (see Def. (15)) as an evaluation of

$$
\left[\Delta_{V_{0}(Z)}+\delta_{V_{0}(Z)}\right](P) \in B_{c}\left\{X_{1}, \ldots, X_{n}, Z_{1}, \ldots, Z_{n}: E_{D}, R, \max _{i}\left(\left\|\mathscr{D}_{i} V_{\alpha}\right\|_{0,0, A_{R}^{n}}\right) \mathbb{C}\right\}
$$

at $(X, Z)=\left(X, \mathscr{D} V_{\alpha}(X)\right) \in\left(C_{c}^{k+2}\left(A, 2 R, B, E_{D}\right)\right)^{2 n}$, the fourth composition result in Corollary B. 34 gives the expected $\left[\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) P\right] \in C_{t r}^{k, 1 ;-1}\left(A, R: B, E_{D}\right)$. The fact that the terms below semigroups are in the expected space then follows from Proposition 8 since $V, W \in C_{c}^{k+4}\left(A, 2 R, B, E_{D}\right)$.

Note that all our terms are known to be in our expected space, thus we can apply (50) so that the equation (26) under $\mathscr{D}$ is true in any representation $X_{0} \in A_{R, \alpha}^{n}$ if it is true under the differential $d_{X_{0}}$. Integrals are dealt with thanks to the continuity of the semigroup with value in $C_{t r}^{k, l ;-1}\left(A, R: B, E_{D}\right)$ from the previous Lemma. Seeing both sides of the equation (26) as a function of $X_{0}$, one can differentiate both sides of (26) under $d_{X_{0}}$ and obtain equality of both sides in each representation. We deduce the equality under the abstract $d_{X_{0}}$-differential in $C_{t r}^{*}$ by injectivity of the map from $C_{t r}^{0, l}$ to $C^{0}\left(A_{R, \alpha}^{n}, A\right)$ (in contrast to the space $C_{t r}^{k, 1 ;-1}$ before where this is unknown). We have thus deduced the equality in each representation :

$$
\begin{aligned}
\mathscr{D}_{X_{0}, i} \varphi_{t}^{\alpha}(P)\left(X_{0}\right)- & \mathscr{D}_{X_{0}, i} P\left(X_{0}\right)-\frac{t}{2} \mathscr{D}_{X_{0}, i}\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) P\left(X_{0}\right) \\
& =\frac{1}{2} \int_{0}^{t} \mathscr{D}_{X_{0}, i}\left(\varphi_{s}^{\alpha}-\varphi_{0}^{\alpha}\right)\left[\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) P\right]\left(X_{0}\right) d s .
\end{aligned}
$$

Applying Lemma B. 35 and seeing $P$ as an element of $C_{t r, V_{\alpha}}^{k, l}\left(A, A_{R, \alpha, c o n j}^{n}\right)$, one knows that all the terms of the equality are in the domain of order $k-2$ free difference quotient and without having applied cyclic derivative, also in the domain of order $k-2$ free difference quotient (since $k, l \geq 2$ ). By closability, if $X_{0} \in$ $A_{R, \alpha, c o n j}^{n}$ we can apply the $k-2$ order free difference quotient to the relation above and deduce corresponding relations. Therefore, the following bound extends for $k \geq 2$ to $P \in C_{t r, V_{\alpha}}^{k, l}\left(A, A_{R, \alpha, \text { con } j}^{n}\right):$

$$
\begin{aligned}
& \left\|\frac{1}{t}\left(\varphi_{t}^{\alpha}(P)-P\right)-\frac{1}{2}\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) P\right\|_{k-2,0 ;-1, A_{R, \alpha, c o n j}^{n}} \\
& \quad \leq \frac{1}{2 t} \int_{0}^{t}\left\|\left(\varphi_{s}^{\alpha}-\varphi_{0}^{\alpha}\right)\left[\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) P\right]\right\|_{k-2,0 ;-1, A_{R, \alpha, c o n j}^{n}} \rightarrow 0
\end{aligned}
$$

goes to zero when $t \rightarrow 0^{+}$, by the strong continuity of $\varphi_{s}^{\alpha}$ on $C_{t r}^{k-2,0 ;-1}\left(A, A_{R, \alpha, c o n j}^{n}\right)$. This gives the right derivative of $\varphi_{t}^{\alpha}$ at zero.

Now for $Q \in C_{c}^{k+l}\left(A, A_{R, \alpha, c o n j}^{n}, B, E_{D}\right)$, by the semigroup property $\varphi_{s+t}^{\alpha}(Q)=$ $\varphi_{s}^{\alpha}\left(\iota^{\prime} \varphi_{t}^{\alpha \prime}(Q)\right)$ and applying the reasoning above to $P=\varphi_{t}^{\alpha \prime}(Q)$, one gets the right derivative at any time.

To compute the left derivative, we start similarly from the result of the Itô formula to $P=\varphi_{t-s}^{\alpha \prime} Q$ starting at time $t-s$ and using also the semigroup property

$$
\begin{aligned}
\varphi_{t} & (Q)\left(X_{0}\right)-\varphi_{t-s}(Q)\left(X_{0}\right)-\frac{s}{2}\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) \varphi_{t}^{\alpha \prime}(Q)\left(X_{0}\right) \\
& =\frac{1}{2} \int_{t-s}^{t}\left(\varphi_{u-t+s}^{\alpha}\left[\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) \varphi_{t-s}^{\alpha \prime} Q\right]-\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) \varphi_{t}^{\alpha \prime}(Q)\right)\left(X_{0}\right) d u \\
& =\frac{1}{2} \int_{t-s}^{t} \varphi_{u-t+s}^{\alpha}\left[\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right)\left(\varphi_{t-s}^{\alpha \prime}-\varphi_{t}^{\alpha \prime}\right)(Q)\right]\left(X_{0}\right) d u \\
& +\frac{1}{2} \int_{t-s}^{t}\left(\varphi_{u-t+s}^{\alpha}-\varphi_{0}^{\alpha}\right)\left[\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) \varphi_{t}^{\alpha \prime}(Q)\right]\left(X_{0}\right) d u
\end{aligned}
$$

Thus, using strong continuity of $\varphi^{\alpha}$ and $\varphi^{\alpha \prime}$, and reasoning as before in the more general spaces with some free difference quotient and cyclic derivative, we conclude that the left derivative is in $C_{t r}^{k-2,0 ;-1}\left(A, A_{R, \alpha, c o n j}^{n}\right)$.

## 4. Construction of the Transport Map

Let $F \in C_{t r}^{k, l}(A, U)^{n}, k, l \geq 1$. Let $X=\left(X_{1}, \ldots, X_{n}\right) \in U$. Then we define $\partial_{F}=\left(\partial_{F^{1}}, \ldots, \partial_{F^{n}}\right)$ on $B\left\langle F^{1}(X), \ldots, F^{n}(X)\right\rangle$ as the free difference quotient of the variables $F^{1}(X), \ldots, F^{n}(X)$. Assume $W^{*}\left(B, X_{1}, \ldots, X_{n}\right)=M \subset(A, \tau)$ and let $S$ be a semicircle variable, free from $M$ with amalgamation over $D$. Let $q \in D^{\prime} \cap M \stackrel{\text { eh }}{\otimes} M$. The adjoint $\partial_{F}^{*}$ of $\partial_{F}$, when it exists, is given by

$$
\tau\left((q \# S)^{*} \partial_{F^{i}} P \# S\right)=\tau\left(\left(\partial_{F^{i}}^{*}(q)\right)^{*} P\right), \quad 1 \leq i \leq n
$$

The Jacobian matrix is given by $\mathscr{J}(F)=\left(\partial_{j} F_{i}\right)_{i j}$. We define for $G \in C_{t r}^{1,1}(A, U)^{n}$, $\mathscr{J}_{F}(G)=\left(\partial_{F^{j}} G^{i}\right)_{1 \leq i, j \leq n}$. Its adjoint is given for $q \in M_{n}\left(D^{\prime} \cap M \underset{D}{\underset{D}{\otimes}} M\right)$ by

$$
\mathscr{J}_{F}^{*}(q)=\left(\sum_{i} \partial_{F^{i}}^{*}\left(q_{j i}\right)\right)_{j=1}^{n}
$$

We will need the following preparatory lemma regarding conjugate variables. We will need a temporary technical assumption, satisfied under Assumption 2 if $X_{0} \in A_{R, A p p}^{n}$ as shown in the proof of Proposition 8. This will thus be the case for semicircular variables and then via our transport map for other models with $h$-convex potential.

Assumption 3. Assume $W^{*}\left(B, X_{0}\right)=M \subset(A, \tau)$ is such that $X \mapsto \tau(S X \# S)$ is a trace on $D^{\prime} \cap M \stackrel{\otimes}{\otimes} \stackrel{\mathrm{eh}}{\otimes} M$ if $S$ is a semicircle variable, free from $M$ with amalgamation over $D$.

Lemma 10. Assume Assumption 3. Fix such an $X \in U$ with $U \subset A_{R, c o n j}^{n}$. Take $l \geq 0$. Consider a $C^{1}$ map $\alpha \mapsto F_{\alpha} \in C_{t r}^{k, l}(A, U)^{n}$, on $\left[0, \alpha_{0}\right]$ for $k \geq 2$, so that $F_{0}=X_{0},\left\|1-\mathscr{J}\left(F_{\alpha}\right)\right\|_{M_{n}\left(M_{\substack{\text { eh } \\ \otimes, c}}^{\text {eh }} M\right)}<1$. Let $1 \otimes 1$ be the diagonal matrix with
entries $1 \otimes_{D} 1$ on the diagonal. Then $\mathscr{J}_{F_{\alpha}}^{*}(1 \otimes 1) \in M^{n}$ exists for any $\alpha \in\left[0, \alpha_{0}\right]$, $\alpha \mapsto \mathscr{J}_{F_{\alpha}}^{*}(1 \otimes 1)$ is in $C^{1}\left(\left[0, \alpha_{0}\right], M^{n}\right)$ and

$$
\begin{equation*}
\frac{d}{d \alpha} \mathscr{J}_{F_{\alpha}}^{*}(1 \otimes 1)=-\mathscr{J}_{F_{\alpha}}^{*}\left(\left[\mathscr{J}_{F_{\alpha}}\left(\partial_{\alpha} F_{\alpha}\right)\right]^{*}\right) \tag{27}
\end{equation*}
$$

Proof. The existence of the conjugate variable is a technical variant of [GS12] explained in the appendix, see Lemma B.39. It is also shown there that

$$
\mathscr{J}_{F_{\alpha}}^{*}(1 \otimes 1)=\mathscr{J}^{*}\left(\left[\mathscr{J} F_{\alpha}\right]^{-1, *}\right)
$$

where we have used the notation $A^{-1, *}=\left(A^{-1}\right)^{*}$. Let us compute the time derivative of the right hand side. From the elementary equation $A^{-1}-B^{-1}=$ $A^{-1}(B-A) B^{-1}$, one deduces an equation on $\left(\mathscr{J} F_{\alpha+h}\right)^{-1}$ which after taking the adjoint reads

$$
\begin{aligned}
& {\left[\mathscr{J} F_{\alpha+h}\right]^{-1, *}=\left[\mathscr{J} F_{\alpha}\right]^{-1, *}-h\left[\mathscr{J} F_{\alpha}\right]^{-1, *}\left[\mathscr{J} \partial_{\alpha} F_{\alpha}\right]^{*}\left[\mathscr{J} F_{\alpha}\right]^{-1, *}} \\
& \quad-\left[\mathscr{J} F_{\alpha+h}\right]^{-1, *}\left[\mathscr{J} F_{\alpha+h}-\mathscr{J} F_{\alpha}-h \mathscr{J} \partial_{\alpha} F_{\alpha}\right]^{*}\left[\mathscr{J} F_{\alpha}\right]^{-1, *} \\
& +h\left(\left[\mathscr{J} F_{\alpha+h}\right]^{-1, *}\left[\mathscr{J} F_{\alpha+h}-\mathscr{J} F_{\alpha}\right]^{*}\left[\mathscr{J} F_{\alpha}\right]^{-1, *}\left[\mathscr{J} \partial_{\alpha} F_{\alpha}\right]^{*}\left[\mathscr{J} F_{\alpha}\right]^{-1, *}\right) .
\end{aligned}
$$

Since by Lemma B.36.(1) the map $\left({\overline{\partial_{i} \otimes_{D} 1}}^{e h} \oplus{\overline{1 \otimes_{D} \partial_{i}}}^{e h}\right)$ is a derivation, its domain $D\left(\left({\overline{\partial_{i} \otimes_{D} 1}}^{e h} \oplus{\overline{1 \otimes_{D} \partial_{i}}}^{e h}\right)\right)$ is an algebra. Since all the terms in the equation above are in a matrix variant of the domain of $\left({\overline{\partial_{i} \otimes_{D} 1}}^{e h} \oplus{\overline{1 \otimes_{D} \partial_{i}}}^{e h}\right)$ and $\mathscr{J} F_{\alpha+h}$ is differentiable in this space (using $k \geq 2$ ), we can deduce differentiability under $\mathscr{J}^{*}$ from Lemma B.36.(4). Thus after letting $h$ go to zero we can conclude that

$$
\frac{d}{d \alpha}\left(\mathscr{J}_{F_{\alpha}}^{*} 1 \otimes 1\right)=-\mathscr{J}^{*}\left[\left[\mathscr{J} F_{\alpha}\right]^{-1, *}\right]\left[\mathscr{J} \partial_{\alpha} F_{\alpha}\right]^{*}\left[\mathscr{J}_{F_{0}} F_{\alpha}\right]^{-1, *}
$$

A version of the chain rule holds for any $g \in C_{t r}^{1,0}(A, U)^{n}$ :

$$
\begin{equation*}
\mathscr{J} g\left(F_{\alpha}\right)=\mathscr{J}_{F_{\alpha}} g \# \mathscr{J} F_{\alpha} \tag{28}
\end{equation*}
$$

so that, by taking $g=\partial_{\alpha} F_{\alpha}$,

$$
\left[\mathscr{J} \partial_{\alpha} F_{\alpha}\right]^{*}=\left[\mathscr{J}_{F_{\alpha}} \partial_{\alpha} F_{\alpha} \# \mathscr{J} F_{\alpha}\right]^{*}=\left[\mathscr{J} F_{\alpha}\right]^{*} \#\left[\mathscr{J} F_{\alpha} \partial_{\alpha} F_{\alpha}\right]^{*}
$$

This completes the proof.
We will now continue with the construction of the transport map $F_{\alpha}$.
Lemma 11. Assume that $V, W, B, D, X=X_{0}$ satisfy Assumptions 1, 2 and 3 and that $V, W \in C_{c}^{6}(A, 2 R: B, D)$, and $X_{0} \in A_{R / 4, c o n j}^{n}$. Let

$$
\mathscr{D} g_{\alpha}:=-\frac{1}{2} \int_{0}^{\infty} \mathscr{D}\left(\varphi_{t}^{\alpha \prime}(W)\right) d t \in C_{t r, V_{\alpha}}^{2,1}\left(A, A_{R, \alpha, c o n j}^{n}: B, E_{D}\right)
$$

Then $\mathscr{D} g_{\alpha}$ satisfies the equation in $C_{t r}^{0,0}\left(A, A_{R, \alpha, c o n j}^{n}: B, E_{D}\right)$ :

$$
\begin{equation*}
\mathscr{D}(W)=\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right)\left(\mathscr{D} g_{\alpha}\right)-\sum_{j=1}^{n} \mathscr{D}_{., \mathscr{D}_{j} g_{\alpha}} \mathscr{D}_{j} V_{\alpha} \tag{29}
\end{equation*}
$$

Moreover, there exists $\alpha_{0} \in(0,1], \alpha_{0}=\alpha_{0}\left(c, R, \sup _{\beta \in[0,1]}\left\|\mathscr{D} g_{\beta}\right\|_{C_{t r}^{2,1}\left(A, A_{R / 3, c o n j}^{n}: B, E_{D}\right)}\right)$, non-increasing in the last variable, so that the differential equation

$$
\frac{d}{d \alpha} F_{\alpha}=\mathscr{D} g_{\alpha}\left(F_{\alpha}\right)=\left(\mathscr{D}_{1} g_{\alpha}\left(F_{\alpha}\right), \ldots, \mathscr{D}_{n} g_{\alpha}\left(F_{\alpha}\right)\right), \quad F_{0}=X
$$

has a unique solution in the space $C_{t r}^{2,2}\left(A, A_{R / 4, \text { conj }}^{n}: B, E_{D}\right)$ for all times $\alpha \in$ $\left[0, \alpha_{0}\right]$.

Proof. The integral defining $\mathscr{D} g_{\alpha}$ exists in the space $C_{t r, c}^{2,1}\left(A, A_{R, \alpha, c o n j}^{n}: B, E_{D}\right)$ because of the exponential bound in Proposition 8 (with $k=2, l=2$ ). From the computation of the derivative in $C_{t r, V_{\alpha}}^{0,0 ;-1}\left(A, A_{R, \alpha, c o n j}^{n}: B, E_{D}\right)$ in Proposition 9 , one gets that the derivative is in $C_{t r}^{0,0}\left(A, A_{R, \alpha, c o n j}^{n}: B, E_{D}\right)$, and is given by

$$
\frac{\partial}{\partial t} \mathscr{D}\left(\varphi_{t}^{\alpha \prime}(W)\right)=\mathscr{D}\left(L_{\alpha}\left(\varphi_{t}^{\alpha \prime}(W)\right)\right)=L_{\alpha} \mathscr{D}\left(\varphi_{t}^{\alpha \prime}(W)\right)-\frac{1}{2} \sum_{j=1}^{n} \mathscr{D}_{., \mathscr{D}_{j}\left(\varphi_{t}^{\alpha \prime}(W)\right)} \mathscr{D}_{j} V_{\alpha}
$$

where the last identity comes from Lemma B. 35 with $g=\varphi_{t}^{\alpha \prime}(W)$ and $k=0$. Integrating in $t$ and since $\mathscr{D}\left(\varphi_{t}^{\alpha \prime}(W)\right)$ tends to 0 when $t \rightarrow \infty$, one gets the identity in $C_{t r}^{0,0}\left(A, A_{R, \alpha, c o n j}^{n}: B, E_{D}\right)$ :

$$
\mathscr{D}(W)=\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right)\left(\mathscr{D} g_{\alpha}\right)-\sum_{j=1}^{n} \mathscr{D}, \mathscr{D}_{j} g_{\alpha} \mathscr{D}_{j} V_{\alpha} .
$$

Fix $\alpha>0$. We next define an appropriate space on which the following map

$$
\chi: F \mapsto\left(\gamma \in[0, \alpha] \mapsto \chi_{\gamma}=F_{0}+\int_{0}^{\gamma} \mathscr{D} g_{\beta}\left(F_{\beta}\right) d \beta\right)
$$

will be a contraction for $\alpha$ small enough. We take $F_{\beta} \in A_{R / 3, c o n j}^{n} \subset A_{R, \beta, \text { conj }}^{n}$ to stay in a space independent of $\beta$. We set, for $\alpha$ to be chosen small enough and for any fixed $K>\left\|F_{0}^{i}\right\|_{2,0, A_{R / 4, c o n j}^{n}} c$,

$$
\begin{aligned}
& \mathcal{E}_{\alpha, K}=\left\{F \in C^{0}\left([0, \alpha],\left(C_{t r, c}^{2,0}\left(A, A_{R / 4, \text { conj }}^{n}: B, E_{D}\right)\right)^{n}\right): F_{0}(X)=X, \forall \beta \in[0, \alpha]\right. \\
& \quad\left\|1-\mathscr{J} F_{\beta}\right\|_{M_{n}\left(M_{\substack{\text { eh } \\
D, c}} \leq \leq \frac{1}{2}, \sup _{X \in A_{R / 4, c o n j}^{n}}\left\|F_{\beta}^{i}(X)\right\| \leq R / 3,\left\|F_{\beta}^{i}\right\|_{2,0, A_{R / 4, c o n j}^{n}, c}^{n} \leq K\right\} .} .
\end{aligned}
$$

First, note that $\mathcal{E}_{\alpha, K}$ is a closed convex set of $C^{0}\left([0, \alpha],\left(C_{t r, c}^{2,0}\left(A, A_{R / 4, c o n j}^{n}\right.\right.\right.$ : $\left.\left.B, E_{D}\right)\right)^{n}$ ), thus it is complete metric space.

By the previous lemma (note that we don't need at this point to know that $\alpha \mapsto F_{\alpha}$ is $\left.C^{1}\right)$, for $F \in \mathcal{E}_{\alpha, K}, \mathscr{J}_{F_{\beta}}^{*}(1 \otimes 1)$ exists for $\beta \leq \alpha$. Thus for any $X \in$ $A_{R / 4, c o n j}^{n}, F_{\beta}(X) \in A_{R / 3, c o n j}^{n}$ and we are in position to apply Lemma B. 33 to get $\mathscr{D} g_{\beta}\left(F_{\beta}\right) \in C_{t r}^{2,0}\left(A, A_{R / 3, \text { conj }}^{n}: B, E_{D}\right)^{n}$. Moreover, applying Lemma B.41, and the same exponential decay as before, to deal with the tail of the integral, we see that $\beta \in[0,1] \mapsto \mathscr{D} g_{\beta} \in C_{t r, c}^{2,1}\left(A, A_{R / 3, c o n j}^{n}: B, E_{D}\right)$ is continuous. Using Lemma B. 33 for composition, $\alpha \in[0,1] \mapsto \mathscr{D} g_{\alpha}\left(F_{\alpha}\right) \in C_{t r, c}^{2,0}\left(A, A_{R / 4, c o n j}^{n}: B, E_{D}\right)$ is also continuous so that the integral defining $\chi$ makes sense. Hence $\chi$ is well defined on $\mathcal{E}_{\alpha, K}$ with value in $C^{0}\left([0, \alpha],\left(C_{t r}^{2,0}\left(A, A_{R / 4, \text { conj }}^{n}: B, E_{D}\right)\right)^{n}\right)$. For $\alpha$ such that

$$
\frac{R}{4}+\alpha \sup _{\beta \in[0,1]}\left\|\mathscr{D} g_{\beta}\right\|_{C_{t r}^{0}\left(A, A_{R / 3, c o n j}^{n}: B, E_{D}\right)} \leq \frac{R}{3}
$$

the image of $\chi$ belongs to $A_{R / 3}^{n}$. Similarly, $\left\|\chi_{\beta}^{i}\right\|_{2,0, A_{R / 4, c o n j}^{n}, c} \leq K$ if $\alpha$ is small enough.

Finally, by the chain rule (28), we have $\mathscr{J} \mathscr{D} g_{\beta}\left(F_{\beta}\right)=\mathscr{J}_{F_{\beta}} \mathscr{D} g_{\beta} \# \mathscr{J} F_{\beta}$ so that

$$
\begin{aligned}
\left\|\mathscr{J} \mathscr{D} g_{\beta}\left(F_{\beta}\right)\right\|_{M_{n}\left(A_{D, c}^{\mathrm{eb}}, A\right)} & \leq\left\|\mathscr{J} F_{\beta}\right\|_{M_{n}\left(A A_{D, c}^{\text {eh }} A\right)}\left\|\mathscr{J} \mathscr{D} g_{\beta}\right\|_{M_{n}(A \underset{D, c}{\text { eh }} A)} \\
& \leq 3 / 2\left\|\mathscr{J} \mathscr{D} g_{\beta}\right\|_{M_{n}(A \underset{D, c}{\text { eh }} \underset{D}{\otimes} A)} .
\end{aligned}
$$

Recalling $\mathscr{J} F_{0}=1$ and using the continuity of $\mathscr{J} \mathscr{D} g_{\beta}$ one can choose $\alpha=\alpha(K)$ small enough such that $\chi$ is valued in $\mathcal{E}_{\alpha, K}$. It remains to obtain a contraction, up to choose $\alpha$ even smaller.

Since $\mathscr{D} g_{\beta}$ lies in a bounded set in $C_{t r, c}^{2,1}\left(A, A_{R / 3, \text { conj }}^{n}: B, E_{D}\right)$ and $\mathcal{E}_{\alpha, K}$ is bounded, $\mathscr{D} g_{\beta}$ is uniformly Lipschitz by Lemma B. 33 , with a Lipschitz norm which does not depend on $\beta \in(0,1)$. Thus $\chi$ is a contraction on $\mathcal{E}_{\alpha, K}$. It has therefore a unique fixed point which is our solution, which is necessarily in $C^{1}\left(\left[0, \alpha_{0}\right],\left(C_{t r}^{2,0}\left(A, A_{R / 4, c o n j}^{n}: B, E_{D}\right)\right)^{n}\right)$.

Lemma 12. Assume the hypotheses of Lemma 11. Let $\Upsilon_{\alpha}=\mathscr{J}_{F_{\alpha}(X)}^{*}(1 \otimes 1)-$ $\mathscr{D} V_{\alpha}\left(F_{\alpha}(X)\right)$, where $F_{\alpha}, \alpha \in\left[0, \alpha_{0}\right]$ is constructed in Lemma 11.

Then $\Upsilon_{\alpha}$ satisfies the following differential equation in $L^{\infty}\left(\left[0, \alpha_{0}\right], W^{*}(X)\right)$ :

$$
\frac{d}{d \alpha} \Upsilon_{\alpha}=-d_{F_{\alpha}}\left[\mathscr{D} g_{\alpha}\left(F_{\alpha}\right) \cdot\left(\Upsilon_{\alpha}\right)\right]
$$

As a consequence, if $\Upsilon_{0}=0$, then $\Upsilon_{\alpha}=0, \forall \alpha \in\left[0, \alpha_{0}\right]$.
In other words, for $\alpha \in\left[0, \alpha_{0}\right], F_{\alpha}(X)$ has conjuguate variables $\mathcal{D} V_{\alpha}$.
Proof. Using our previous computation of the derivative of conjugate variables in Lemma 10, we obtain

$$
\begin{equation*}
\frac{d}{d \alpha} \Upsilon_{\alpha}=-\mathscr{J}_{F_{\alpha}}^{*}\left[\mathscr{J}_{F_{\alpha}} \mathscr{D} g_{\alpha}\left(F_{\alpha}\right)\right]-\mathscr{J} \mathscr{D} V_{\alpha}\left(F_{\alpha}\right) \# \mathscr{D} g_{\alpha}\left(F_{\alpha}\right)-\mathscr{D} W\left(F_{\alpha}\right) \tag{30}
\end{equation*}
$$

We next rewrite the right hand side. To this end, notice that (51) yields

$$
\left(\mathscr{J}_{F_{\alpha}}^{*} \mathscr{J}_{F_{\alpha}} \mathscr{D} g_{\alpha}\left(F_{\alpha}\right)\right)=\mathscr{J} \mathscr{D} g_{\alpha}\left(F_{\alpha}\right) \#\left(\mathscr{J}_{F_{\alpha}}^{*}(1 \otimes 1)\right)-\Delta\left(\mathscr{D} g_{\alpha}\left(F_{\alpha}\right)\right) .
$$

Moreover, (13) gives

$$
\Delta_{V_{\alpha}}\left(\mathscr{D} g_{\alpha}\left(F_{\alpha}\right)\right)=\Delta\left(\mathscr{D} g_{\alpha}\left(F_{\alpha}\right)\right)-\mathscr{J} \mathscr{D} g_{\alpha}\left(F_{\alpha}\right) \#\left(\mathscr{D} V_{\alpha}\left(F_{\alpha}\right)\right)
$$

Hence, we have

$$
\begin{aligned}
& -\left(\mathscr{J}_{F_{\alpha}}^{*} \mathscr{J}_{F_{\alpha}} \mathscr{D} g_{\alpha}\left(F_{\alpha}\right)\right)+\mathscr{J} \mathscr{D} g_{\alpha}\left(F_{\alpha}\right) \#\left(\mathscr{J}_{F_{\alpha}}^{*}(1 \otimes 1)-\mathscr{D} V_{\alpha}\left(F_{\alpha}\right)\right) \\
& =\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) \mathscr{D} g_{\alpha}\left(F_{\alpha}\right)-\delta_{V_{\alpha}} \mathscr{D} g_{\alpha}\left(F_{\alpha}\right)
\end{aligned}
$$

Moreover (12) and $\partial_{i} \mathscr{D}_{j} V_{\alpha}=\rho\left(\partial_{j} \mathscr{D}_{i} V_{\alpha}\right)$ yield

$$
\sum_{j}\left[\mathscr{D}_{X, \mathscr{D}_{j} g_{\alpha}} \mathscr{D}_{j} V_{\alpha}\right]\left(F_{\alpha}\right)=\mathscr{J} \mathscr{D} V_{\alpha}\left(F_{\alpha}\right) \# \mathscr{D} g_{\alpha}\left(F_{\alpha}\right)
$$

Putting these equalities together gives:

$$
\begin{aligned}
&-\left(\mathscr{J}_{F_{\alpha}}^{*} \mathscr{J}_{F_{\alpha}} \mathscr{D} g_{\alpha}\left(F_{\alpha}\right)\right)+\mathscr{J} \mathscr{D} g_{\alpha}\left(F_{\alpha}\right) \#\left(\mathscr{J}_{F_{\alpha}}^{*}(1 \otimes 1)\right. \\
&\left.-\mathscr{D} V_{\alpha}\left(F_{\alpha}\right)\right)-\mathscr{J} \mathscr{D} V_{\alpha}\left(F_{\alpha}\right) \# \mathscr{D} g_{\alpha}\left(F_{\alpha}\right) \\
&=\left(\Delta_{V_{\alpha}}+\delta_{V_{\alpha}}\right) \mathscr{D} g_{\alpha}\left(F_{\alpha}\right)-\delta_{V_{\alpha}} \mathscr{D} g_{\alpha}\left(F_{\alpha}\right)-\sum_{j}\left[\mathscr{D}_{X, \mathscr{D}_{j} g_{\alpha}} \mathscr{D}_{j} V_{\alpha}\right]\left(F_{\alpha}\right) \\
&=\mathscr{D} W\left(F_{\alpha}\right)-\left[d \mathscr{D} g_{\alpha}\left(E_{F_{\alpha}, D}\right) \cdot\left(\mathscr{J}_{F_{\alpha}}^{*}(1 \otimes 1)-\mathscr{D} V_{\alpha}\left(F_{\alpha}\right)\right)\right]\left(F_{\alpha}\right) .
\end{aligned}
$$

where at the end we have used equation (29) and Lemma B.35.(1) applied to $\mathscr{D} g_{\alpha}$.
Hence, (30) yields

$$
\begin{equation*}
\frac{d}{d \alpha} \Upsilon_{\alpha}=-\mathscr{J} \mathscr{D} g_{\alpha}\left(F_{\alpha}\right) \# \Upsilon_{\alpha}-\left[d \mathscr{D} g_{\alpha}\left(E_{F_{\alpha}, D}\right) \cdot\left(\Upsilon_{\alpha}\right)\right]\left(F_{\alpha}\right) \tag{31}
\end{equation*}
$$

We thus obtain the claimed equation from which we deduce the bound:

$$
\left\|\Upsilon_{\alpha}\right\|_{\infty}:=\max _{i}\left\|\Upsilon_{\alpha}^{i}\right\|_{A} \leq\left\|\Upsilon_{0}\right\|_{\infty}+\int_{0}^{\alpha}\left\|g_{\beta}\right\|_{C_{t r, c}^{0,2}\left(A, A_{R / 3, c o n j}^{n}\right)}\left\|\Upsilon_{\beta}\right\|_{\infty} d \beta
$$

so that Gronwall's Lemma yields the claim.
Recall that $V_{0}=\frac{1}{2} \sum_{i=1}^{n} X_{i}^{2}$. We have to slightly strengthen Assumption 1; this is still satisfied by our examples of quartic potentials.

Assumption 4. Let $V, W \in C_{c}^{3}\left(A, 2 R: B, E_{D}\right)$ be two non-commutative $(c, 2 R)$ h-convex functions satisfying Assumption 1 and satisfying additionally that for any $\alpha \in[0,1]$, there exists a solution $\left(X_{1}^{V+\alpha W}, \ldots, X_{n}^{V+\alpha W}\right) \in A_{R / 4, U l t r a A p p}^{n}$.

Corollary 13. Let $V, W, B, D$ satisfy Assumption 4 and 2 and $V, W \in C_{c}^{6}(A, 2 R$ : $B, D)$. Assume also the pair $\left(c V_{0}, V-c V_{0}\right)$ satisfies Assumption 4. Fix an $X \in$ $A_{R / 4, c o n j}^{n}$ and suppose it follows the free Gibbs law with potential $V$.

Let $F_{\alpha}, 0 \leq \alpha \leq \alpha_{0}$ be the solution constructed in Lemmas 11 and 12. Then:
(i) The law of $F_{\alpha}(X)$ is the free Gibbs law with potential $V_{\alpha}=V+\alpha W$;
(ii) The $W^{*}$-algebras $W^{*}\left(F_{\alpha}(X), B\right)$ are equal for all $\alpha \in\left[0, \alpha_{0}\right]$.

In particular, for any $\alpha \in[0,1]$, the von Neumann algebras generated by $B$ and generators of the free Gibbs law with potential $V_{\alpha}=V+\alpha W$ are isomorphic.

Proof. We first check that Assumption 3 is satisfied under our assumptions. We first start with the case $V=c V_{0}$, in which case Assumption 3 is satisfied thanks to Assumption 2 and Proposition A.24.(2). Then in building the transport map for the pair $\left(c V_{0}, V-c V_{0}\right)$ the same Assumption 3 is satisfied for $X \in A_{R / 4, c o n j}^{n}$.

By the previous Lemma 12 , we find that $\Upsilon_{\alpha}=0$, which means that $\mathscr{J}_{F_{\alpha}}(1 \otimes 1)=$ $\mathscr{D} V_{\alpha}$ for $\alpha \in\left[0, \alpha_{0}\right]$. Since $V_{\alpha}$ is by assumption $(c, 2 R)$-convex and $\left\|F_{\alpha}\right\|<R / 3$ it follows that the law of $F_{\alpha}$ is the free Gibbs law with potential $V_{\alpha}$. This proves (i).

To see part (ii) fix $\alpha_{1} \in\left[0, \alpha_{0}\right]$. Let $\hat{V}_{\alpha}=V_{\alpha_{1}}-\alpha W$, with $\alpha \in\left[0, \alpha_{1}\right]$, and consider the same ODE as in Lemma 11, and call $\hat{F}_{\alpha}$ the solution. $V_{\alpha}$ replaced by $\hat{V}_{\alpha}$. Note that $F_{\alpha_{1}}(X) \in A_{R / 4, \text { UltraApp }}^{n}$ by Assumption 4. It is not hard to see that $\hat{F}_{\alpha}\left(F_{\alpha_{1}}(X)\right), F_{\alpha_{1}-\alpha}(X)$ are solutions to the same ODE (except that $W$ is replaced by $-W$, due to time reversal), and is thus the unique solution. Thus by what we proved, $W^{*}\left(\hat{F}_{\alpha}\left(F_{\alpha_{1}}(X)\right), B\right) \subset W^{*}\left(F_{\alpha_{1}}(X), B\right)$, which shows the reverse inclusion and thus equality $W^{*}\left(F_{\alpha}(X), B\right)=W^{*}(X, B)$, for $\alpha \in\left[0, \alpha_{0}\right]$.

Let us prove the last point of the Corollary. We have just checked the case $\alpha \in\left[0, \alpha_{0}\right]$. Moreover, $\left(V_{\alpha_{0}},\left(1-\alpha_{0}\right) W\right)$ satisfies the same assumption as $(V, W)$ with the same constants $(c, R)$. We can therefore perform the previous construction of a function $F_{\alpha}$ with $(V, W)$ replaced by $\left(V_{\alpha_{0}},\left(1-\alpha_{0}\right) W\right)$. This can be done until a parameter $\alpha_{0}^{\prime}$ which can be chosen to be equal to $\alpha_{0}$ as the constants $(c, R)$ are the same and the semi-groups under consideration are the same. Note also that Assumption 4 enables us to verify that $\left\|F_{\alpha_{0}}(X)\right\| \leq R / 4$ and thus $F_{\alpha_{0}}(X)$ satisfies the same assumption as $X$. Applying (i),(ii) in that case concludes to the isomorphism of $W^{*}\left(X^{V+\alpha W}, B\right)$ for $\alpha \in\left[\alpha_{0}, \alpha_{0}+\alpha_{0}\left(1-\alpha_{0}\right)\right]$ if $X^{V+\alpha W}$ are the unique variables with conjugate variables $\mathscr{D}_{i}(V+\alpha W)$.

Inductively, one concludes to the isomorphism for any $\alpha \in[0,1[$. To complete the proof, it suffices to note that for $\epsilon$ small enough, $V,(1+\epsilon) W$ satisfy the same assumptions (a priori with a different convexity constant and replacing $R / 4<R / 3$ by any larger value).

## A. Cyclic Haagerup Tensor Products

Let $M$ be a finite von Neumann algebra and $D \subset M$ be a von Neumann subal$\stackrel{\text { eh }}{\otimes} n$ gebra. Our goal is to define a notion of $n$-fold cyclic tensor product $M^{\otimes, D^{D}}$ which will be a certain subspace of the Haagerup tensor product $M^{\substack{\text { eh } \\ \otimes \\ D}}$. We start by considering the case $n=2$, and then use amalgamated free products to build the more general cyclic tensor powers.

The inspiration for the construction comes from subfactor theory. Indeed, if $M_{0} \subset M_{1}$ is a finite-index inclusion of $\mathrm{II}_{1}$ factors and if $M_{k}$ denotes the $k$-th step in the iterated Jones basic construction, then (see e.g. [JSS, Prop 4.4.1(ii)]) $L^{2}\left(M_{k}\right)$ are precisely the tensor powers of $L^{2}\left(M_{1}\right)$ regarded as an $M_{0}$ Hilbert bimodule: $L^{2}\left(M_{k}\right)=L^{2}\left(M_{1}\right)^{\otimes M_{0} k}$. Moreover, the higher relative commutants $M_{0}^{\prime} \cap M_{k}$ are precisely the cyclic tensor powers of $M_{1}$. These ideas have been extended to the infinite-index case $[\mathbf{B}, \mathbf{P e}, \mathbf{P e 1 3}]$. In particular, the notion of Burns rotation will be useful for us to get a certain traciality property.

## A.1. Preliminaries.

A.1.1. Background and basic results on tensor powers of Hilbert bimodules. Let $D$ be a $I I_{1}$-factor and let ${ }_{D} H_{D}$ be a $D$-Hilbert bimodule, i.e., a Hilbert space carrying a pair of commuting normal actions of $D$. Recall that a vector $\xi \in H$ is called left (resp. right) bounded if the left (resp. right) action of $M$ on $\xi$ extends to an action of $L^{2}(M)$ on $\xi$. There is always a $D$-basis $\{\alpha\}$ of vectors for $H$ which are both right and left bounded [Po86]. We write $H_{L^{2}(D)}$ the set of right bounded vectors and ${ }_{L^{2}(D)} H$ the set of left bounded vectors. We call $B_{H}={ }_{L^{2}(D)} H \cap H_{L^{2}(D)}$ the set of vectors which are both left and right bounded.

Let us denote by $H^{\otimes_{D} n}$ the $n$-fold Hilbert module relative tensor product (for convenience, we set $H^{\otimes_{D} 0}=L^{2}(D)$ ). Denote by $P_{H}^{n}=D^{\prime} \cap H^{\otimes_{D} n}$ the set of central vectors. Following [Pe13], we denote by $\left\{\alpha^{n}\right\}$ the basis for $H^{\otimes_{D} n}$ of tensors of elements of $\{\alpha\}$. Similarly, fix $D$-bases $\{\beta\},\left\{\beta^{n}\right\}$ for $H_{D}$ and $\left(H^{\otimes_{D} n}\right)_{D}$, respectively.

Let

$$
C_{n, H}=D^{o p \prime} \cap B\left(H^{\otimes_{D} n}\right)
$$

and endow it with the canonical trace

$$
T r_{n}=\sum_{\beta^{n}}\left\langle\cdot \beta^{n}, \beta^{n}\right\rangle
$$

An example of this is the Jones basic construction, which we denote by $\left\langle M, e_{D}\right\rangle$ for $D \subset M$. Then $\left\langle M, e_{D}\right\rangle=D^{o p \prime} \cap B\left(L^{2}(M)\right)=C_{1, L^{2}(M)}$. Similarly, let

$$
C_{n, H}^{o p}=D^{\prime} \cap B\left(H^{\otimes_{D} n}\right)
$$

with canonical trace

$$
T r_{n}^{o p}=\sum_{\alpha^{n}}\left\langle\cdot \alpha^{n}, \alpha^{n}\right\rangle
$$

Finally, define the centralizer algebras

$$
Q_{n, H}=C_{n, H} \cap C_{n, H}^{o p} .
$$

We recall the following definitions from [Pe13]:
Definition A.14. (i) A Hilbert bimodule $H$ on a factor $D$ is said to be extremal if $T r_{1}=T r_{1}^{o p}$ on the positive cone $Q_{1, H}^{+}$.
(ii) A Burns rotation is a map $\rho: P_{H}^{n} \rightarrow P_{H}^{n}$ such that for all $\zeta \in P_{H}^{n}, b_{1}, \ldots, b_{n} \in$ $B_{H}$, we have:

$$
\left\langle\rho(\zeta), b_{1} \otimes \ldots \otimes b_{n}\right\rangle=\left\langle\zeta, b_{2} \otimes \ldots \otimes b_{n} \otimes b_{1}\right\rangle
$$

Examples are given in [Pe13, section 5.2]. The easiest example is when $H$ has a two-sided basis [Pe13, Rmk 4.5].

Theorem A.15. [Pe13, Theorems 4.7, 4.20]If $H$ is extremal, $H^{\otimes_{D} n}$ is also extremal and for all n, there exists a Burns rotation $\rho$ on $P_{H}^{n}$ which is a unitary map.

There is also a partial converse $[\mathbf{P e 1 3}$, Th 1.4], although it is not needed for our purposes.
A.1.2. Haagerup tensor products and the basic construction. With these preliminaries recalled, we now turn to the definition of the cyclic Haagerup tensor product. We start by a well-known technical result concerning the Jones basic construction.

If $A$ is an operator space, we write $A^{*}$ for its dual as an operator space $[\mathbf{P}]$. When $A$ is a $D-D$ bimodule, we write $A^{\natural}$ for the dual operator $D^{\prime}-D^{\prime}$ bimodule in the sense of Magajna [M05]. We will also denote by $A^{\natural D n o r m}$ the normal dual defined when $A$ is itself a tensor product over $D$ in [M05, Th 3.2]. While we will not recall the general definition of the normal dual here, we will mention that in the case that $A$ is itself a tensor product over $D$ (and therefore its dual can be viewed as the space of certain linear maps), the normal dual corresponds to maps that satisfy a normality condition on basic tensors. In the case that $D=\mathbb{C}$, the bimodule dual is the same as the operator space dual $A^{*}$.

Let $D \subset M$ be finite von Neumann algebras, let $e_{D}$ be the Jones projection onto $D$, and denote by $\left\langle M, e_{D}\right\rangle$ the basic construction for $D \subset M$. Let

$$
A\left(M, e_{D}\right)=\operatorname{Span}\left\{x e_{D} y: x \in L^{2}(M)_{L^{2}(D)}, y \in L_{L^{2}(D)} L^{2}(M)\right\}
$$

Denote by $\mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right)$ the compact ideal space (cf. [Po02, section 1.3.3]). Let $E_{D^{\prime}}: \mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right) \rightarrow D^{\prime} \cap \mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right)$ be the conditional expectation constructed in [Po02, Prop 1.3.2].
Lemma A.16. With the above notations, $A\left(M, e_{D}\right)$ is weak-* dense in $\left\langle M, e_{D}\right\rangle$, dense in $L^{2}\left(\left\langle M, e_{D}\right\rangle\right), \mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right)$ as well as $L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$.

The following hold isometrically:
$L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \simeq L^{2}(M)^{*} \otimes_{h D^{o p}} L^{2}(M)=\mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right)^{* D n o r m} \subset \mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right)^{*}$.
The restriction of $E_{D^{\prime}}$ to a normal projection on $\mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right) \cap L^{2}(M) \otimes_{D}$ $L^{2}(M)$ induces a cross-section to the quotient map $\mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right) \rightarrow$ $\mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right) / \overline{\left[D, \mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right)\right]}$. The Dixmier conditional expectation $E_{D^{\prime}}:\left\langle M, e_{D}\right\rangle \rightarrow D^{\prime} \cap\left\langle M, e_{D}\right\rangle$ is an extension of $E_{D^{\prime}}$.

The map $E_{D^{\prime}}$ is pointwise normal in $D$ and thus its adjoint $E_{D^{\prime}}^{*}$ induces a projection $E_{D^{\prime}}^{*}: L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \rightarrow D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ agreeing with the usual projection on $L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \cap L^{2}(M) \otimes_{D} L^{2}(M)$, and giving an isomorphism

$$
D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \simeq L^{1}\left(\left\langle M, e_{D}\right\rangle\right) / \overline{\left[D, L^{1}\left(\left\langle M, e_{D}\right\rangle\right)\right]}
$$

Proof. The identification

$$
L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \simeq L^{2}(M)^{*} \otimes_{h D^{o p}} L^{2}(M)=\mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right)^{* D n o r m}
$$

comes from the fact that both spaces are preduals of the same von Neumann algebra as follows from the computation of their duals in [M05, Corollary 3.3], the computation of $\mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right)$ as Haagerup tensor product below and the identification with extended Haagerup products [M05, Rmk 2.18]:

$$
L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \simeq L^{2}(M)^{*} \otimes_{h D^{o p}} L^{2}(M) \simeq L^{2}(M)^{*} \underset{D^{o p}}{\stackrel{e h}{\otimes}} L^{2}(M)
$$

From [M05, Th 3.2, Ex 3.15] we have the isomorphism

$$
\left[\mathbb{C}\left(M_{M}^{2}(M)_{L^{2}(D)}\right)_{D} \otimes_{h D D}\left(L^{2}(D) L^{2}(M)_{M}\right)_{\mathbb{C}}\right]^{* D n o r m} \simeq L^{1}\left(\left\langle M, e_{D}\right\rangle\right)
$$

Note that here the operator space structure ${ }_{D}\left(L^{2}(D) L^{2}(M)_{M}\right)_{\mathbb{C}}$ is the one of the indicated Hilbert module structure, not the one as a module over $D^{o p}$. It remains to check

$$
\left.\left.\left.\begin{array}{rl}
\mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right) & \simeq\left[\mathbb{C}\left({ }_{M} L^{2}(M)_{L^{2}(D)}\right)_{D} \otimes_{h D}\left(L_{L^{2}(D)} L^{2}(M)_{M}\right)_{\mathbb{C}}\right] \\
& \subset\left[\mathbb { C } ( { } _ { M } L ^ { 2 } ( M ) _ { L ^ { 2 } ( D ) } ) _ { D } \stackrel { \mathrm { eh } } { D } _ { \otimes } ^ { \otimes _ { D } } \left(L^{2}(D)\right.\right.
\end{array} L^{2}(M)_{M}\right)_{\mathbb{C}}\right] \simeq\left\langle M, e_{D}\right\rangle\right)
$$

but the last inclusion comes again from [M05, Th 3.2, Ex 3.15]. In this way we identify the compact ideal space with the norm closure of basic tensors in the extended Haagerup tensor product. This norm closure is exactly the Haagerup tensor product and thus we deduce the first isomorphism.

On the dense space $\mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right) \cap L^{2}(M) \otimes_{D} L^{2}(M), E_{D^{\prime}}$ vanishes on $[D, U]$ for any $U$. Since $E_{D^{\prime}}(U)$ is a limit of convex combinations of $u^{*} U u=U+\left[u^{*} U, u\right], u \in$ $D, E_{D^{\prime}}(U)$ has the same image as $U$ in the quotient $\mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right) / \overline{\left[D, \mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right)\right]}$. This gives the claimed isomorphism between the image of $E_{D}, D^{\prime} \cap \mathcal{I}_{0}\left(\left\langle M, e_{D}\right\rangle\right)$, and the quotient, as well as the identification with the Dixmier conditional expectation.

The key part of our Lemma is to check $D$-normality of $d \mapsto \operatorname{Tr}\left(E_{D^{\prime}}^{*}(V) \xi d e_{D} \eta\right)$, $V \in L^{1}\left(\left\langle M, e_{D}\right\rangle\right), \xi \in L^{2}(M)_{L^{2}(D)}, \eta \in L^{2}(D) L^{2}(M)$. Since $E_{D^{\prime}}$ is bounded, one
may assume $V \in L^{2}(M) \otimes_{D} L^{2}(M)$ in which case obviously $E_{D^{\prime}}^{*}(V)=E_{D^{\prime}}(V)$. This one is again close to $\sum \lambda_{u} u V u^{*}$ so that since $d \mapsto \operatorname{Tr}\left(\sum \lambda_{u} u V u^{*} \xi d e_{D} \eta\right)$, is normal, one gets our result. The second quotient statement is analogous.
The reader should note that the identification $L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \simeq L^{2}(M)^{*} \otimes_{h D^{o p}} L^{2}(M)$ is given on basic tensors by:

$$
\begin{equation*}
x e_{D} y \mapsto y \otimes_{D^{o p}} x \tag{32}
\end{equation*}
$$

This will be the key to various flips appearing naturally later.
A.2. The cyclic Haagerup tensor product, case $n=2$. Recall that the spaces $L^{p}\left(\left\langle M, e_{D}\right\rangle\right)$ are made in compatible couples in the sense of interpolation theory $[\mathbf{P}]$. We can see them as the inductive limit of $L^{p}\left(q\left\langle M, e_{D}\right\rangle q\right)$ for $q$ finite projections. Thus these spaces are realized as an interpolation pair as a subspace of the topological direct sum $\oplus_{q \in P_{f}\left(\left\langle M, e_{D}\right\rangle\right)} L^{1}\left(q\left\langle M, e_{D}\right\rangle q\right)$.

We refer to [Dab15, Th 2] for a literature overview of the main algebraic operations available on module Haagerup tensor products (see also the original references [BS92, B97a, B97b, EK, ER03, M95, M97, M05, SS98] and books [BLM, ER00, P]). We will use them extensively. We single out several operations. The first is the map * (see Section 2) which is given on basic tensors by $(a \otimes b)^{\star}=b^{*} \otimes a^{*}$. Next, for a basic tensor $X=a \otimes b \in M \stackrel{\text { eh }}{\otimes} M$ and a basic product $U=x e_{D} y \in\left\langle M, e_{D}\right\rangle$ we write:

$$
U \# X=E_{D^{\prime}}\left(b x e_{D} y a\right), \quad \text { (inner action) }
$$

and if $U \in D^{\prime} \cap\left\langle M, e_{D}\right\rangle$ :

$$
X \# U=a x e_{D} y b, \quad \text { (outer action) }
$$

With these notations, we have the following statements, which we group into three Theorems for convenience of presentation.
Theorem A.17. Let $D \subset(M, \tau)$ finite von Neumann algebras.
(1a) The outer action $(X, U) \mapsto X \# U$ extends to all $X \in M \stackrel{\text { eh }}{\otimes} M$ and $U \in$ $D^{\prime} \cap\left\langle M, e_{D}\right\rangle \subset D^{\prime} \cap B\left(L^{2}(M)\right)$, taking values in $\left\langle M, e_{D}\right\rangle$. The inner action $(X, V) \mapsto V \# X$ extends to all $X \in M \stackrel{\stackrel{\text { eh }}{\otimes}}{D} M$ and $V \in L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ with values in $D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$.
(1b) If in addition $X \in D^{\prime} \cap M \stackrel{\text { eh }}{\otimes} M, U \in D^{\prime} \cap\left\langle M, e_{D}\right\rangle$, then $X \# U \in D^{\prime} \cap\left\langle M, e_{D}\right\rangle$.
(1c) The inner and outer multiplication actions give rise to inclusions $\sigma_{1}, \sigma_{2}$,

$$
\begin{aligned}
\sigma_{i}: D^{\prime} \cap M \stackrel{\mathrm{eh}}{\otimes} M & \\
\qquad & \\
& B\left(D^{\prime} \cap\left\langle M, e_{D}\right\rangle \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right), D^{\prime} \cap\left(\left\langle M, e_{D}\right\rangle+L^{1}\left(\left\langle M, e_{D}\right\rangle\right)\right) .\right.
\end{aligned}
$$

Proof. The $M^{o p}$-modularity of the action on $D^{\prime} \cap B\left(L^{2}(M)\right)$ whose definition is recalled in [Dab15] Theorem 2.(4) insures stability of $\left\langle M, e_{D}\right\rangle=\left(D^{o p}\right)^{\prime} \cap B\left(L^{2}(M)\right)$ under the outer action.

Let us give an explicit description of the predual map giving the inner action on $D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$. From the canonical map $M \otimes_{h} L^{2}(M)=M \otimes_{e h} L^{2}(M) \rightarrow L^{2}(M)$
and its row analogue $L^{2}(M)^{*} \otimes_{e h} M \rightarrow L^{2}(M)^{*}$, (see [BLM, Prop 3.1.7]), one gets a map from

$$
L^{2}(M)^{*} \otimes_{h}(M \stackrel{\mathrm{D}}{\stackrel{\mathrm{eh}}{\otimes}} M) \otimes_{h} L^{2}(M) \simeq\left(L^{2}(M)^{*} \otimes_{e h} M\right) \otimes_{e h D}\left(M \otimes_{e h} L^{2}(M)\right)
$$

into $L^{2}(M)^{*} \otimes_{e h D} L^{2}(M)$, inducing in particular a map

$$
m: L^{2}(M)^{*} \otimes_{h} L^{2}(M) \times M \stackrel{\mathrm{eh}}{\otimes} M \rightarrow L^{2}(M)^{*} \otimes_{e h D} L^{2}(M)=L^{2}(M)^{*} \otimes_{h D} L^{2}(M)
$$

which is our inner multiplication. Composing with $E_{D^{\prime}}$ one induces a map

$$
E_{D^{\prime}} \circ m: L^{2}(M)^{*} \otimes_{h D^{o p}} L^{2}(M) \times M \stackrel{\mathrm{eh}}{\otimes} M \rightarrow D^{\prime} \cap L^{2}(M)^{*} \otimes_{e h D} L^{2}(M)
$$

The latter is isomorphic to $D^{\prime} \cap L^{2}(M)^{*} \otimes_{e h D^{o p}} L^{2}(M)$, the last inclusion following for instance from the identification of this commutant with a quotient or because $E_{D^{\prime}}(d U-U d)=0$. Note that the last isomorphism sends $a \otimes_{D} b \in D^{\prime} \cap L^{2}(M)^{*} \otimes_{e h D}$ $L^{2}(M)$ to $a \otimes_{D^{o p}} b$ and thus on basic tensors

$$
E_{D^{\prime}} \circ m\left(y \otimes_{D^{o p}} x, a \otimes_{D} b\right)=E_{D^{\prime}}\left(y a \otimes_{D^{o p}} b x\right)
$$

which is identified with $E_{D^{\prime}}\left(b x e_{D} y a\right)$ in $D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ via (32) and coincides with our inner action.

For $X \in D^{\prime} \cap(M \underset{D}{\stackrel{\mathrm{eh}}{\otimes}} M), U \in D^{\prime} \cap\left\langle M, e_{D}\right\rangle, X \# U \in D^{\prime} \cap\left\langle M, e_{D}\right\rangle$. This proves (1b).

We next claim that for $V \in L^{1}\left(\left\langle M, e_{D}\right\rangle\right), X \in(M \stackrel{\stackrel{\mathrm{eh}}{\otimes}}{\otimes} M), U \in D^{\prime} \cap\left\langle M, e_{D}\right\rangle$ :

$$
\begin{equation*}
\operatorname{Tr}(U[V \# X])=\operatorname{Tr}([X \# U] V) \tag{33}
\end{equation*}
$$

To show this, it suffices to take $V \in A$ by density. We can also assume $X$ is a finite sum. Indeed, if $X=x \otimes_{D} y$ a standard decomposition for $X$ [M05, (2.4),(2.5)] the ultrastrong convergence of finite families $x_{F}^{*} \rightarrow x^{*}, y_{F} \rightarrow y$ implies if $X_{F}=x_{F} \otimes_{D} y_{F} X_{F} \# U \rightarrow X \# U$ ultraweakly. Likewise if $V=\xi \otimes_{D^{o p}} \eta$ we have the convergence

Now for the remaining case $V=\xi \otimes_{D^{o p}} \eta, X=x \otimes_{D} y$ (without matrix tensor products), we note that the image of $V$ in the identification with $L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ is $\eta e_{D} \xi$, as explained in (32) so that $[V \# X]=E_{D^{\prime}}\left(\left[y \eta e_{D} \xi x\right]\right)$ and

$$
\operatorname{Tr}(U[V \# X])=\operatorname{Tr}\left(U\left[y \eta e_{D} \xi x\right]\right)=\operatorname{Tr}([x U y] V)=\operatorname{Tr}([X \# U] V)
$$

We have also shown the existence of an extension for the definition of our inner action, namely that for $V \in D^{\prime} \cap\left\langle M, e_{D}\right\rangle \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$, and $x, y \in M$,

$$
\begin{equation*}
\left[V \#\left(x \otimes_{D} y\right)\right]=E_{D^{\prime}}\left(\left[y \otimes_{D} x\right] \# V\right) \tag{34}
\end{equation*}
$$

We now prove (1c); all we need to show is that $\sigma_{1}(X): U \rightarrow X \# U, \sigma_{2}(X): V \rightarrow$ $V \# X$ give inclusions. Note that $\sigma_{1}(\cdot)\left(e_{D}\right)$ is the canonical inclusion $M \stackrel{\text { eh }}{\otimes} M \rightarrow$ $\left\langle M, e_{D}\right\rangle=L^{2}(M)_{L^{2}(D)} \stackrel{\text { eh }}{\stackrel{\otimes}{D} L^{2}(D)} L^{2}(M)$ given by the theory of extended Haagerup product (see e.g. [Dab15, Prop 14]), so that $\sigma_{1}$ is injective.

By the definition of $\sigma_{2}, \sigma_{2}(X)\left(e_{D}\right)=E_{D^{\prime}}(i(X))$ with $i: M \stackrel{\text { eh }}{\otimes} M \rightarrow L^{2}(M)^{*} \stackrel{\text { eh }}{\stackrel{\otimes}{D}}$ $L^{2}(M)$ since it equals $i(X)$ for $X \in D^{\prime} \cap M \stackrel{\text { eh }}{\otimes} M$; this gives injectivity of $\sigma_{2}$.

Definition A.18. Denote by $M^{\substack{\mathrm{eh} \\ \mathrm{D}, c}}$. the intersection space of the images $\sigma_{i}\left(D^{\prime} \cap\right.$ $M \stackrel{\mathrm{D}}{\stackrel{\mathrm{eh}}{\otimes}} M), i=1,2$, in the sense of interpolation theory. This space is called the cyclic extended Haagerup tensor square of $M$.

Theorem A.19. We keep the notations and assumptions of Theorem $A .17$ and Definition A. 18.
(1d) The restriction of the map * defined in [Dab15] Theorem 2.(4) to $M^{\stackrel{\mathrm{eh}}{\otimes, c} 2}$ and the map $\sigma=\sigma_{2} \circ \sigma_{1}^{-1}$ define two commuting isometric involutions on $M^{\frac{\text { eh }}{\otimes, c} 2}$.
(1e) The involution $U \mapsto U^{*}:=(\sigma(U))^{\star}$ and the product induced on $M^{\stackrel{\text { eh }}{\otimes, c c} 2}$ via $\sigma_{1}$

(1f) For each $X \in M^{\substack{\mathrm{eh} \\ \otimes, c}}, \sigma_{1}^{-1}(X) \# \cdot: D^{\prime} \cap\left\langle M, e_{D}\right\rangle \rightarrow D^{\prime} \cap\left\langle M, e_{D}\right\rangle$ and $\cdot \# \sigma_{2}^{-1}(X)$ : $D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \rightarrow D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ interpolate to give an action of $X \in$ $M^{\stackrel{\mathrm{eh}}{\otimes, c} 2}$ on $D^{\prime} \cap L^{2}(M) \otimes_{D} L^{2}(M)$.
(1g) There is also an outer action denoted $X \#_{L^{1}}$. of $M^{\substack{\text { eh } \\ D, c}}$ on $L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ leaving $D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ globally invariant and commuting with the inner action.
(2a) The map $Y \in(M \stackrel{\text { eh }}{\otimes} M) \mapsto Y \# e_{D} \in\left\langle M, e_{D}\right\rangle \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ gives the canonical weak-* continuous inclusion of $M \stackrel{\text { eh }}{\otimes} M$ into $L^{2}\left(\left\langle M, e_{D}\right\rangle\right) \simeq L^{2}(M) \otimes_{D} L^{2}(M)$ (cf. [Dab15, Proposition 14]).
(2b) For any $Y, Z \in D^{\prime} \cap M \stackrel{\text { eh }}{\otimes} M$ the map $X \mapsto\left\langle Z \# e_{D}, X \# Y \# e_{D}\right\rangle$ is weak-* continuous on bounded sets of $M \stackrel{\mathrm{eh}}{\otimes} M$.
(2c) $M^{\stackrel{\mathrm{eh}}{\otimes, c} 2} \# e_{D}$ is dense in $D^{\prime} \cap L^{2}(M) \otimes_{D} L^{2}(M)$ and $M^{\stackrel{\mathrm{eh}}{\otimes, c} 2}$ weak-* dense in $D^{\prime} \cap M^{\stackrel{\text { eh }}{\otimes 2}}{ }^{2}$.
(2d) The multiplication map $(U, V) \mapsto U \# V$ is separately weak-* continuous on bounded sets in the second variable as a map

$$
\left(M \stackrel{\text { eh }}{\otimes}{ }_{D} M\right) \times\left(D^{\prime} \cap M \stackrel{\text { eh }}{\otimes} M\right) \rightarrow\left(M \stackrel{\text { eh }}{\otimes}{ }_{D}^{\otimes} M\right),
$$

and on each variable when restricted to:

Proof. Note that the intersection space $M^{\stackrel{\text { eh }}{\otimes}, c^{D}}$ is thus well-defined because of (1c).
We start by proving (1d). If $X \in M^{\substack{\text { eh } \\ D, c}}$, let $X^{\prime}=\sigma(X) \in \sigma_{2}\left(D^{\prime} \cap M^{\stackrel{\mathrm{eh}}{\otimes 2}} \stackrel{D^{\otimes}}{D}\right)$ so if we show $X^{\prime}=\sigma^{\prime}(X):=\sigma_{1}\left(\sigma_{2}^{-1}(X)\right)$ we will have shown $\sigma$ leaves $M^{\stackrel{\text { eh }}{\otimes, c} 2}$ globally invariant. The adjoint relation (33) gives for $U, V \in D^{\prime} \cap\left\langle M, e_{D}\right\rangle \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$

$$
\begin{gathered}
\operatorname{Tr}(X(U) V)=\operatorname{Tr}\left(\left[\sigma_{1}^{-1}(X) \# U\right] V\right)=\operatorname{Tr}\left(U\left[V \# \sigma_{1}^{-1}(X)\right]\right)=\operatorname{Tr}(U[\sigma(X)(V)]) \\
\operatorname{Tr}(X(U) V)=\operatorname{Tr}\left(\left[U \# \sigma_{2}^{-1}(X)\right] V\right)=\operatorname{Tr}\left(U\left[\sigma_{2}^{-1}(X) \#(V)\right]\right)=\operatorname{Tr}\left(U\left[\sigma^{\prime}(X)(V)\right]\right)
\end{gathered}
$$

Since $U$ and $V$ are arbitrary in dense spaces this shows the desired relation and as a consequence that $\sigma$ is involutive.

With the same notation and using the definitions, $\sigma=\sigma^{\prime}$ and the adjoint relation (33) several times, we have:

$$
\begin{aligned}
\operatorname{Tr}\left(\left[X^{\star}(U)\right] V\right) & :=\operatorname{Tr}\left(\left[\sigma_{1}^{-1}(X)^{\star} \# U\right] V\right) \\
& =\operatorname{Tr}\left(\left[\sigma_{1}^{-1}(X) \# U^{*}\right]^{*} V\right)=\overline{\operatorname{Tr}\left(\left[\sigma_{1}^{-1}(X) \# U^{*}\right] V^{*}\right)} \\
& =\overline{\operatorname{Tr}\left(U^{*}\left[V^{*} \#\left(\sigma_{1}^{-1}(X)\right)\right]\right)}=\operatorname{Tr}\left(U\left[V^{*} \#\left(\sigma_{1}^{-1}(X)\right)\right]^{*}\right) \\
& \left.=\operatorname{Tr}\left(U\left[\sigma(X)\left(V^{*}\right)\right]^{*}\right)=\operatorname{Tr}\left(U\left[\sigma_{2}^{-1}(X) \# V^{*}\right)\right]^{*}\right) \\
& \left.\left.\left.=\operatorname{Tr}\left(U\left[\sigma_{2}^{-1}(X)^{\star} \# V\right)\right]\right)=\operatorname{Tr}\left(\left[U \# \sigma_{2}^{-1}(X)^{\star}\right] V\right)\right]\right)
\end{aligned}
$$

This shows both the two possible inductions of * coincide and stability of $M^{\substack{\mathrm{eh} \\ \mathrm{D}, \mathrm{c}}} \mathrm{a}^{2}$ by ${ }^{\star}$. The commutation with $\sigma$ also follows since we showed $\sigma_{2}^{-1}(X)^{\star}=\sigma_{2}^{-1}\left(X^{\star}\right)$, $\sigma_{1}^{-1}(X)^{\star}=\sigma_{1}^{-1}\left(X^{\star}\right)$, thus $\sigma\left(X^{\star}\right)=\sigma_{1}\left(\sigma_{2}^{-1}(X)^{\star}\right)=\sigma_{1}\left(\sigma_{1}^{-1}(\sigma(X))^{\star}\right)=\sigma(X)^{\star}$.

To prove (1e), it remains to check the composition and the adjunction $*$ give the expected Banach algebra structure.

We can reason similarly using our formula (33) and $\sigma=\sigma^{\prime}$ to check closure under the product:

$$
\begin{aligned}
\operatorname{Tr}([(X Y)(U)] V) & :=\operatorname{Tr}\left(\left[\sigma_{1}^{-1}(X) \sigma_{1}^{-1}(Y) \# U\right] V\right) \\
& =\operatorname{Tr}\left(\left[\sigma_{1}^{-1}(Y) \# U\right]\left[V \# \sigma_{1}^{-1}(X)\right]\right)=\operatorname{Tr}\left(U\left[\sigma(X)(V) \# \sigma_{1}^{-1}(Y)\right]\right) \\
& =\operatorname{Tr}(U[\sigma(Y)(\sigma(X)(V))]) \\
& =\operatorname{Tr}\left(U\left[\sigma_{2}^{-1}(Y) \#\left(\sigma_{2}^{-1}(X) \# V\right)\right]=\operatorname{Tr}\left(\left[U \# \sigma_{2}^{-1}(Y) \sigma_{2}^{-1}(X)\right] V\right)\right.
\end{aligned}
$$

The middle relation then also shows $\sigma(X Y)=\sigma(Y) \sigma(X)$. Similarly, $(U V)^{\star}=$ $(U)^{\star}(V)^{\star}$ which gives the only missing relation between * and product to get an involutive Banach algebra.

We next prove (1f). Since commutants have conditional expectations on them $D^{\prime} \cap\left(L^{2}\left(\left\langle M, e_{D}\right\rangle\right)\right)$ is indeed an interpolation of commutants (see e.g. [P, Prop 2.7.6]). For $X \in M^{\stackrel{\mathrm{eh}}{\otimes, c} 2}$, the very definition of $M^{\stackrel{\mathrm{eh}}{\otimes, c} 2}$ give the compatibility for interpolation of the pair of maps $\sigma_{1}^{-1}(X) \# \cdot: D^{\prime} \cap\left\langle M, e_{D}\right\rangle \rightarrow D^{\prime} \cap\left\langle M, e_{D}\right\rangle$ and $\cdot \# \sigma_{2}^{-1}(X): D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \rightarrow D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$. This gives the action on $D^{\prime} \cap L^{2}(M) \otimes_{D} L^{2}(M)$.

We now turn to $(1 \mathrm{~g})$. Because $L^{2}(M)^{*} \otimes_{h} L^{2}(M)=L^{2}(M)^{*} \otimes_{e h} L^{2}(M) \supset M \otimes_{e h}$ $M$ (obviously weak-* continuous injection), one can extend the projection $E_{D^{\prime}}$ from $M \otimes_{e h} M \rightarrow D^{\prime} \cap M \otimes_{e h} M$ to a map $L^{2}(M)^{*} \otimes_{h} L^{2}(M) \rightarrow D^{\prime} \cap L^{2}(M)^{*} \otimes_{h} L^{2}(M)$.

Indeed, by construction, the projection $E_{D^{\prime}}(U)$ is built as a weak-* limit of convex combinations $\sum \lambda_{u} u U u^{*}$ converging thanks to the embedding $M \otimes_{e h}$ $M \subset L^{2}(M) \otimes L^{2}(M)$. Moreover, we have $\left\|\sum \lambda_{u} u U u^{*}\right\|_{L^{2}(M)^{*} \otimes_{h} L^{2}(M)} \leq$ $\|U\|_{L^{2}(M)^{*} \otimes_{h} L^{2}(M)}$. Because the injection is weak-* continuous, one also gets weak* convergence of the convex combination in $L^{2}(M)^{*} \otimes_{h} L^{2}(M)$ and thus, for any $U \in M \otimes_{e h} M$,

$$
\left\|E_{D^{\prime}}(U)\right\|_{L^{2}(M)^{*} \otimes_{h} L^{2}(M)} \leq\|U\|_{L^{2}(M)^{*} \otimes_{h} L^{2}(M)}
$$

By density, $E_{D^{\prime}}$ extends to a bounded map on $L^{2}(M)^{*} \otimes_{h} L^{2}(M)$ which obviously induces a map $L^{2}(M)^{*} \otimes_{h D^{o p}} L^{2}(M) \rightarrow D^{\prime} \cap L^{2}(M)^{*} \otimes_{h} L^{2}(M)$, a cross-section to the quotient map (as seen first for $U \in M \otimes_{e h} M$ by the weak-* limit above).

Now take $U \in L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \simeq L^{2}(M)^{*} \otimes_{h D^{o p}} L^{2}(M), X \in M^{\substack{\text { eh } \\ D, c}}$ write $\sigma_{2}^{-1}(X)=$ $y \otimes_{D} x$, a canonical decomposition with $y \in M_{1, I}(M), x \in M_{I, 1}(M)$ and take $U^{\prime}=E_{D^{\prime}}(U)=\sum_{j} u_{j} \otimes v_{j} \in D^{\prime} \cap L^{2}(M)^{*} \otimes_{h} L^{2}(M)$ sent to $U$ by the quotient map $\pi: L^{2}(M)^{*} \otimes_{h} L^{2}(M) \rightarrow L^{2}(M)^{*} \otimes_{h D^{o p}} L^{2}(M)$.

Then $X \#_{L^{1}} U:=\sum_{i, j} \pi\left(x_{i} u_{j} \otimes v_{j} y_{i}\right)$ is well defined in $L^{2}(M)^{*} \otimes_{h D^{\circ p}} L^{2}(M)$. Indeed, if $\sigma_{2}^{-1}(X)=0 \in M \stackrel{\text { eh }}{\otimes} M$, by $[\mathbf{M 0 5}](2.5)$ there exists $P \in M_{I}(D)$ with $P x=$ $x, y P=0$ so that $\sum \pi\left(x E_{D^{\prime}}(U) y\right)=\sum \pi\left(P x E_{D^{\prime}}(U) y\right)=\sum \pi\left(x E_{D^{\prime}}(U) y P\right)=0$. Moreover, we have a bound $\sum_{i, j}\left\|x_{i} u_{j}\right\|_{2}^{2} \leq\left\|\sum x_{i}^{*} x_{i}\right\| \sum_{j}\left\|u_{j}\right\|_{2}^{2}$ so that $\left(x_{i} u_{j}\right)$ is indeed a row vector in $L^{2}(M)^{*}$, and similarly $\left(v_{j} y_{i}\right)$ is a column vector in $L^{2}(M)$. Thus we have indeed $\sum_{i, j} x_{i} u_{j} \otimes v_{j} y_{i} \in L^{2}(M)^{*} \otimes_{e h} L^{2}(M) \simeq L^{2}(M)^{*} \otimes_{h} L^{2}(M)$ as claimed.

Moreover, by the definition of the norm, it is now easy to see

$$
\left\|X \#_{L^{1}} U\right\|_{L^{2}(M) * \otimes_{e h} L^{2}(M)} \leq\|\sigma(X)\|_{\substack{\text { eh } \\ M \\ D}}\left\|E_{D^{\prime}}(U)\right\| \leq\|X\| \underset{\substack{\text { eh } \\ M^{D, c}}}{ }\|U\|_{L^{2}(M) * \otimes_{h D^{o p} L^{2}(M)} .}
$$

This gives the outer action on $L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ owing to the identity $\sigma_{2}^{-1}(X Y)=$ $\sigma_{2}^{-1}(Y) \# \sigma_{2}^{-1}(X)$. The stability and commutation are easy.

We now turn to (2a)-(2d). First note that $\sigma_{T C}: L^{2}\left(M^{o p}\right)^{*} \otimes_{h D} L^{2}\left(M^{o p}\right) \rightarrow$ $L^{2}(M)^{*} \otimes_{h D^{o p}} L^{2}(M)$, given by $\sigma_{T C}\left(a \otimes_{D} b\right)=b \otimes_{D^{o p}} a$, is isometric. This uses that a row vector of $L^{2}\left(M^{o p}\right)^{*}$ is the same as a column vector of $L^{2}(M)$.

To prove (2a) note that the canonical map $j: M \stackrel{\stackrel{\text { eh }}{\otimes}}{D} M \rightarrow L^{2}(M)^{*} \stackrel{\text { eh }}{\otimes}{ }_{D}^{\otimes} L^{2}(M)=$ $L^{2}(M)^{*} \otimes_{h D} L^{2}(M)$ composed with $\sigma_{T C}$ above gives the map $\sigma_{T C} j$ valued in $L^{2}(M)^{*} \otimes_{h D^{o p}} L^{2}(M)=L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ such that $Y \# e_{D}$ coincides in the canonical identification with $\sigma_{T C} j(Y)$, proving $Y \# e_{D} \in\left\langle M, e_{D}\right\rangle \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$. The statement about the agreement with canonical inclusion is then obvious.

Let us prove (2b). Since $D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \cap\left\langle M, e_{D}\right\rangle$ is dense in $D^{\prime} \cap L^{2}\left(\left\langle M, e_{D}\right\rangle\right)$, by approximating $Z \# e_{D}$ by $Z^{\prime} \in D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \cap\left\langle M, e_{D}\right\rangle$ and even $Z^{\prime}=$ $\sum_{i} z_{i}^{\prime} e_{D} z_{i} \in M e_{D} M$ in $L^{2}$ norm, we see that it suffices to prove that $X \rightarrow$ $\left\langle Z^{\prime}, X \# Y \# e_{D}\right\rangle$ is weak-* continuous on bounded sets.

For $Y \in D^{\prime} \cap M \stackrel{\text { eh }}{\otimes} M$, note that $Y \# e_{D} \in D^{\prime} \cap\left\langle M, e_{D}\right\rangle \subset\left\langle M^{o p}, e_{D}\right\rangle$. Since $Y \# e_{D} \in D^{\prime} \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)=\left(D^{\prime} \cap\left\langle M, e_{D}\right\rangle\right)_{*} \subset L^{1}\left(\left\langle M^{\prime}, e_{D}\right\rangle\right)$, we see that $Y \# e_{D} \in$ $L^{1}\left(\left\langle M^{\prime}, e_{D}\right\rangle\right) \cap\left\langle M^{\prime}, e_{D}\right\rangle$. Since $L^{1}\left(\left\langle M^{\prime}, e_{D}\right\rangle\right) \simeq L^{2}(M)^{*} \otimes_{h D} L^{2}(M)$ we have a canonical form $Y \# e_{D}=\sum\left(y_{k}^{\prime}\right)^{o p} e_{D} y_{k}{ }^{o p}$ with $\left(y_{k}^{\prime}\right)$ column vector in $L^{2}(M)$ and $\left(y_{k}\right)$ row vector in $L^{2}(M)^{*}$. Note that for $\xi \in M$, one can compute the evaluation with the formula above $\left[\left(x^{\prime} \otimes x\right) \#\left(Y \# e_{D}\right)\right](\xi)=\sum_{k} x^{\prime} E_{D}\left(x \xi y_{k}\right) y_{k}^{\prime} \in L^{1}(M)$ (one can first approximate $y_{k}, y_{k}^{\prime}$ by elements of $M$ to establish the formula).

If we take $\left(g_{j}\right)_{j \in J}$ a basis of $L^{2}(M)$ as a right D-module (of elements of $M$ if we want), then one can use the well-known formula

$$
\operatorname{Tr}\left(Z^{\prime}\left[X \#\left(Y \# e_{D}\right)\right]\right)=\sum_{j}\left\langle g_{j}, Z^{\prime}\left[X \#\left(Y \# e_{D}\right)\left(g_{j}\right)\right]\right\rangle
$$

We compute a term in the last formula. We continue our computation by applying $Z^{\prime}$ which also gives a map on $L^{1}(M)$ :

$$
Z^{\prime}\left[\left(x^{\prime} \otimes x\right) \#\left(Y \# e_{D}\right)\left(g_{j}\right)\right]=\sum_{i} z_{i}^{\prime} E_{D}\left(z_{i} \sum_{k} x^{\prime} E_{D}\left(x g_{j} y_{k}\right) y_{k}^{\prime}\right) \in L^{1}(M)
$$

Then since $g_{j} \in M$, one can compute the trace :

$$
\tau\left(g_{j}^{*} Z^{\prime}\left[\left(x^{\prime} \otimes x\right) \#\left(Y \# e_{D}\right)\left(g_{j}\right)\right]\right)=\sum_{i} \tau\left(E_{D}\left(g_{j}^{*} z_{i}^{\prime}\right) z_{i} \sum_{k} x^{\prime} E_{D}\left(x g_{j} y_{k}\right) y_{k}^{\prime}\right)
$$

which could be expressed as a duality formula for $Y \# e_{D} \in D^{\prime} \cap L^{1}\left(\left\langle M^{\prime}, e_{D}\right\rangle\right)$ since the sum in $i$ is finite, thus one can use its commutativity with $D$ :

$$
\begin{aligned}
\tau\left(g_{j}^{*} Z^{\prime}\left[\left(x^{\prime} \otimes x\right) \#\left(Y \# e_{D}\right)\left(g_{j}\right)\right]\right. & =\sum_{i} \tau\left(z_{i} \sum_{k} x^{\prime} E_{D}\left(x g_{j} E_{D}\left(g_{j}^{*} z_{i}^{\prime}\right) y_{k}\right) y_{k}^{\prime}\right) \\
& =\sum_{i} \tau\left(z_{i}\left(x^{\prime} \otimes x\right) \#\left(Y \# e_{D}\right)\left(g_{j} E_{D}\left(g_{j}^{*} z_{i}^{\prime}\right)\right)\right.
\end{aligned}
$$

where we have used one of our previous formulas with $\xi=g_{j} E_{D}\left(g_{j}^{*} z_{i}^{\prime}\right)$ instead of $g_{j}$ at the last equality. Again viewing $\left(x^{\prime} \otimes x\right) \#\left(Y \# e_{D}\right)$ as the bounded operator on $L^{2}$ and using the relation for a right basis $\sum_{j} g_{j} E_{D}\left(g_{j}^{*} z_{i}^{\prime}\right)=z_{i}^{\prime}$ with convergence in $L^{2}$, one may use operator weak-* convergence to replace $\left(x^{\prime} \otimes x\right)$ by $X=\sum\left(x_{l}^{\prime} \otimes x_{l}\right)$ :

$$
\begin{aligned}
\operatorname{Tr}\left(Z^{\prime}\left[X \#\left(Y \# e_{D}\right)\right]\right) & \left.=\sum_{i} \tau\left(z_{i} X \#\left(Y \# e_{D}\right)\left(z_{i}^{\prime}\right)\right)\right) \\
& =\sum_{i, k, l} \tau\left(z_{i} x_{l}^{\prime} E_{D}\left(x_{l} z_{i}^{\prime} y_{k}\right) y_{k}^{\prime}\right)=\left\langle X, \sum_{k, i} y_{k}^{\prime} z_{i} \otimes_{D^{o p}} z_{i}^{\prime} y_{k}\right\rangle
\end{aligned}
$$

Since $\sum_{k, i} y_{k}^{\prime} z_{i} \otimes_{D^{o p}} z_{i}^{\prime} y_{k} \in L^{2}\left(M^{*}\right) \otimes_{e h D^{o p}} L^{2}(M) \subset L^{1}(M)^{\otimes_{h D^{\prime}}{ }^{2}}$, the predual of the weak-* Haagerup tensor product, one gets the claimed weak-* continuity and thus the proof of $(2 \mathrm{~b})$ is complete.

To prove the density part in (2c), it is enough to show that for a finite sum, $E_{D^{\prime}}\left(\sum_{i} x_{i} \otimes_{D} y_{i}\right) \in M^{\substack{\text { eh } \\ \otimes, c}}$.

More precisely, we will show that

$$
\begin{equation*}
\sigma_{1}\left(E_{D^{\prime}}\left(\sum_{i} x_{i} \otimes_{D} y_{i}\right)\right)=\sigma_{2}\left(E_{D^{\prime}}\left(\sum_{i} y_{i} \otimes_{D} x_{i}\right)\right) . \tag{35}
\end{equation*}
$$

We thus want to prove, for any $U, V \in D^{\prime} \cap\left\langle M, e_{D}\right\rangle \cap L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ :

$$
\begin{aligned}
\operatorname{Tr}\left(\left[\left(E_{D^{\prime}}\left(\sum_{i} x_{i} \otimes_{D} y_{i}\right)\right) \# U\right] V\right) & =\operatorname{Tr}\left(\left[U \#\left(E_{D^{\prime}}\left(\sum_{i} y_{i} \otimes_{D} x_{i}\right)\right)\right] V\right) \\
& =\operatorname{Tr}\left(U\left[\left(E_{D^{\prime}}\left(\sum_{i} y_{i} \otimes_{D} x_{i}\right)\right) \# V\right]\right)
\end{aligned}
$$

By density (simultaneous weak-* and $L^{1}$ using the agreeing conditional expectations) it suffices to take $U=X \# e_{D}, V=Y \# e_{D}, X, Y \in D^{\prime} \cap M^{\stackrel{\text { eh }}{\otimes 2} 2}$.

But now we can use the weak-* continuity we just proved to replace the conditional expectations by the limit of a net of convex combinations of conjugates by unitaries of $D$, and thus by commutativity with $D$, the conditional expectations can be removed, and the relation then becomes obvious.

Finally, for (2d), taking bounded nets $U_{n} \rightarrow U, V_{\nu} \rightarrow V$ we note that $U_{n} \# V, U \# V_{\nu}$ are still bounded, thus weak-* precompact and it thus suffices to show that $U \# V$ is the unique cluster point, for instance by showing the nets converge weakly in $L^{2}(M) \otimes_{D} L^{2}(M)$ or $D^{\prime} \cap L^{2}(M) \otimes_{D} L^{2}(M)$. For $Z \in D^{\prime} \cap M \stackrel{\text { eh }}{\otimes} M$, by (2b) we have $\left\langle Z \# e_{D}, U_{n} \# V \# e_{D}\right\rangle \rightarrow\left\langle Z \# e_{D}, U \# V \# e_{D}\right\rangle$, and since the elements $Z \# e_{D}$ are dense in $D^{\prime} \cap L^{2}(M) \otimes_{D} L^{2}(M)$, one deduces the wanted weak convergence in $D^{\prime} \cap L^{2}(M) \otimes_{D} L^{2}(M)$. Applying formula (33) to $\left(Z \# e_{D}\right)^{*} \in L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$, one gets for $Z \in M \stackrel{\mathrm{eh}}{\otimes} M$,

$$
\begin{aligned}
\left\langle Z \# e_{D}, U \# V_{\nu} \# e_{D}\right\rangle & =\operatorname{Tr}\left(U \#\left(V_{\nu} \# e_{D}\right)\left(Z \# e_{D}\right)^{*}\right)=\operatorname{Tr}\left(\left(V_{\nu} \# e_{D}\right)\left[\left(Z \# e_{D}\right)^{*} \# U\right]\right) \\
& \rightarrow \operatorname{Tr}\left(\left(V \# e_{D}\right)\left[\left(Z \# e_{D}\right)^{*} \# U\right]\right)=\left\langle Z \# e_{D}, U \# V \# e_{D}\right\rangle
\end{aligned}
$$

The convergence is due to the weak-* continuity of the map.$\# e_{D} M \stackrel{\text { eh }}{\otimes} M \rightarrow$ $\left\langle M, e_{D}\right\rangle$ (following from the corresponding one with value $L^{2}\left(\left\langle M, e_{D}\right\rangle\right)$ ). Again, by density we deduce the weak convergence in $L^{2}(M) \otimes_{D} L^{2}(M)$, and since.$\# e_{D}$ is the canonical weak-* continuous map to $L^{2}(M) \otimes_{D} L^{2}(M)$, this concludes.

Theorem A.20. We keep the assumptions and notation of Theorem A. 17 and Definition A. 18.
(3) Assume either that there exists a $D$-basis of $L^{2}(M)$ as a right $D$ module $\left(f_{i}\right)_{i \in I}$ which is also a D-basis of $L^{2}(M)$ as a left $D$ module or that $D$ is a $I I_{1}$ factor and that $L^{2}(M)$ is an extremal $D-D$ bimodule. Then (writing $\sigma_{1}^{-1}(X) \# e_{D}=$ $\left.X \# e_{D}\right) \tau(X)=\left\langle e_{D}, X \# e_{D}\right\rangle$ is a trace on $D^{\prime} \cap M_{D}^{\stackrel{\text { eh }}{\otimes 2}}{ }_{D}$ such that $L^{2}\left(M^{\stackrel{\text { eh }}{\otimes, c} 2}, \tau\right)=$ $D^{\prime} \cap L^{2}(M) \otimes_{D} L^{2}(M)$. Moreover the involution on $M^{\substack{\text { eh } \\ D, c}}$ coincides with the adjoint in its action on $D^{\prime} \cap L^{2}(M) \otimes_{D} L^{2}(M)$.
(4) Assuming the conclusion of (3), the inner action of $M^{\substack{\mathrm{eh} \\ D, c}}{ }^{2}$ on $L^{2}\left(M^{\stackrel{\mathrm{eh}}{\otimes, c} 2}, \tau\right)=$ $D^{\prime} \cap L^{2}(M) \otimes_{D} L^{2}(M)$ extends to an action on $L^{2}(M) \otimes_{D} L^{2}(M)$.

We may later identify $M^{\substack{\text { eh } \\ \otimes, c c}}$ as a subset of $D^{\prime} \cap M^{\stackrel{\text { eh }}{\otimes 2}}{ }^{2}$ via $\sigma_{1}^{-1}$.

Proof. (3) Our proof relies on the existence of a unitary Burns rotation, which exists in the extremal case. The case with a two-sided basis is an easy variant of that case and is left to the reader.

First, note that, without any assumption on $M$ related to traciality, for $X \in$
 (1):

$$
\left.\operatorname{Tr}\left(\left[\sigma_{1}^{-1}(X)^{\star} \# U\right] V\right)=\operatorname{Tr}\left(U\left[\sigma_{2}^{-1}(X) \# V^{*}\right)\right]^{*}\right)
$$

to $U=e_{D}, V=\left(Y \# e_{D}\right)$ to get

$$
\begin{align*}
\tau\left(X^{*} Y\right) & =\operatorname{Tr}\left(e_{D}\left[\left(\sigma_{1}^{-1}(\sigma(X))\right) \#\left(Y \# e_{D}\right)^{*}\right]^{*}\right) \\
& \left.=\operatorname{Tr}\left(Y \# e_{D}\left[\sigma_{2}^{-1}(\sigma(X)) \# e_{D}\right)\right]^{*}\right)  \tag{36}\\
& \left.=\operatorname{Tr}\left(\left[\sigma_{1}^{-1}(X) \# e_{D}\right)\right]^{*}\left(Y \# e_{D}\right)\right) \\
& =\left\langle X \# e_{D}, Y \# e_{D}\right\rangle
\end{align*}
$$

In particular, this realizes canonically isometrically $L^{2}\left(M^{\stackrel{\text { eh }}{\otimes, c} 2}, \tau\right)$ as a subspace of $D^{\prime} \cap L^{2}(M) \otimes_{D} L^{2}(M)$ and as a consequence shows the agreement of the previously defined adjoint with the Hilbert space one. The density in our part (2c) give the identification $L^{2}\left(M^{\substack{\text { eh } \\ D, c}}, \tau\right)=D^{\prime} \cap L^{2}(M) \otimes_{D} L^{2}(M)$.

It remains to prove traciality $\tau(X Y)=\tau(Y X)$; it is enough to prove it for $X, Y \in M \underset{D, c}{\stackrel{e h}{\otimes}} M$. Indeed, using the proof of the density and weak-* continuity in our part (2), we only need to consider $X=E_{D^{\prime}}\left(x_{1} \otimes x_{2}\right), Y=E_{D^{\prime}}\left(y_{1} \otimes y_{2}\right)$ for $x_{i}, y_{i} \in M$. But from our previous computation, this reduces to:

$$
\begin{aligned}
\left\langle X^{*} \# e_{D}, Y \# e_{D}\right\rangle & =\left\langle E_{D^{\prime}}\left(x_{1}^{*} e_{D} x_{2}^{*}\right), E_{D^{\prime}}\left(y_{1} e_{D} y_{2}\right)\right\rangle \\
& =\left\langle E_{D^{\prime}}\left(y_{1}^{*} e_{D} y_{2}^{*}\right), E_{D^{\prime}}\left(x_{1} e_{D} x_{2}\right)\right\rangle \\
& =\left\langle Y^{*} \# e_{D}, X \# e_{D}\right\rangle
\end{aligned}
$$

Now the key equality in the middle line comes from the extremality of $L^{2}(M)$ that gives from Theorem A. 15 a unitary Burns rotation. From unitarity it is easy to see that $\rho\left(E_{D^{\prime}}\left(y_{1} \otimes_{D} y_{2}\right)\right)=E_{D^{\prime}}\left(y_{2} \otimes_{D} y_{1}\right)$ so that the equality in the middle line comes from

$$
\begin{aligned}
\left\langle E_{D^{\prime}}\left(x_{1}^{*} e_{D} x_{2}^{*}\right), E_{D^{\prime}}\left(y_{1} e_{D} y_{2}\right)\right\rangle & =\left\langle E_{D^{\prime}}\left(x_{1}^{*} \otimes_{D} x_{2}^{*}\right), E_{D^{\prime}}\left(y_{1} \otimes_{D} y_{2}\right)\right\rangle \\
& =\left\langle\rho\left(E_{D^{\prime}}\left(x_{1}^{*} \otimes_{D} x_{2}^{*}\right)\right), \rho\left(E_{D^{\prime}}\left(y_{1} \otimes_{D} y_{2}\right)\right)\right\rangle \\
& =\left\langle\left(E_{D^{\prime}}\left(x_{2}^{*} \otimes_{D} x_{1}^{*}\right)\right),\left(E_{D^{\prime}}\left(y_{2} \otimes_{D} y_{1}\right)\right)\right\rangle \\
& =\left\langle E_{D^{\prime}}\left(x_{2}^{*} e_{D} x_{1}^{*}\right), E_{D^{\prime}}\left(y_{2} e_{D} y_{1}\right)\right\rangle \\
& =\operatorname{Tr}\left(x_{1} e_{D} x_{2} E_{D^{\prime}}\left(y_{2} e_{D} y_{1}\right)\right) \\
& =\left\langle E_{D^{\prime}}\left(y_{1}^{*} e_{D} y_{2}^{*}\right), E_{D^{\prime}}\left(x_{1} e_{D} x_{2}\right)\right\rangle .
\end{aligned}
$$

(4) The extension of the inner action of $M^{\stackrel{\text { eh }}{\otimes, c} 2}$, to an action on $L^{2}(M) \otimes_{D} L^{2}(M)$ $\stackrel{\substack{\text { eh } \\ D, c}}{ } 2$ will extend for $U \in L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \cap$
$L^{2}(M) \otimes_{D} L^{2}(M)$,

$$
U \# X:=\sigma(X) \#_{L^{1}} U
$$

with the outer action on $L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ built at the end of $(1)$.
We aim to construct the action of $M^{\stackrel{\mathrm{eh}}{\mathrm{Q}}, \mathrm{c}} 2$ by interpolation of the previous action with a dual action on $\left\langle M, e_{D}\right\rangle$, defined by duality for $V \in\left\langle M, e_{D}\right\rangle$ :

$$
\operatorname{Tr}\left(\left(V \#_{L^{\infty}} X\right) U\right)=\operatorname{Tr}\left(V\left(X \#_{L^{1}} U\right)\right)
$$

It thus remains to see these two actions agree on a common dense subspace.
Take $U=Y \# e_{D} \in L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \cap\left\langle M, e_{D}\right\rangle$, for $Y \in \pi\left(M \otimes_{a l g} M\right) \subset M \otimes_{h D} M \subset$ $M \stackrel{\text { eh }}{\stackrel{\text { eh }}{D}} M$. We already noticed they form a dense subspace in both $L^{1}\left(\left\langle M, e_{D}\right\rangle\right)$ and (for the weak-* topology) in $\left\langle M, e_{D}\right\rangle$. Note that this indeed gives (even for $Y \in M \stackrel{\text { eh }}{\otimes} M)$ the expected inner action

$$
\sigma(X) \#_{L^{1}} U=\sigma(X) \#_{L^{1}}\left(\sigma_{T C} j(Y)\right)=\sigma_{T C} j(Y \# X)
$$

For the last key equality, take a canonical representation of $Y=\sum y_{j} \otimes_{D} y_{j}^{\prime}, X=$ $\sum x_{i} \otimes_{D} x_{i}^{\prime}$ then we note that
$\sigma(X) \#_{L^{1}}\left(\sigma_{T C} j(Y)\right)=\sigma(X) \#_{L^{1}}\left(\sum y_{j}^{\prime} \otimes_{D^{\circ p}} y_{j}\right)=\sum_{i j} x_{i}^{\prime} y_{j}^{\prime} \otimes_{D^{\circ p}} y_{j} x_{i}=\sigma_{T C} j(Y \# X)$
Now, take also $V=Z \# e_{D} \in L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \cap\left\langle M, e_{D}\right\rangle$, for $Z=\sum z_{i}^{\prime} \otimes_{D} z_{i} \in$ $\pi\left(M \otimes_{\text {alg }} M\right)$ to compute $V \#_{L^{\infty}} X$ :

$$
\begin{aligned}
\operatorname{Tr}\left(\left(V \#_{L^{\infty}} X\right) U\right) & =\operatorname{Tr}\left(\left(Z \# e_{D}\right)\left[(Y \# \sigma(X)) \# e_{D}\right]\right) \\
& =\operatorname{Tr}\left(\left(Z \# e_{D}\right)\left[Y \#\left(\sigma(X) \# e_{D}\right)\right]\right) \\
& =\operatorname{Tr}\left(\left[\left(Z \# e_{D}\right) \# Y\right]\left(\sigma(X) \# e_{D}\right)\right) \\
& =\operatorname{Tr}\left(\left[\sum_{i j} y_{j}^{\prime} z_{i}^{\prime} e_{D} z_{i} y_{j}\right]\left(\sigma(X) \# e_{D}\right)\right) \\
& =\operatorname{Tr}\left(e_{D}\left[\left(E_{D^{\prime}}\left(\sum_{i j} z_{i} y_{j} \otimes_{D} y_{j}^{\prime} z_{i}^{\prime}\right) \# \sigma(X) \# e_{D}\right)\right)\right.
\end{aligned}
$$

where we started by using the relations we just established, the adjoint relation (33) in the third line, an explicit computation in the fourth valid for finite sums and the weak-* continuity on bounded sets of our part (2b) to introduce a conditional expectation.

Now having elements in $D^{\prime} \cap M \stackrel{\text { eh }}{\otimes} M$ we can use the traciality we just proved, the adjoint relation (33), then in the third line the definition of $\sigma$ and a removal of conditional expectation since $X \# e_{D} \in D^{\prime} \cap\left\langle M, e_{D}\right\rangle$ and finally again explicit
computations for finite sums to get:

$$
\begin{aligned}
\operatorname{Tr}\left(\left(V \#_{L^{\infty}} X\right) U\right) & =\operatorname{Tr}\left(e_{D}\left[\sigma(X) \#\left(\left(E_{D^{\prime}}\left(\sum_{i j} z_{i} y_{j} \otimes_{D} y_{j}^{\prime} z_{i}^{\prime}\right) \# e_{D}\right)\right)\right]\right) \\
& =\operatorname{Tr}\left(\left(e_{D} \# \sigma(X)\right)\left[\left(\left(E_{D^{\prime}}\left(\sum_{i j} z_{i} y_{j} \otimes_{D} y_{j}^{\prime} z_{i}^{\prime}\right) \# e_{D}\right)\right)\right]\right) \\
& =\operatorname{Tr}\left(\left(X \# e_{D}\right)\left[\left(\left(\sum_{i j} z_{i} y_{j} \otimes_{D} y_{j}^{\prime} z_{i}^{\prime}\right) \# e_{D}\right)\right]\right) \\
& =\operatorname{Tr}\left(\left[\sum_{i} z_{i}^{\prime}\left(X \# e_{D}\right) z_{i}\right]\left(Y \# e_{D}\right)\right) \\
& =\operatorname{Tr}\left(\left[(Z \# X) \# e_{D}\right]\left(Y \# e_{D}\right)\right)
\end{aligned}
$$

Thus $\left(V \#_{L^{\infty}} X\right)=(Z \# X) \# e_{D}=\sigma(X) \#_{L^{1}} V$ and we can thus interpolate both maps to get the desired action. Finally, the agreement with the inner action on the commutant comes from the equality $\sigma(X) \#_{L^{1}}\left(Y \# e_{D}\right)=(Y \# X) \# e_{D}$ we proved for $Y \in M \stackrel{\text { eh }}{\underset{D}{\otimes}} M$.
A.3. $k$-fold cyclic module extended Haagerup tensor products. We now turn to the construction of $k$-fold cyclic tensor powers $M^{\substack{\text { eh } \\ D, c}}$ extending the case $k=2$ we have just dealt with. The desired properties of these tensor powers include the action of cyclic permutations, commutation with left-right actions of $D$ as well as compatibility with various multiplication and evaluation operations. Elements in these modules will serve as coefficients for our generalized analytic functions, on which free difference quotient and cyclic gradients will be well-defined.

We will use free products with amalgamation as a convenient trick to reduce to the case of 2 -fold cyclic modules we have already considered.

We thus now fix the appropriate notation. Let $D \subset M$ finite von Neumann algebras and consider $D \subset N_{\kappa}=M *_{D}\left(D \otimes W^{*}\left(S_{1}, \ldots, S_{\kappa}\right)\right)$ the free product with amalgamation with a free semicircular element $S_{1}, \ldots, S_{\kappa}$ for $\kappa$ an ordinal. This gives an isomorphic result for each ordinal of same cardinality. Note that as $D$ bimodules, $L^{2}\left(N_{\kappa}\right) \simeq \bigoplus_{n=0}^{\infty}\left(L^{2}(M)^{\otimes_{D} n}\right)^{\kappa^{n-1}}$, with $\bigoplus_{n=0}^{k}\left(L^{2}(M)^{\otimes_{D} n}\right)^{\kappa^{n-1}}$ being the usual orthonormalisation of $\overline{\operatorname{Span}\left\{\left(M S_{i_{1}}\right) \ldots\left(M S_{i_{n-1}}\right) M, 1 \leq n \leq k, i_{j} \in[1, \kappa]\right\}}$ ("Wick words").

In particular, for any word $n=n_{1} \ldots n_{|n|}$ in $\kappa$ letters there is an embedding

$$
\iota_{n}: M^{\substack{\mathrm{eh} \\ D}}(|n|+1) \rightarrow L^{2}\left(N_{\kappa}\right)
$$

valued in $L^{2}(M)^{\otimes_{D}|n|+1} \cap N_{\kappa}$ obtained by first sending the tensor $x_{0} \otimes \cdots \otimes x_{|n|}$ to $x_{0} S_{n_{1}} x_{1} \cdots S_{n_{|n|}} x_{|n|}$ and then projecting onto the orthogonal complement of the space $\overline{\operatorname{Span}\left\{\left(M S_{i_{1}}\right) \ldots\left(M S_{i_{k-1}}\right) M, 1 \leq k \leq|n|, i_{j} \in[1, \kappa]\right\}}$. We will write

$$
L^{2}(M)^{\otimes_{D} n} \simeq L^{2}(M)^{\otimes_{D}(|n|+1)}
$$

for the closure of the image of $\iota_{n}$.
A.3.1. Construction of intersection spaces. To handle the action of a basic cyclic permutation, we need an intersection space similar to the intersection $L^{1}\left(\left\langle M, e_{D}\right\rangle\right) \cap$ $\left\langle M, e_{D}\right\rangle$ in the previous section (which corresponds to the case $|n|+1=2$ ). For this, we will use $L^{1}\left(\left\langle N_{\kappa}, e_{D}\right\rangle\right) \cap\left\langle N_{\kappa}, e_{D}\right\rangle$ (for any fixed $\kappa \geq k$, e.g. $\kappa=\omega$ )

Let $\mathcal{K}_{m, m}=L^{2}(M)^{\otimes_{D}|m|+1}, \mathcal{K}_{m, n}=L^{2}(M)^{\otimes_{D}|m|+1} \oplus L^{2}(M)^{\otimes_{D}|n|+1}$, if $m \neq n$, considered with the right normal action of $D$, and consider the corresponding basic construction $B(M: D,(m, n))=B\left(\mathcal{K}_{m, n}, \mathcal{K}_{m, n}\right)_{D}$ with a canonical semifinite trace $\operatorname{Tr}$ (see e.g. [PV11, section 2.3] or the beginning of section 6.1). In our operator space terminology, we have, by [M05, Corol 3.3] (and the preceding Theorem to change the reference Hilbert space structure to compute duality), $B(M: D,(m, n)) \simeq\left(\mathcal{K}_{m, n}\right)_{L^{2}(D)} \stackrel{\text { eh }}{\otimes} L^{2}(D)\left(\mathcal{K}_{m, n}^{*}\right)$. Via this isomorphism $\xi d \otimes_{D} \bar{\eta}=\xi \otimes_{D} \overline{\eta d^{*}}$ is send to $L_{\xi d} L_{\eta}^{*}=L_{\xi} d L_{\eta}^{*}=L_{\xi} L_{\eta d^{*}}^{*}$, where $L_{\xi}$ denotes left multiplication by $\xi$, see [PV11, Section 2.3]. Its predual is $\mathscr{T} \mathscr{C}(M: D,(m, n)):=$ $L^{1}(B(M: D,(m, n)), T r) \simeq \mathcal{K}_{m, n}^{*} \otimes_{h D^{o p}} \mathcal{K}_{m, n}$. The spaces $B(M: D,(m, n))$ and $\mathscr{T} \mathscr{C}(M: D,(m, n))$ are considered as an interpolation pair as before.

We will be mostly interested in off-diagonal block matrices in these constructions, namely (for $k \neq l$ ),

$$
\begin{aligned}
\mathscr{T} \mathscr{C}(M: D, k, l) & :=L^{2}(M)^{\otimes_{D}|k|+1 *} \otimes_{h D^{o p}} L^{2}(M)^{\otimes_{D}|l|+1}, \\
B(M: D, k, l) & :=B\left(L^{2}(M)^{\otimes_{D}|k|+1}, L^{2}(M)^{\otimes_{D}|l|+1}\right)_{D}
\end{aligned}
$$

so that $B(M: D, k, l)=\mathscr{T} \mathscr{C}(M: D, l, k)^{*}$ and the duality can be seen as induced by $\operatorname{Tr}$ above when they are seen as block matrices in the space above.

Let us start with a lemma making explicit this relation. Consider, for $n$ a word in $\kappa$ letters, $P_{n} \in\left\langle N_{\kappa}, e_{D}\right\rangle \cap B\left(L^{2}\left(N_{\kappa}\right), L^{2}(M)^{\otimes_{D} n}\right)$ the orthogonal projection on the $n$-th component in the decomposition $L^{2}\left(N_{\kappa}\right) \simeq \bigoplus_{k=0}^{\infty} \bigoplus_{|n|=k} L^{2}(M)^{\otimes_{D} n}$. Note that we draw a distinction between the adjoint $P_{n}^{*} \in B\left(L^{2}(M)^{\otimes_{D} n}, L^{2}\left(N_{\kappa}\right)\right)$ and the map $\overline{P_{n}} \in B\left(L^{2}\left(N_{\kappa}\right)^{*}, L^{2}(M)^{\otimes_{D} n *}\right): \overline{P_{n}}(\bar{\xi})=\bar{\xi} \circ P_{n}^{*}=\overline{P_{n} \xi}$, even though they may be conjugate by some isomorphisms above.

Lemma A.21. (1) Let $X \in\left\langle N_{\kappa}, e_{D}\right\rangle$ and $Y \in L^{1}\left(\left\langle N_{\kappa}, e_{D}\right\rangle\right) \simeq L^{2}(N)^{*} \otimes_{h D^{o p}}$ $L^{2}(N) . X$ and $Y$ agree in the classical intersection space, if and only if for all $k, l$ words in $\kappa$ letters, $P_{l} X P_{k}^{*} \in B(M: D, k, l)$ and $\left(\overline{P_{k}} \otimes_{D^{\text {op }}} P_{l}\right)(Y)$ agree in the intersection space coming from the inclusions $B(M: D, k, l) \subset B(M$ : $D,(k, l)), \mathscr{T} \mathscr{C}(M: D, k, l) \subset \mathscr{T} \mathscr{C}(M: D,(k, l))$.
(2) We have the inclusions:

$$
\mathscr{T} \mathscr{C}(M: D, k, l) \subset B\left(L^{2}(M)^{\otimes_{D} k}, L^{1}(D) \otimes_{h D^{o p}} L^{2}(M)^{\otimes_{D} l}\right)_{D} \supset B(M: D, k, l)
$$

(the right module structure on $L^{1}(D) \otimes_{h D^{o p}} L^{2}(M)^{\otimes_{D} l}$ given by right multiplication on $L^{1}(D)$ ). Moreover the intersection space of interpolation theory $\mathscr{T} \mathscr{C}(M: D, k, l) \cap B(M: D, k, l)$ coincides with the one coming from the inclusions $B(M: D, k, l) \subset B(M: D,(k, l)), \mathscr{T} \mathscr{C}(M: D, k, l) \subset \mathscr{T} \mathscr{C}(M:$ $D,(k, l))$, those spaces being realized as classical compatible couple for interpolation of $L^{p}$ spaces of a semifinite von Neumann algebra.

Proof. (1) This point readily comes from the agreement of the trace induced by projections from $\left\langle N_{\kappa}, e_{D}\right\rangle$ with the one defined on $B(M: D,(k, l))$. Thus if $p$ finite projection in $B(M: D,(k, l)), P_{k}^{*} p P_{k}$ is finite in $\left\langle N_{\kappa}, e_{D}\right\rangle$. Hence the agreement of
$X$ and $Y$, which boils down to the agreement for any finite projection of their compressions, gives $P_{l}^{*} p P_{l} X P_{k}^{*} p P_{k}=\left(\overline{P_{k}^{*} p P_{k}} \otimes_{D^{o p}} P_{l}^{*} p P_{l}\right)(Y)$ and thus the agreement after removing one application of $P_{i}^{*}$, i.e. as we said since this is for all finite projection $p, P_{l} X P_{k}=\left(\overline{P_{k}} \otimes_{D^{\circ p}} P_{l}\right)(Y)$. Conversely, since $P_{\leq n}=P_{0}+\ldots+\sum_{|m|=n} P_{m}$ increases to identity, it suffices to consider finite projection $q \in\left\langle N_{\kappa}, e_{D}\right\rangle$ with $q \leq P_{\leq n}$ which readily reduces to compression by $q \wedge P_{k}=P_{k}^{*}\left(q \wedge P_{k}\right) P_{k}$ (on the right and $q \wedge P_{l}$ on the left) for a projection $p$ on $B(M: D,(k, l))$. And we can then apply the converse reasoning.
(2) Note that

$$
\begin{aligned}
\left(L^{2}(M)^{\otimes_{D} k}\right) & =\left(L^{2}(M)_{L^{2}(D)}^{\otimes_{D} k}\right) \stackrel{\text { eh }}{\otimes} L_{D}^{2}(D) \\
& \simeq C B\left(L^{2}(M)^{\otimes_{D} k *}, L^{2}\left(D^{o p}\right)^{*}\right)_{D^{o p}} \stackrel{\text { eh }}{\otimes} L_{D}^{2}(D) \\
& \simeq C B\left(L^{2}(M)^{\otimes_{D} k *}, L^{2}\left(D^{o p}\right)^{*} \stackrel{\text { eh }}{\otimes} D_{D}^{2}(D)\right)_{D^{o p}}=C B\left(L^{2}(M)^{\otimes_{D} k *}, L^{1}(D)\right)_{D^{o p}}
\end{aligned}
$$

For any $\phi \in\left(L^{2}(M)^{\otimes_{D} k}\right)$ we have a map $\phi \otimes_{h D^{o p}} 1: L^{2}(M)^{\otimes_{D} k *} \otimes_{h D^{o p}}$ $L^{2}(M)^{\otimes_{D} l} \rightarrow L^{1}(D) \otimes_{h D^{o p}} L^{2}(M)^{\otimes_{D} l}$. Moreover, take $Z=x \otimes_{D^{o p}} y$ a typical element in $L^{2}(M)^{\otimes_{D} k *} \otimes_{h D^{o p}} L^{2}(M)^{\otimes_{D} l}$, if its image vanishes, this means for all $\phi \in L^{2}(M)^{\otimes_{D} k}, \phi(x) \otimes_{D^{o p}} y=0$, thus by [M05] formula (2.5) there is $P_{\phi} \in M_{J}\left(D^{o p}\right)$ such that $\phi(x) P_{\phi}=0, P_{\phi} y=y$. Take $P=\bigwedge_{\phi \in L^{2}(M)^{\otimes D^{k}}} P_{\phi}$ then $P y=y$ and $\phi(x P)=\phi(x) P=\phi(x) P_{\phi} P=0$ thus since $\phi$ is arbitrary in a space containing the dual of the space of $x, x P=0$ and thus $x \otimes_{D^{o p}} y=0$; thus we get the first claimed injectivity.

The agreement of intersections spaces comes from the fact that the intersection space of $L^{1}$ and $L^{\infty}$ can be reduced to equality when compressed by rank 1 projections coming from elements in a fixed right-module basis. Then the agreement corresponds in the second picture to agreement when evaluating at this fixed basis (and evaluating by duality at this basis too).
A.3.2. Wick's formula. We will also need a straightforward tensor variant of Wick's formula. For the scalar version of Wick's formula for expectations in free probability, the most standard version is [MS, Def. 6 p 41]. We also have in mind its extension to describe ordinary product of Wick words (a.k.a Wick products), see e.g. in the scalar case $[\mathbf{E P},(14)]$ (their formula (15) shows how this generalizes Wick's formula for expectations). For the operator-valued version, more relevant to this section, one can refer, for the basic case, to the more general operator-valued moment cumulant formula [MS, (9.16)] which reduces to Wick's formula when the only non-vanishing cumulant is $\kappa_{2}^{D}$. More precisely, using projections, we will focus on describing each term of the sum involved in a tensor variant of Wick's formula for the product of two Wick words. The focus will be on the extension to Haagerup tensor products of rather elementary formulas at the basic tensor level.

For $k=k_{1} \ldots k_{|k|}, m=m_{1} \ldots m_{|m|}$ words in $\kappa$ letters, we write $k \circ m=k_{1} \ldots k_{|k|} m_{1} \ldots m_{|m|}$ for the concatenation, and also $k \circ_{i} m=$ $k_{1} \ldots k_{|k|-i} m_{1+i \ldots} \ldots m_{|m|},|k| \wedge|m| \geq i \geq 0$ (defined only if the last $i$ letters of $k$ and the first $i$ letters of $m$ form identical words). Note that $\left|k \circ_{i} m\right|=|k|+|m|-2 i$. We also write $\bar{k}=k_{|k|} \ldots k_{1}$. Sometimes, we will need to emphasize the following
isomorphism:

$$
\begin{aligned}
\iota_{m_{1}, m_{2}, l_{1}, l_{2}}: & B\left(M: D, m_{1} m_{2}, l_{1} l_{2}\right) \simeq\left(L^{2}(M)^{\otimes D l_{1} l_{2}}\right)_{L^{2}(D)} \stackrel{\text { eh }}{\stackrel{\text { eh }}{D}} L^{2}(D)\left(L^{2}(M)^{\otimes_{D} m_{1} m_{2} *}\right) \\
& \simeq\left(L^{2}(M)^{\otimes D\left|l_{1}\right|}\right)_{L^{2}(D)}{\underset{D}{\text { eh }}}_{\otimes}^{\otimes\left(M: D, m_{2}, l_{2}\right)} \stackrel{\text { eh }}{D}_{\otimes}^{L^{2}(D)}\left(L^{2}(M)^{*}\right)^{\otimes_{D}\left|\overline{m_{1}}\right|}
\end{aligned}
$$

given by $\iota_{m_{1}, m_{2}, l_{1}, l_{2}}\left(\xi_{1} \otimes_{D} \ldots \otimes_{D} \xi_{\left|l_{1}\right|+\left|l_{2}\right|+1}\right) \otimes_{D} \overline{\left(\eta_{1} \otimes_{D} \ldots \otimes_{D} \eta_{\left|m_{1}\right|+\left|m_{2}\right|+1}\right)}=\xi_{1} \otimes_{D}$ $\ldots \otimes_{D} \xi_{\left|l_{1}\right|} \otimes_{D}\left(\xi_{\left|l_{1}\right|+1} \otimes_{D} \ldots \otimes_{D} \xi_{\left|l_{1}\right|}\right) \otimes_{D} \overline{\left(\eta_{\left|m_{1}\right|+1} \otimes_{D} \ldots \otimes_{D} \eta_{\left|m_{1}\right|+\left|m_{2}\right|+1}\right)} \otimes_{D} \overline{\eta_{\left|m_{1}\right|}} \otimes_{D}$ $\ldots \otimes_{D} \overline{\eta_{1}}$.

Likewise, we have :

$$
\begin{aligned}
& \hat{\iota}_{m_{1}, m_{2}, l_{1}, l_{2}}: \mathscr{T} \mathscr{C}\left(M: D, m_{1} m_{2}, l_{1} l_{2}\right) \simeq\left(L^{2}(M)^{\otimes D m_{1} m_{2} *}\right) \stackrel{\text { Dop }}{\stackrel{\text { eh }}{\otimes}}\left(L^{2}(M)^{\otimes D l_{1} l_{2}}\right)
\end{aligned}
$$

given by

$$
\begin{aligned}
& \hat{\iota}_{m_{1}, m_{2}, l_{1}, l_{2}} \overline{\left(\eta_{1} \otimes_{D} \ldots \otimes_{D} \eta_{\left|m_{1}\right|+\left|m_{2}\right|+1}\right)} \otimes_{D^{o p}}\left(\xi_{1} \otimes_{D} \ldots \otimes_{D} \xi_{\left|l_{1}\right|+\left|l_{2}\right|+1}\right) \\
& =\overline{\left(\eta_{\left|m_{1}\right|+1} \otimes_{D} \ldots \otimes_{D} \eta_{\left|m_{1}\right|+\left|m_{2}\right|+1}\right)} \otimes_{D} \\
& \left(\overline{\eta_{\left|m_{1}\right|}} \otimes_{D} \ldots \otimes_{D} \overline{\eta_{1}}\right) \otimes_{D^{o p}}\left(\xi_{1} \otimes_{D} \ldots \otimes_{D} \xi_{\left|l_{1}\right|}\right) \otimes_{D}\left(\xi_{\left|l_{1}\right|+1} \otimes_{D} \ldots \otimes_{D} \xi_{\left|l_{1}\right|+\left|l_{2}\right|+1}\right) .
\end{aligned}
$$

Lemma A.22. Let $X \in\left\langle N_{\kappa}, e_{D}\right\rangle, Y \in L^{1}\left(\left\langle N_{\kappa}, e_{D}\right\rangle\right), k, l, m, n, p, q$ words in $\kappa$


If we consider $P_{m} X P_{n}^{*} \in B(M: D, n, m) \cap \mathscr{T} \mathscr{C}(M: D, n, m)$, we have
and $P_{p}\left[V \#\left(P_{m} X P_{n}^{*}\right)\right] P_{q}^{*}=0$ for either $|q|>|n|+|l|$ or $|q|<|n|+|l|-2(|l| \wedge|n|)$ or $|p|<|m|+|k|-2(|k| \wedge|m|)$ or $|p|>|m|+|k|$.

Moreover, if we consider the canonical map
extending:

$$
\begin{aligned}
\left.m_{\infty}^{\left(|k|, k o k^{\prime},|l|, \mid l l^{\prime}\right)}\right) & \left(m_{1} \otimes \cdots m_{|k|} \otimes \xi_{|k|+1} \otimes \xi_{|k|} \otimes \cdots \otimes \xi_{1} \otimes \xi_{|k|+2} \otimes \cdots \otimes \xi_{|k|+\left|k^{\prime}\right|+1}\right. \\
& \left.\otimes \overline{\eta_{|l|+1} \otimes \eta_{|l|} \otimes \cdots \otimes \eta_{1} \otimes \eta_{|l|+2} \otimes \cdots \otimes \eta_{|l|+\left|l^{\prime}\right|+1} \otimes \overline{n_{|l|}} \otimes \cdots \otimes \bar{n}_{1}}\right) \\
& =m_{1} E_{D}\left(m_{2} \cdots E_{D}\left(m_{|k|} E_{D}\left(\xi_{|k|+1}\right) \xi_{|k|}\right) \cdots \xi_{2} \xi_{1} \otimes \xi_{|k|+2} \otimes \cdots \otimes \xi_{|k|+\left|k^{\prime}\right|+1}\right. \\
& \otimes \overline{n_{1} E_{D}\left(n_{2} \cdots E_{D}\left(n_{|l|} E_{D}\left(\eta_{|l|+1}\right) \eta_{|l|}\right) \cdots \eta_{2}\right) \eta_{1} \otimes \eta_{|l|+2} \otimes \cdots \otimes \eta_{|l|+\left|l^{\prime}\right|+1}}
\end{aligned}
$$

for $|k|,|l| \geq 0$, (by convention $m_{\infty}^{\left(0, k^{\prime}, 0, l^{\prime}\right)}=I d$ ) then we have the relation for $P \in$ $\llbracket 0,|k| \wedge|m| \rrbracket, Q \in \llbracket 0,|l| \wedge|n| \rrbracket:$
$\iota \overline{l_{[Q+1,|l|]}, n_{[Q+1,|n|]},\left.k\right|_{[1,|k|-P]}, m_{[P+1,|m|]}}\left(P_{k_{\circ_{P} m}}\left[V \#\left(P_{m} X P_{n}^{*}\right)\right] P_{\bar{l}_{Q} n}^{*}\right)=\prod_{i=1}^{P} 1_{k_{|k|-(i-1)}=m_{i}} \times$
$\times \prod_{i=1}^{Q} 1_{l_{i}=n_{i}}\left[1^{\otimes|k|-P} \otimes m_{\infty}^{(P, m, Q, n)} \otimes 1^{\otimes|l|-Q}\right]_{\bar{l}, n, k, m}\left(P_{k \circ m}\left[V \#\left(P_{m} X P_{n}^{*}\right)\right] P_{\bar{l} \circ n}^{*}\right)$.
Likewise we have:

$$
\begin{aligned}
& \left.\hat{\iota}_{\bar{k}, n, l, m}\left(\overline{P_{\bar{k} \circ n}} \otimes_{D^{o p}} P_{l o m}\right)\left[\left(\overline{P_{n}} \otimes_{D^{o p}} P_{m}\right)\right](Y) \# V\right]
\end{aligned}
$$

and $\left.\left(\overline{P_{q}} \otimes_{\text {Dop }^{o p}} P_{p}\right)\left[\left(\overline{P_{n}} \otimes_{D^{o p}} P_{m}\right)\right](Y) \# V\right]=0$ for $|q|>|n|+|k|$ or $|q|<|n|+|k|-$ $2(|k| \wedge|n|)$ or $|p|<|m|+|l|-2(|l| \wedge|m|)$ or $|p|>|m|+|l|$. Moreover there is a canonical map

$$
\begin{aligned}
& \rightarrow \mathscr{T} \mathscr{C}\left(M: D, k \circ_{Q} n, l \circ_{P} m\right),
\end{aligned}
$$

given on elementary tensors by:
$m_{1}^{(|l|, P, m,|k|, Q, n)}\left(\overline{\eta_{|k|+1} \otimes \eta_{|k|} \otimes \cdots \otimes \eta_{1} \otimes \eta_{|k|+2} \otimes \cdots \otimes \eta_{|n|+1}}\right.$
$\left.\left.\otimes \overline{n_{|k|}} \otimes \cdots \otimes \overline{n_{1}}\right) \otimes\left(m_{1} \otimes \cdots m_{|l|} \otimes \xi_{|l|+1} \otimes \xi_{|l|} \otimes \cdots \otimes \xi_{1} \otimes \xi_{|l|+2} \otimes \cdots \otimes \xi_{|m|+1}\right)\right)=$ $\left[\overline{n_{1} \otimes \cdots \otimes n_{|l|-Q+1} E_{D}\left(n_{|l|-Q+1} \cdots E_{D}\left(n_{|l|} E_{D}\left(\eta_{|l|+1}\right) \eta_{|l|}\right) \cdots \eta_{|l|-Q+2}\right) \eta_{|l|-Q+1}}\right.$

$$
\overline{\otimes \cdots \otimes \eta_{1} \otimes \eta_{|l|+2} \otimes \cdots}
$$

$\otimes\left[\left(m_{1} \otimes \cdots m_{|k|-P} \otimes m_{|k|-P+1} E_{D}\left(m_{|k|-P+2} \cdots E_{D}\left(m_{|k|} E_{D}\left(\xi_{|k|+1}\right) \xi_{|k|}\right) \cdots \xi_{|k|-P+2}\right) \xi_{|k|-P+1}\right.\right.$
$\left.\otimes \xi_{|k|-P} \otimes \cdots \otimes \xi_{1} \otimes \xi_{|k|+2} \otimes \cdots \otimes \xi_{|k|+\left|k^{\prime}\right|+1}\right]$.
These maps satisfy:

when restricted to the intersection of their domain viewed as a subset of $B(M$ : $D, \bar{l} \circ n, k \circ m)+\mathscr{T} \mathscr{C}(M: D, \bar{l} \circ n, k \circ m)$. For $P \in \llbracket 0,|l| \wedge|m| \rrbracket, Q \in \llbracket 0,|k| \wedge|n| \rrbracket:$

$$
\begin{align*}
& \left.\left(\overline{P_{\bar{k} \bigcirc_{Q} n}} \otimes_{D^{o p}} P_{l \circ_{P} m}\right)\left[\left(\overline{P_{n}} \otimes_{D^{o p}} P_{m}\right)\right](Y) \# V\right]=\prod_{i=1}^{Q} 1_{k_{i}=n_{i}} \prod_{i=1}^{P} 1_{l_{|l|-(i-1)}=m_{i}} \times  \tag{38}\\
& \left.\quad \times m_{1}^{(|l|, P, m,|k|, Q, n)} \hat{\iota}_{\bar{k}, n, l, m}\left(\left(\overline{P_{\bar{k} \circ n}} \otimes_{D^{o p}} P_{l \circ m}\right)\left[\left(\overline{P_{n}} \otimes_{D^{o p}} P_{m}\right)\right](Y) \# V\right]\right) .
\end{align*}
$$

Proof. The definition of the map $m_{\infty}^{\left(|k|, k \circ k^{\prime},|l|, l o l^{\prime}\right)}$ and its weak-* continuity in the variable $B\left(M: D, l \circ l^{\prime}, k \circ k^{\prime}\right)$ are easy. Thus one can assume $X \in$ $[\operatorname{Alg}(S, M)] e_{D}[\operatorname{Alg}(S, M)]$. Then using canonical forms for the extended Haagerup tensor product and strong convergence of corresponding finite sums, we are reduced to the case where $V$ is a finite sum. For finite tensors, the relation reduces to
the usual Wick formula. The second part of the statement is similar using norminstead of weak-* density.

What really matters for us in the previous result is that the highest component of the product is a tensor product, while the remaining terms are then determined by applying multiplication and conditional expectations to its various components. For convenience for words $m, n$ and $k \leq|m|$, we write :

$$
\begin{aligned}
m \#_{K} n & =m_{1} \ldots m_{K-1} n_{1} \ldots n_{|n|} m_{K+1} \ldots m_{|m|} \\
m \hat{\#}_{K} n & =m_{1} \ldots m_{K} n_{1} \ldots n_{|n|} m_{K+1} \ldots m_{|m|}
\end{aligned}
$$

A.3.3. Flips and cyclic permutations. We start by interpreting a cyclic permutation $\sigma=(l+2, l+3, \ldots l+k+2,1,2, \ldots, l+1)$ in $\mathfrak{C}_{n}, n=l+k+2$, as the flip (i.e., period two permutation) of the blocks $\llbracket l+2, \ldots, l+k+2 \rrbracket$ and $\llbracket 1, \ldots, l+1 \rrbracket$. We mimic this point of view in terms of injections in our free product von Neumann algebra $N_{\kappa}$. We thus make use of our results on the two-fold cyclic Haagerup tensor product in this context to construct a suitable intersection space, using which we then construct the $n$-fold cyclic Haagerup tensor product.

Proposition A.23. Let $D \subset M$ finite von Neumann algebras and $N=N_{\kappa}=$ $M *_{D}\left(D \otimes W^{*}\left(S_{1}, \ldots, S_{\kappa}\right)\right)$. We assume $\kappa$ infinite $k, l$ words in $\kappa$ letters.

Let $\sigma \in \mathfrak{C}_{n}$ be a cyclic permutation as above, $n=|k|+|l|+2, \sigma(1)=|l|+2$. Using $\sigma_{i}$ of Theorem A. 17 for $D \subset N_{\kappa}$ we have two inclusions $I_{1}(\sigma)=\sigma_{1} \circ\left(\iota_{k} \stackrel{\text { eh }}{\stackrel{\otimes}{D} \iota_{l}}\right), I_{2}(\sigma)=$ $\sigma_{2} \circ\left(\iota_{l} \stackrel{\mathrm{eh}}{\otimes} \iota_{D}\right)$

$$
I_{i}(\sigma): D^{\prime} \cap M_{D}^{\stackrel{\mathrm{eb}}{\otimes} n} \rightarrow B\left(D^{\prime} \cap\left\langle N, e_{D}\right\rangle \cap L^{1}\left(\left\langle N, e_{D}\right\rangle\right), D^{\prime} \cap\left(\left\langle N, e_{D}\right\rangle+L^{1}\left(\left\langle N, e_{D}\right\rangle\right)\right)\right.
$$

The intersection space in the sense of interpolation of these inclusions, written $M^{\stackrel{\text { eh }}{\otimes}(k \circ l, \sigma)}=M^{\stackrel{\text { eh }}{\otimes(k, l)}}$, has a change of inclusion $I(\sigma)=I_{2}\left(\sigma^{-1}\right) \circ I_{1}(\sigma)^{-1}$ :

 $N C B\left(\left(D^{\prime}\right)^{n-1}, B\left(L^{2}(M)\right)\right.$ given by $U^{\star}\left(X_{1}, \ldots, X_{n-1}\right)=U\left(X_{n-1}^{*}, \ldots, X_{1}^{*}\right)^{*}$ extending $\left(x_{1} \otimes_{D} \cdots \otimes_{D} x_{n}\right)^{\star}=\left(x_{n}^{*} \otimes_{D} \cdots \otimes_{D} x_{1}^{*}\right)$ sends $M^{\substack{\mathrm{eh} \\ \otimes \\ D}}(k \circ l, \sigma)$ to $M^{\stackrel{\mathrm{eh}}{\otimes}\left(l o k, \sigma^{-1}\right)}$.

The product $. \#_{K}: M^{\stackrel{\text { eh }}{\otimes}|n|+2} \times\left(D^{\prime} \cap M_{D}^{\stackrel{\text { eh }}{\otimes}|m|+1}\right) \rightarrow M_{D}^{\stackrel{\text { eh }}{D}(|n|+|m|+1)}$ for $K \in \llbracket 1,|n|+$ 1], induced by the composition in the $K$-th entry of $N C B\left(\left(D^{\prime}\right)^{|n|+1}\right.$
$N C B\left(\left(D^{\prime}\right)^{|n|+1}, B\left(L^{2}(M)\right) \times N C B\left(\left(D^{\prime}\right)^{|m|}, D^{\prime} \cap B\left(L^{2}(M)\right)\right) \rightarrow N C B\left(\left(D^{\prime}\right)^{|n|+|m|}, B\left(L^{2}(M)\right)\right.\right.$
corresponds on tensors to the map $\left(x_{1} \otimes_{D} \cdots \otimes_{D} x_{|n|+2}\right) \#_{K}\left(y_{1} \otimes_{D} \cdots \otimes_{D} y_{|m|+1}\right)=$ $x_{1} \otimes_{D} \cdots \otimes_{D} x_{K} y_{1} \otimes_{D} y_{2} \otimes_{D} \cdots \otimes_{D} y_{|m|+1} x_{K+1} \otimes_{D} \cdots \otimes_{D} x_{|n|+2}$. The product is separately weak-* continuous on bounded sets in each variable and has the following stability properties:

- If $\sigma \in \mathfrak{C}_{|n|+2}, \tau \in \mathfrak{C}_{|n|+\left|n^{\prime}\right|+1} \sigma(1)=|n|-k^{\prime}+2, \tau(1)=|n|+\left|n^{\prime}\right|+1-k^{\prime}$, $k^{\prime}<K-1$, then for any $U \in M^{\stackrel{\text { eh }}{\otimes}(n, \sigma)}, V \in D^{\prime} \cap M_{D}^{\stackrel{\text { eh }}{\otimes}\left(\left|n^{\prime}\right|+1\right)}$ we have $U \#_{K} V \in$ $M^{\stackrel{\text { eh }}{\otimes}\left(n \#{ }_{K} n^{\prime}, \tau\right)}$,
- If $\sigma \in \mathfrak{C}_{|n|+2}, \tau \in \mathfrak{C}_{|n|+\left|n^{\prime}\right|+1} \sigma(1)=|n|-k^{\prime}+2=\tau(1), k^{\prime} \geq K$, then for any

- If $\sigma \in \mathfrak{C}_{|n|+2}, \rho \in \mathfrak{C}_{\left|n^{\prime}\right|+2}, \tau \in \mathfrak{C}_{|n|+\left|n^{\prime}\right|+2} \sigma(1)=|n|-K+3, \rho(1)=\left|n^{\prime}\right|-k^{\prime}+2$ $\tau(1)=|n|+\left|n^{\prime}\right|-K-k^{\prime}+3, k^{\prime} \in \llbracket 1,\left|n^{\prime}\right|-1 \rrbracket$, then for any $U \in M^{\substack{\text { eh } \\ \stackrel{\otimes}{D}(n, \sigma)}}, V \in$ $M^{\substack{\text { eh } \\ \stackrel{\otimes}{\otimes}\left(n^{\prime}, \rho\right)}}$ we have $U \#_{K} V \in M_{{ }_{D}^{\text {eh }}(n \hat{\#}}^{\left.{ }^{\otimes} n^{\prime}, \tau\right)}$.
Similarly, the map $M^{\substack{\text { eh } \\ \otimes} n \mid+1} \times\left(M^{\stackrel{\text { eh }}{\otimes}|m|+1}\right) \rightarrow M^{\substack{\text { eh }}}{ }_{D}^{(|n|+|m|+1)}$ induced by the product in $B\left(L^{2}(M)\right)$
$N C B\left(\left(D^{\prime}\right)^{|n|}, B\left(L^{2}(M)\right) \times N C B\left(\left(D^{\prime}\right)^{|m|}, B\left(L^{2}(M)\right)\right) \rightarrow N C B\left(\left(D^{\prime}\right)^{|n|+|m|}, B\left(L^{2}(M)\right)\right.\right.$ and corresponds on tensors to the map $\left(x_{1} \otimes_{D} \cdots \otimes_{D} x_{|n|+1}\right)\left(y_{1} \otimes_{D} \cdots \otimes_{D} y_{|m|+1}\right)=$ $x_{1} \otimes_{D} \cdots \otimes_{D} x_{|n|+1} y_{1} \otimes_{D} y_{2} \otimes_{D} \cdots \otimes_{D} y_{|m|+1}$. It has the following stability properties:
- If $\sigma \in \mathfrak{C}_{|n|+2}, \tau \in \mathfrak{C}_{|n|+|m|+2} \sigma(1)=|n|-k^{\prime}+2, \tau(1)=|n|+|m|+2-k^{\prime}$,

- If $\sigma \in \mathfrak{C}_{|m|+2}, \tau \in \mathfrak{C}_{|n|+|m|+2} \sigma(1)=|m|-k^{\prime}+2=\tau(1)$, then for any

$$
V \in M_{D}^{\stackrel{\text { eh }}{\otimes}(m, \sigma)}, U \in D^{\prime} \cap M_{D}^{\text {eht }}{ }_{D}^{\stackrel{\text { en }}{ }} \text { we have } U V \in M_{D}^{\stackrel{\text { eh }}{\otimes}(n m, \tau)} \text {. }
$$

Proof. (i) For the first statement, we only have to prove that $I_{2}\left(\sigma^{-1}\right) \circ I_{1}(\sigma)^{-1}=$ $I_{1}\left(\sigma^{-1}\right) \circ I_{2}(\sigma)^{-1}$. In this it becomes clear that the image of $I(\sigma)$ is indeed $M^{\stackrel{\text { eh }}{\otimes}\left(l o k, \sigma^{-1}\right)}$ and that $I(\sigma)^{-1}=I\left(\sigma^{-1}\right)$. Take $X \in M^{\stackrel{\text { eh }}{\otimes, c}(k, l)}$ We know there is

 $V^{\prime}=\sigma_{2}^{-1}(X)$. Then by definition

$$
I_{2}\left(\sigma^{-1}\right) \circ I_{1}(\sigma)^{-1}(X)=\sigma_{2}\left(U^{\prime}\right)=\sigma(X)=\sigma_{1}\left(\sigma_{2}^{-1}(X)\right)=I_{1}\left(\sigma^{-1}\right) \circ I_{2}(\sigma)^{-1}(X)
$$

using in the middle the key relation proved in Theorem A.17.(1) and then the definition of our maps $I_{i}$.
(ii) For the statement about the adjoint, one uses

$$
\left[\left(\iota_{k} \stackrel{\mathrm{eh}}{\otimes} \iota_{D} \iota_{l}\right)(U)\right]^{\star}=\left[\left(\iota_{l} \stackrel{\mathrm{eh}}{\underset{D}{\otimes} \iota_{k}}\right)\left(U^{\star}\right)\right]
$$

and our previous results in Theorems A. 17 and Theorem A.19.(1) to deduce:

$$
I(\sigma)\left(U^{\star}\right)=\left[I\left(\sigma^{-1}\right)(U)\right]^{\star} .
$$

(iii) For the weak-* continuity of composition products, take bounded nets $U_{n} \rightarrow$ $U, V_{\nu} \rightarrow V$. By weak-* precompactness of $U_{n} \#_{K} V, U \#{ }_{K} V_{\nu}$, it suffices to show that they converge weakly in $L^{2}(M)^{\otimes_{D}(|n|+|m|+1)}$ to $U \#_{K} V$. By density it is enough
to check convergence dually against any $Z \in M_{D^{\text {eh }}}^{\substack{\text { en }}}(|n|+|m|+1)$. Take any word $o$ of length $|o|=|m|-1$. We claim that $\left(\iota_{\epsilon} \otimes_{D} \iota_{o}\right)\left(V_{\nu}-V\right) \rightarrow 0$ weak-* in $N \stackrel{\text { eh }}{\underset{D}{\otimes}} N$. This is obvious again by the isometric embedding at $L^{2}$ level and since it suffices to check weak convergence in $L^{2}(N) \otimes_{D} L^{2}(N)$. Take similarly $n=k l,|k|=K-1$, then $\left(\iota_{k} \otimes_{D} \iota_{l}\right)\left(U_{n}-U\right) \rightarrow 0$. From the result in Theorem A.19.(2),

$$
\begin{aligned}
& {\left[\left(\iota_{k} \otimes_{D} \iota_{l}\right)\left(U_{n}\right)\right] \#\left[\left(\iota_{\epsilon} \otimes_{D} \iota_{o}\right)(V)\right] \rightarrow\left[\left(\iota_{k} \otimes_{D} \iota_{l}\right)(U)\right] \#\left[\left(\iota_{\epsilon} \otimes_{D} \iota_{o}\right)(V)\right],} \\
& {\left[\left(\iota_{k} \otimes_{D} \iota_{l}\right)(U)\right] \#\left[\left(\iota_{\epsilon} \otimes_{D} \iota_{o}\right)\left(V_{\nu}\right)\right] \rightarrow\left[\left(\iota_{k} \otimes_{D} \iota_{l}\right)(U)\right] \#\left[\left(\iota_{\epsilon} \otimes_{D} \iota_{o}\right)(V)\right],}
\end{aligned}
$$

in $N^{\substack{\mathrm{eh} \\ \otimes_{2} 2}}$. Since from the computation below coming from Lemma 37

$$
\left\langle Z, U \#{ }_{K} V\right\rangle=\left\langle\left(\iota_{k \epsilon} \otimes_{D} \iota_{o l}\right)(Z) \# e_{D},\left[\left(\iota_{k} \otimes_{D} \iota_{l}\right)(U)\right] \#\left[\left(\iota_{\epsilon} \otimes_{D} \iota_{o}\right)(V)\right]\right\rangle
$$

we get the weak convergence by duality against $\left(\iota_{k \epsilon} \otimes_{D} \iota_{o l}\right)(Z) \# e_{D}$.
(iv) For the stability of composition products, consider first the situation of the third
 $\left|k_{1}\right|=K-1,\left|k_{2}\right|=k^{\prime}$ and consider $U^{\prime}=I_{2}(\sigma)^{-1} I_{1}(\sigma)(U), V^{\prime}=I_{2}(\rho)^{-1} I_{1}(\rho)(V)$. But from the definitions, one easily gets for $X \in\left\langle N, e_{D}\right\rangle \cap L^{1}\left(\left\langle N, e_{D}\right\rangle\right)$ :

$$
\begin{aligned}
P_{k_{1} \circ k_{2} \circ m} & \left(\left[\iota_{k_{1} k_{2}} \otimes_{D} \iota_{l_{2} l_{1}}\left(U \# \#_{K} V\right)\right] \#\left(P_{m} X P_{l}^{*}\right)\right) P_{\overline{l_{2} \circ l_{1}} \circ l}^{*} \\
& =P_{k_{1} \circ k_{2} \circ m}\left(\left[\iota_{k_{1}} \otimes_{D} \iota_{l_{1}}(U)\right] \#\left[\iota_{k_{2}} \otimes_{D} \iota_{l_{2}}(V)\right] \#\left(P_{m} X P_{l}^{*}\right)\right) P_{l_{2} \circ l_{1} \circ l}^{*} .
\end{aligned}
$$

and similarly :

$$
\begin{aligned}
& \left(\overline{P_{l_{2} \circ l_{1} \circ l}} \otimes_{D^{o p}} P_{k_{1} \circ k_{2} \circ m}\right)\left([ ( \overline { P _ { l } } \otimes _ { D ^ { o p } } P _ { m } ) ] ( X ) \# \left[\iota _ { l _ { 2 } l _ { 1 } } \otimes _ { D } \iota _ { k _ { 1 } k _ { 2 } } \left(V^{\prime} \#\left|n^{\prime}\right|+1-k^{\prime}\right.\right.\right. \\
& \left.\left.\left.U^{\prime}\right)\right]\right) \\
& =\left(\overline{P_{\overline{l_{2} \circ l_{1} \circ l}}} \otimes_{D^{o p}} P_{k_{1} \circ k_{2} \circ m}\right)\left(\left[\left(\overline{P_{l}} \otimes_{D^{o p}} P_{m}\right)\right](X) \#\left[\iota_{l_{2}} \otimes_{D} \iota_{k_{2}}\left(V^{\prime}\right)\right] \#\left[\iota_{l_{1}} \otimes_{D} \iota_{k_{1}}\left(U^{\prime}\right)\right]\right)
\end{aligned}
$$

From the assumptions on $U$ and $V$ the two second lines are equal, and then, from (37) and (38), one deduces the conclusion we wanted, for all $p, q$ :

$$
\begin{aligned}
& P_{p}\left(\left[\iota_{k_{1} \circ k_{2}} \otimes_{D} \iota_{l_{2} \circ l_{1}}\left(U \#_{K} V\right)\right] \#\left(P_{m} X P_{l}^{*}\right)\right) P_{q}^{*} \\
& \quad=\left(\overline{P_{q}} \otimes_{D^{o p}} P_{p}\right)\left(\left[\left(\overline{P_{l}} \otimes_{D^{o p}} P_{m}\right)\right](X) \#\left[\iota_{l_{2} l_{1}} \otimes_{D} \iota_{k_{1} k_{2}}\left(V^{\prime} \#\left|n^{\prime}\right|+1-k^{\prime} U^{\prime}\right)\right]\right),
\end{aligned}
$$

which, using Lemma A.21.(1), implies our statement and :

$$
I_{2}(\tau)^{-1} I_{1}(\tau)\left(U \#_{K} V\right)=V^{\prime} \#_{\left|n^{\prime}\right|+1-k^{\prime}} U^{\prime}
$$

The other statements about composition product and product are similar, the first statement in each case always following from the second using the stability by adjoint proved before. We give a few details concerning the second point for the composition product.
 and let $U^{\prime}=I_{2}(\sigma)^{-1} I_{1}(\sigma)(U)$. Note that $n \#_{K}\left(n^{\prime}\right)=\left[k_{1} \#_{K}\left(n^{\prime}\right)\right] \circ l_{1}$. As before it suffices to prove:

$$
\left.\left.\left.\begin{array}{l}
P_{\left[k_{1} \#_{K}\left(n^{\prime}\right)\right] \circ m}\left(\left[\iota_{k_{1}} \#_{K}\left(n^{\prime}\right) \otimes_{D} \iota_{l_{1}}\left(U \#_{K} V\right)\right] \#\left(P_{m} X P_{l}^{*}\right)\right) P_{\overline{l_{1}} \circ l}^{*} \\
=\left(\overline{P_{\overline{l_{1} \circ l}}} \otimes_{D^{o p}} P_{\left[k_{1} \#_{K}\left(n^{\prime}\right)\right] \circ m}\right)\left([ ( P _ { l } \otimes _ { D ^ { o p } } P _ { m } ) ] ( X ) \# \left[\iota _ { l _ { 1 } } \otimes _ { D } \iota _ { k _ { 1 } } \# _ { K } ( n ^ { \prime } ) \left(U^{\prime} \#|n|+2-K\right.\right.\right.
\end{array}\right)\right]\right), ~ \$
$$

But now, by assumption, we know:

$$
\begin{aligned}
& P_{k_{1} \circ m}\left(\left[\iota_{l_{1}} \otimes_{D} \iota_{k_{1}} U\right] \#\left(P_{m} X P_{l}^{*}\right)\right) P_{\overline{l_{1} \circ l}}^{*} \\
& =\left(\overline{P_{\overline{l_{1} \circ l}}} \otimes_{D^{o p}} P_{k_{1} \circ m}\right)\left(\left[\left(P_{l} \otimes_{D^{o p}} P_{m}\right)\right](X) \#\left[\iota_{l_{1}} \otimes_{D} \iota_{k_{1}} U^{\prime}\right]\right),
\end{aligned}
$$

Moreover, by Lemma A. 22 the left and right-hand sides are valued respectively in
 $\left.\left.\left.\bar{M}^{\stackrel{\text { eh }}{\otimes}\left|l_{1}\right|}\right) \stackrel{\underset{D^{o p}}{\otimes}}{\stackrel{\text { eh }}{\otimes}}\left(M_{D}^{\stackrel{e h}{\otimes}\left|k_{1}\right|} \stackrel{\text { eh }}{\otimes} L_{D}^{2}(M)^{\otimes_{D} m}\right)\right)\right]$. By Lemma A.21.(2), it suffices to see that the two elements we wish to prove equal in $B\left(L^{2}(M)^{\otimes_{D} \overline{l_{1}} \circ l}, L^{1}(D) \otimes_{h D^{o p}}\right.$ $\left.\left.L^{2}(M)^{\otimes_{D}\left[k_{1} \# K\right.}\left(n^{\prime}\right)\right] \circ m\right)_{D}$ have the same value on any $\xi \in L^{2}(M)^{\otimes_{D} \overline{l_{1} \circ l} .}$

Since $P_{k_{1} \circ m}\left(\left[\iota_{l_{1}} \otimes_{D} \iota_{k_{1}} U\right] \#\left(P_{m} X P_{l}^{*}\right)\right) P_{\bar{l}_{1} \circ l}^{*}(\xi) \in L^{2}(D) \otimes_{h D^{o p}}\left(M_{D}^{\stackrel{\text { eh }}{\otimes}\left|k_{1}\right|} \stackrel{\text { eh }}{\stackrel{\otimes}{D}} \stackrel{D}{\otimes_{D}}\right.$ $L^{2}(M)^{\otimes_{D} m}$ ) the equality we want can be obtained from the one we know by applying the multiplication $\# V$ which is well defined on the appropriate extended Haagerup tensor powers of $M$ in the range of our maps.

The reader should note that in this case, we actually proved

$$
I_{2}(\tau)^{-1} I_{1}(\tau)\left(U \#_{K} V\right)=U^{\prime} \#_{|n|+2-K} V
$$

A.3.4. Cyclic Haagerup tensor products: the general case. We are now ready to introduce our cyclic extended Haagerup tensor product as an intersection space with enough compatibility condition to have a cyclic group action on it. Once those cyclic group actions are obtained, our various products and actions leave stable our intersection space as expected. We also obtain a density result saying that our spaces are non-trivial as soon as $D^{\prime} \cap L^{2}(M)^{\otimes_{D} n}$ are. We also obtain traciality and functoriality results crucial to build later evaluations maps.

Proposition A.24. Let $D \subset M$ finite von Neumann algebras and $N_{\kappa}=M *_{D}$ $\left(D \otimes W^{*}\left(S_{1}, \ldots, S_{\kappa}\right)\right), \kappa$ infinite. We write $n$ a generic word in $\kappa$ letters of length $N$. Let $M^{\otimes_{\text {ehscD }}(N+2)}$ the intersection space of
for $\sigma \in \mathfrak{C}_{N+2}$, completely isometrically included via $I=\bigoplus_{n,|n|=N}(I d \oplus$ $\left.(J(\sigma, n))_{\sigma \in\left(\mathfrak{C}_{n}-\{I d\}\right)}\right)$ into $\left(D^{\prime} \cap M^{\substack{\text { eh } \\ \otimes}}{ }^{(N+2)}\right)^{\oplus\left(\mathfrak{C}_{N+2} \times \kappa^{N}\right)}$, (with operator space direct sum norm) and write $J(I d)=I d, J(\sigma, n)=I_{1}\left(\sigma^{-1}, \sigma . n\right)^{-1} \circ I_{2}\left(\sigma^{-1}, \sigma . n\right)$, with $I_{i}$ associated to $n$. This intersection space is independent of $\kappa$ infinite.

Consider $\quad M^{\otimes_{e h S c D} N+2}=\left(\bigcap_{n \neq m,|n|=|m|=N} \operatorname{Ker}(J(\sigma, n)-J(\sigma, m))\right) \subset$ $M^{\otimes_{e h s c D} N+2}$ and on $\left(M^{\otimes_{e h S c D} n}\right)^{\mathfrak{C}_{N+2}}, P_{\sigma}$ the projection on the $\sigma$ component and
the maps $J\left(\sigma_{1}, \sigma_{2}\right)=J\left(\sigma_{1}\right) P_{\sigma_{2}, n}$, with $J(\sigma)=J(\sigma, n)$ for any $n$, and a corresponding I without repetition over $n$ and then define

$$
\begin{aligned}
M^{\substack{\text { eh } \\
\otimes, c, c}+2} & :=I^{-1}\left(\bigcap_{\left(\sigma_{1}, \sigma_{2}\right) \in \mathfrak{C}_{N+2}^{2}} \operatorname{Ker}\left(J\left(\sigma_{1}, \sigma_{2}\right)-J\left(I d, \sigma_{1} \sigma_{2}\right)\right)\right) \\
& \subset I^{-1}\left(\left(M^{\otimes_{e h S c D} N+2}\right)^{\mathfrak{C}_{N+2}}\right) \subset M^{\otimes_{e h s c D} N+2},
\end{aligned}
$$

with the induced norm, for which we have equality with the previous definition when $N=0$.
(1) For any $U \in M^{\otimes_{\text {ehscD }} N+2}, V \in M^{\otimes_{\text {ehscD }} M+2}$, we deduce $U^{\star} \in$ $M^{\otimes_{\text {ehscD }} N+2}, U \#_{i} V \in M^{\otimes_{\text {ehscD }} N+M+2}$ for all $i \in \llbracket 1, N+1 \rrbracket, U V \in$ $M^{\otimes_{e h s c D} N+M+3}$, and similarly for $s$ replaced by $S$.
Moreover the maps $J(\sigma)$ induce a continuous action of $\mathfrak{C}_{N+2}$ on $M^{\stackrel{\mathrm{eh}}{\otimes, c} N+2}$.

 $M_{D}^{\text {eh }} \stackrel{\otimes}{\otimes} N+2$ and dense in $D^{\prime} \cap L^{2}(M)^{\otimes_{D} N+2}$.
(2) Assume either that there exists a $D$-basis of $L^{2}(M)$ as a right $D$ module $\left(f_{i}\right)_{i \in I}$ which is also a D-basis of $L^{2}(M)$ as a left $D$ module or that $D$ is a $I I_{1}$ factor and that $L^{2}(M)$ is an extremal $D-D$ bimodule. Then, the linear map $J(\sigma)$ extends to an isometry on the subspace generated $D^{\prime} \cap L^{2}(M)^{\otimes_{D} n}$. As a consequence, $\tau(X)=\left\langle e_{D}, X \# e_{D}\right\rangle$ is a trace on $D^{\prime} \cap N_{\kappa}^{\stackrel{\mathrm{eh}}{\otimes_{2}} 2}$.
(3) [Partial fonctoriality] If $\phi_{1}: M^{\stackrel{\mathrm{eb}}{\otimes\left(n_{1}\right.}} \rightarrow N_{\kappa}, \ldots, \phi_{p}: M^{\stackrel{\mathrm{eh}}{\otimes} n_{p}} \rightarrow N_{\kappa}$ are multiplication maps to canonical semicircular variables in $N_{\kappa}$, then

$$
\phi_{1} \otimes_{D} \ldots \otimes_{D} \phi_{p}: M^{\stackrel{\text { eh }}{\otimes, c} n} \rightarrow \underset{N^{D, c}}{\substack{\text { eh } \\ \otimes, c, c}}
$$

is a completely bounded map with $n=\sum n_{i}$. In particular, in the degenerate

Moreover if $E: N_{\kappa} \rightarrow M$ is the canonical conditional expectation, $E^{\otimes_{D} p}$ :

Proof. The independence of the intersection space of $\kappa$ infinite is obvious since any equation to check can be reduced to a countably generated algebra, and thus to countably many $S_{i}$ as variables. The agreement with the previous definition in the case $N=0$ is easy from Lemma A.21.(2) and left to the reader.
(1) The stability of $M^{\otimes_{\text {ehscD }} n}$ by adjoint, composition product and product are
obvious from Proposition A.23. The stability of $M^{\substack{\text { eh } \\ D, c}}$. . . we (could have) got on $J(\tau)\left(U \#_{k} V\right), J\left(\sigma\left(U^{\star}\right)\right)$ in the proof in each case. We fix $n$ and first compute the inverse of $J(\sigma)=J(\sigma, n)=I_{1}\left(\sigma^{-1}\right)^{-1} \circ I_{2}\left(\sigma^{-1}\right)$ on $M^{\otimes_{\text {ehscD }} N+2}$. Note first that $J\left(\sigma^{-1}\right) J(\sigma)=I_{1}(\sigma)^{-1} \circ I_{2}(\sigma) I_{1}\left(\sigma^{-1}\right)^{-1} \circ I_{2}\left(\sigma^{-1}\right)=$ $I_{1}(\sigma)^{-1} I\left(\sigma^{-1}\right) I_{2}\left(\sigma^{-1}\right)$ so that $J\left(\sigma^{-1}\right) J(\sigma) I_{1}(\sigma)^{-1}=I_{1}(\sigma)^{-1} I\left(\sigma^{-1}\right) I(\sigma)=I_{1}(\sigma)^{-1}$
by (1) and since $I_{1}(\sigma)^{-1}$ is surjective, one gets $J\left(\sigma^{-1}\right) J(\sigma)=I d$ and likewise the converse to that $J(\sigma, n)^{-1}=J\left(\sigma^{-1}, \sigma . n\right)$.

By definition as an intersection, $(J(\sigma))$ defines an action on $M^{\substack{\text { eh } \\ D, c}}$ since on the intersection of kernels we exactly have $J\left(\sigma_{1}\right) J\left(\sigma_{2}\right)=J\left(\sigma_{1} \sigma_{2}\right)$.

It mostly remains to show the density results. For, we prove that for any $x_{1}, \ldots, x_{N+2} \in M$, then $E_{D^{\prime}}\left(x_{1} \otimes_{D} \ldots \otimes_{D} x_{N+2}\right) \in M^{\substack{\text { eh } \\ D, c}}, ~$. From the weak-* continuity on bounded sets of $E_{D^{\prime}}$, this implies the weak-* density. The $L^{2}$ density is easier. More precisely, we show that $E_{D^{\prime}}\left(x_{1} \otimes_{D} \ldots \otimes_{D} x_{N+2}\right) \in M^{\otimes_{e h s c D} N+2}$ and

$$
J(\sigma, n)\left(E_{D^{\prime}}\left(x_{1} \otimes_{D} \ldots \otimes_{D} x_{N+2}\right)\right)=E_{D^{\prime}}\left(x_{\sigma^{-1}(1)} \otimes_{D} \ldots \otimes_{D} x_{\sigma^{-1}(N+2)}\right)
$$

and on this formula one reads it is also in the intersection of kernels defining $M^{\substack{\mathrm{eh} \\ \mathrm{D}, c}}$.
Thus we can fix $\sigma \in \mathfrak{C}_{N+2}$ and $n=k l, \sigma(1)=|l|+2,|l|=N+1-|k|$. We have to show for any $X \in\left\langle N_{\kappa}, e_{D}\right\rangle \cap L^{1}\left(\left\langle N_{\kappa}, e_{D}\right\rangle\right)$ :
$\left(\iota_{k} \otimes_{D} \iota_{l}\left(E_{D^{\prime}}\left(x_{1} \otimes_{D} \ldots \otimes_{D} x_{N+2}\right)\right)\right) \# X=X \#\left(\iota_{l} \otimes_{D} \iota_{k}\left(E_{D^{\prime}}\left(x_{k+1} \otimes_{D} \ldots \otimes_{D} x_{k}\right)\right)\right)$.
This reduces to (35) if we show that

$$
\iota_{k} \otimes_{D} \iota_{l}\left(E_{D^{\prime}}\left(x_{1} \otimes_{D} \ldots \otimes_{D} x_{N+2}\right)\right)=E_{D^{\prime}}\left(\iota_{k} \otimes_{D} \iota_{l}\left(x_{1} \otimes_{D} \ldots \otimes_{D} x_{N+2}\right)\right)
$$

But we saw both sides can be further included in $L^{2}(M)^{\otimes D N+2}$ as a subspace with both $E_{D^{\prime}}$ agreeing with the projection there.
(2) From the action property in (1) on the dense set where $J(\sigma)$ is defined, it suffices to consider $\sigma$ a generator of the cyclic group. We thus extend $J(\sigma)$ isometrically in the case $\sigma$ is such that $\sigma(1)=N+2$.

Moreover, by the density of (linear combinations of) vectors of the form $E_{D^{\prime}}\left(x_{1} \otimes_{D} \cdots \otimes_{D} x_{N+2}\right)$ obtained in the proof of (1), it suffices to show that the restriction of $J(\sigma)$ to those vectors is an isometry.

But note that with our fixed $\sigma$, we have obtained the relation :

$$
J(\sigma)\left[E_{D^{\prime}}\left(x_{1} \otimes_{D} \ldots \otimes_{D} x_{N+2}\right)\right]=E_{D^{\prime}}\left(x_{2} \otimes_{D} \ldots \otimes_{D} x_{N+2} \otimes_{D} x_{1}\right)
$$

Moreover, assuming extremality, there is by Theorem A. 15 a unitary Burns rotation, and by its defining relation, it coincides with $J(\sigma)^{-1}$ so that $J(\sigma)$ is an isometry as stated. The case with a basis is left to the reader.

For the last statement about traciality of $\tau(X)=\left\langle e_{D}, X \# e_{D}\right\rangle$ on $D^{\prime} \cap N_{\kappa}^{\substack{\mathrm{eh} \\ \otimes}} \mathrm{N}_{2}^{D}$, we start from the result we obtained using the action for a general $\sigma$. Let $U, U^{\prime} \in$ $D^{\prime} \cap M^{\substack{\text { eh } \\ D, c}}(N+2), V=J(\sigma)(U), V^{\prime}=J(\sigma)\left(U^{\prime}\right) \in D^{\prime} \cap M^{\substack{\text { eh } \\ D}}(N+2)$. One easily gets from the isometry relation :

$$
\begin{aligned}
\operatorname{Tr}\left(e_{D}\left[\left(\iota_{\bar{k}} \otimes \iota_{\bar{l}}\left(V^{\star}\right)\right) \#\left[\left(\iota_{k} \otimes \iota_{l}\left(U^{\prime}\right)\right) \# e_{D}\right]\right]\right. & =\left\langle U, U^{\prime}\right\rangle=\left\langle V, V^{\prime}\right\rangle \\
& =\operatorname{Tr}\left(\left[\left(\iota_{k} \otimes \iota_{l}\left(U^{\prime}\right)\right) \#\left[\left(\iota_{\bar{k}} \otimes \iota_{\bar{l}}\left(V^{\star}\right)\right) \# e_{D}\right]\right] e_{D}\right)
\end{aligned}
$$

and one easily gets zero for various other injections.
Finally, we know that linear combinations of $E_{D^{\prime}}\left(n \otimes_{D} n^{\prime}\right), n, n^{\prime} \in N_{\kappa}$ are weak* dense in $D^{\prime} \cap N_{\kappa}{ }^{\stackrel{\text { eh }}{\otimes_{D}} 2}$, and then using the strong density of $\operatorname{Span}\left(\iota_{k}\left(M_{{ }_{D}^{\text {eh }}}^{\stackrel{\otimes}{D} k}\right), k \in\right.$ $\left.\kappa^{N}, N \geq 0\right)$ in $N_{\kappa}$, we get the same result, with $n, n^{\prime}$ in this span. But now, we
already noticed that $E_{D^{\prime}}\left(\iota_{k} \otimes \iota_{l}(U)\right)=\left(\iota_{k} \otimes \iota_{l}\left(E_{D^{\prime}}(U)\right)\right.$ thus proving the weak-* density of $\operatorname{Span}\left\{E_{D^{\prime}}\left(\iota_{k} \otimes \iota_{l}\left(D^{\prime} \cap M^{\substack{\mathrm{eh} \\ \otimes, c}} N+2\right),|k|+|l|=N \geq 0\right\}\right.$ in $D^{\prime} \cap N_{\kappa}^{\stackrel{\text { eh }}{\otimes 2}}{ }^{D}$ (and even of the intersection of the unit ball in the intersection of the unit ball by using the Kaplansky density theorem $[\mathbf{K R}]$ in the reasoning above). Now, the weak-* continuity proved in Theorem A.19.(2) of $X \mapsto\left\langle e_{D}, X \#\left(Y \# e_{D}\right)\right\rangle$ (and the obvious one of $Y \mapsto\left\langle e_{D}, X \#\left(Y \# e_{D}\right)\right\rangle$ using (33)) proves the statement.
(3) The complete boudedness statements follow from replacing $M$ by $M_{n}(M)$ and checking the bounds don't depend on $n$. For the first statement, using Wick's expansion, it suffices to prove boundedness of $\iota_{k_{1}} \otimes_{D} \ldots \otimes_{D} \iota_{k_{p}}: M^{\substack{\mathrm{eh} \\ \otimes, c c}} \rightarrow N_{\kappa}^{\substack{\mathrm{eh} \\ \otimes, c}}$ for $\left|k_{p}\right|=n_{p}-1$. Since the map is defined $D^{\prime} \cap M^{\stackrel{\text { eh }}{\otimes} n} \rightarrow D^{\prime} \cap N_{\kappa}{ }^{\stackrel{\text { eh }}{\otimes} p}$ b by the universal property, it suffices to check the stability of corresponding subspaces. Since $N_{\kappa}$ is involved, we consider $N^{\prime}=W^{*}\left(N_{\kappa}, S_{1}^{\prime}, \ldots, S_{\kappa}^{\prime}\right)$ and $\iota_{k}^{\prime}$ the corresponding evaluation for a word in $\kappa$ letters (with primes), $\iota_{k}^{\prime \prime}$ the evaluation for $M$ with a word $k$ in $2 \kappa$ letters. If $|l|=p-1$ is a word in $\kappa$ letters with primes, and $k_{i}$ 's are word in $\kappa$ letters without prime as before, we write $l \circ\left(k_{1}, \ldots, k_{p}\right)=k_{1} l_{1} \ldots l_{p-1} k_{p}$ and one then notices (using some orthogonality in free products) that $\iota_{l}^{\prime} \circ\left(\iota_{k_{1}} \otimes_{D} \ldots \otimes_{D} \iota_{k_{p}}\right)=\iota_{l \circ\left(k_{1}, \ldots, k_{p}\right)}^{\prime \prime}$. One easily deduces from this the stated stability, the boundedness following from the very definitions of norms involving more specific evaluation and from $\left(N^{\prime}, E_{M}\right) \simeq$ $\left(N_{\kappa}, E_{M}\right)$ since $\kappa$ is infinite.

For the statement on conditional expectations, it suffices to prove the boundedness on $E^{\otimes_{D} p}: N_{\kappa} \otimes_{e h s c D p} \rightarrow M^{\otimes_{e h s c D} p}$ by the symmetry of this map which implies the stability of kernels under the action of the cyclic group. It suffices to check that $I_{1}(\sigma) \circ E^{\otimes_{D} p}(X)=E_{W^{*}\left(M, S_{1}^{\prime}, \ldots, S_{\kappa}^{\prime}\right)}\left[I_{1}(\sigma)(X)\right] E_{W^{*}\left(M, S_{1}^{\prime}, \ldots, S_{\kappa}^{\prime}\right)}$ and $I_{2}(\sigma) \circ E^{\otimes_{D} p}(X)=\left(E_{W^{*}\left(M, S_{1}^{\prime}, \ldots, S_{k}^{\prime}\right)} \otimes_{D^{\circ p}} E_{W^{*}\left(M, S_{1}^{\prime}, \ldots, S_{\kappa}^{\prime}\right)}\right) I_{2}(\sigma)(X)$, which can be routinely checked on elementary tensors using freeness with amalgamation over $M$ of $N_{\kappa}$ and $W^{*}\left(M, S_{1}^{\prime}, \ldots, S_{\kappa}^{\prime}\right)$.

## B. Function Spaces

In this appendix, we study several function spaces crucial to our constructions. We start by considering spaces of analytic functions as well as cyclic analytic functions (these can be regarded as enlargements of spaces of non-commutative polynomials and cyclically symmetrizable non-commutative polynomials). We then consider analytic functions that depend on expectations, i.e., enlargements of functions of the form $X_{i_{1}} E\left(X_{i_{2}} X_{i_{3}} E\left(X_{i_{4}} X_{i_{5}}\right) X_{i_{6}}\right) X_{i_{7}}$, where $E$ is a (formal) conditional expectation. Finally, we consider analogues of spaces of $C^{k}$-functions, defined as completions in certain $C^{k}$ norms.
B.1. Generalized cyclic non-commutative analytic functions. In this section we study the properties of cyclic $B_{c}\left\langle X_{1}, \ldots, X_{n}: D, R, \mathbb{C}\right\rangle$ and ordinary $B\left\langle X_{1}, \ldots, X_{n}: D, R, \mathbb{C}\right\rangle$ generalized analytic functions in $n$ variables with radius of convergence at least $R$, defined in subsection 2 . Here, as before, $D \subset B$ are finite von Neumann algebras. We will also consider a variant with several radius of convergence $R, S, B\left\langle X_{1}, \ldots, X_{n}: D, R ; Y_{1}, \ldots, Y_{m}: D, S\right\rangle, B_{c}\left\langle X_{1}, \ldots, X_{n}: D, R ; Y_{1}, \ldots, Y_{m}\right.$ :
$D, S \mathbb{C}\rangle$. We will use it freely later. If $X=\left(X_{1}, \cdots, X_{n}\right)$, we also write $B\langle X: D, S\rangle$ for $B\left\langle X_{1}, \ldots, X_{n}: D, S\right\rangle$, etc.

We have the following basic result:
Proposition B.25. Let $X=\left(X_{1}, \ldots, X_{n}\right), Y=\left(Y_{1}, \ldots, Y_{m}\right)$. Then (a) The linear spaces $B_{c}\langle X: D, R, \mathbb{C}\rangle, B\langle X: D, R, \mathbb{C}\rangle$ (resp. $B\langle X: D, R\rangle$ ) are Banach *-algebras as well as operator spaces (resp. Banach algebra and strong operator $D$ module). Moreover, $B\langle X: D, R, \mathbb{C}\rangle, B\langle X: D, R\rangle$ are dual operator spaces when seen as (module) duals of (module) $c_{0}$ direct sums of the fixed preduals of each term of the $\ell^{1}$ direct sum. We always equip them with this weak-* topology. Finally the algebra generated by $B, X$ is weak-* dense in those spaces.
(b) For $P \in B\langle X: D, R\rangle, Q_{1}, \ldots, Q_{n} \in D^{\prime} \cap B\langle X: D, S, \mathbb{C}\rangle$, such that $\left\|Q_{i}\right\| \leq R$, there is a well defined composition obtained by evaluation at $Q_{j}: P\left(Q_{1}, \ldots, Q_{n}\right) \in$ $B\langle X: D, S\rangle$. The composition also makes sense on the cyclic variants and is compatible with canonical inclusion maps on these function spaces.
(c) If $B_{\otimes k}\langle X: D, R, C\rangle$ (with $C=\mathbb{C}$ or $C=D$ ) is the subspace of $B\langle X, Y$ : $D, R, C\rangle$ consisting of functions linear in each $Y_{1}, \ldots, Y_{m}$ and so that in each monomial each letter $Y_{j}$ only appears to the right of all letters $Y_{i}$ with $i<j$,then there are canonical maps

$$
. \#(., \ldots, .): B_{\otimes k}\langle X: D, R\rangle \times \prod_{i=1}^{k} B_{\otimes l_{i}}\langle X: D, R, \mathbb{C}\rangle \rightarrow B_{\otimes\left(\sum_{i} l_{i}\right)}\langle X: D, R\rangle,
$$

$l_{i} \geq 0$ induced from composition in the $Y$ variables. (Note that by definition $\left.B_{\otimes 0}\langle X: D, R\rangle=B\langle X: D, R\rangle.\right)$
(d) For any $N \supset B$ a finite von Neumann algebra, $P \in B\langle X: D, R\rangle$ defines a $\operatorname{map}\left(D^{\prime} \cap N\right)_{R}^{n} \rightarrow N$, by evaluation, with $P\left(X_{1}, \ldots, X_{n}\right) \in W^{*}\left(B, X_{1}, \ldots, X_{n}\right)$.

Proof. The fact that $B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$ is a Banach algebra is obtained in [Dab15, Th 39]. The dual operator space structure and weak-* density also come from this result. The stability by adjoint only works for direct sums over $\mathbb{C}$ (since adjoint is not a module map and would require the conjugate module structure). The stability by multiplication obtained in Proposition A. 24 gives the same result for $B_{c}\left\langle X_{1}, \ldots, X_{n}: D, R, \mathbb{C}\right\rangle$. For the stability by composition, the well-known composition map in [Dab15] Theorem 2 is completely bounded in each of the middle variables and it is easy to see that the compositions built in Proposition A. 24 also are (since the intersection norm is obtained from Haagerup norms dealt with in the non-cyclic case). Thus, $\ell^{1}$ direct sums are dealt with using universal property, the only key point is that we use operator space (and not module) $\ell^{1}$ direct sum for composition in $Q_{i}$ variables since the multilinear map $\left(P, Q_{1}, \ldots, Q_{n}\right) \rightarrow P\left(Q_{1}, \ldots, Q_{n}\right)$ is a $D-D$ module map only in the variable $P$. In this way, the previous complete contractivity can be used in each variable with the right universal property for each type of $\ell^{1}$ direct sum. In order to use the universal property in $P$, one also needs to know the source and target modules are strong operator modules over $D$ in the non-cyclic case, and they are since those extended Haagerup products are even normal dual operator modules. The statements for $B_{\otimes k}$ are obvious consequences. The evaluation map comes from the standard inclusion $B^{\stackrel{\mathrm{eh}}{\otimes, n} n} \subset N^{\stackrel{\mathrm{eb}}{\mathrm{D}} n}$ (see e.g. [Dab15] Theorem 2.(2)), and from the multiplication maps explained e.g. in
[Dab15] Theorem 2.(4). The reader should note that they can be applied on a larger space than the one in [Dab15, Th 39] since in general $D^{\prime} \cap N \supset E_{D}^{\prime} \cap N$. Note the evaluation maps used here may not a have any kind of weak-* continuity, contrary to those of [Dab15, Th 39].
B.1.1. Difference quotient derivations and cyclic derivatives.

Proposition B.26. Let $S<R$. (a) The iterated free difference quotients $\partial_{\left(i_{1}, \ldots, i_{k}\right)}^{k}=\left(\partial_{X_{i_{1}}} \otimes 1^{\otimes k-1}\right) \circ \ldots \circ \partial_{X_{i_{k}}}$ define completely bounded maps from $B\langle X: D, R, C\rangle$ to $B_{\otimes k}\langle X: D, S, C\rangle$ (with $C=\mathbb{C}$ or $C=D$, and thus in both cases to $\left.B\langle X: D, S\rangle_{D}^{\substack{\text { eh } \\ D_{k+1}}}\right)$.
(b) The space $B_{c}\langle X: D, R, \mathbb{C}\rangle$ is mapped by $\partial_{\left(i_{1}, \ldots, i_{k}\right)}^{k}$ to $B_{\otimes k c}\langle X: D, R, \mathbb{C}\rangle$.
(c) For $d \in B_{c}\langle X: D, S \mathbb{C}\rangle$, the cyclic gradient $\mathscr{D}_{X_{i}, d}$ defines a bounded map from $B_{c}\langle X: D, R, \mathbb{C}\rangle$ to $B_{c}\left\langle X_{1}, \ldots, X_{n}: D, S \mathbb{C}\right\rangle$
(d) The following cyclic derivation relation holds:

$$
\begin{equation*}
\mathscr{D}_{X_{i}, d}(P Q)=\mathscr{D}_{X_{i}, Q d}(P)+\mathscr{D}_{X_{i}, d P}(Q) . \tag{39}
\end{equation*}
$$

(e) The following relations between derivatives and composition hold, denoting $Q=\left(Q_{1}, \ldots, Q_{n}\right):$

$$
\begin{align*}
& \partial_{\left(j_{1}, \ldots, j_{k}\right)}^{k}(P(Q))=\sum_{l=2}^{k} \sum_{n_{1}, \ldots, n_{l}} \sum_{1 \leq i_{1}<\ldots<i_{l}=k}\left(\partial_{\left(n_{1}, \ldots, n_{l}\right)}^{l}(P)\right)(Q) \#  \tag{40}\\
&\left(\partial_{\left(j_{1}, \ldots, j_{i_{1}}\right)}^{i_{1}} Q_{n_{1}}, \partial_{\left(j_{i_{1}+1}, \ldots, j_{i_{2}}\right)}^{i_{2}-i_{1}} Q_{n_{2}}, \ldots, \partial_{\left(j_{i_{l-1}+1}, \ldots, j_{k}\right)}^{k-i_{l-1}} Q_{n_{l}}\right) .
\end{align*}
$$

and

$$
\begin{equation*}
\mathscr{D}_{X_{i}, d}(P(Q))=\sum_{j=1}^{n} \mathscr{D}_{X_{i}, \mathscr{D}_{Q_{j}, d}(P)(Q)}\left(Q_{j}\right), \tag{41}
\end{equation*}
$$

where we wrote $\mathscr{D}_{Q_{j}, d}(P)(Q)=\left[\mathscr{D}_{X_{j},\left[d\left(X_{1}^{\prime}, \ldots, X_{n}^{\prime}\right)\right.}(P)\right](Q, X)$ considering $P \in B_{c}\langle X$ : $D, R, \mathbb{C}\rangle \subset B_{c}\left\langle X, X^{\prime}: D, R, \mathbb{C}\right\rangle, d\left(X^{\prime}\right) \in B_{c}\left\langle X^{\prime}: D, R, \mathbb{C}\right\rangle \subset B_{c}\left\langle X, X^{\prime}: D, R, \mathbb{C}\right\rangle$, so that $\left.\mathscr{D}_{X_{j},\left[d\left(X^{\prime}\right)\right.}(P)\right] \in B_{c}\left\langle X, X^{\prime}: D, R, \mathbb{C}\right\rangle$ is well defined and can be evaluated at $X_{i}=Q_{i}, X_{i}^{\prime}=X_{i}$.
Proof. Let us write $n_{X_{i}}(m)$ for the $X_{i}$ degree of a monomial $m$, i.e., the number of times the variable $X_{i}$ occurs in $m$. To define the free difference quotient and cyclic gradient, we start from the formal differentiation on monomial, add appropriate change of radius of convergences $S<R$ to allow boundedness of the map and then gather the monomials at the $\ell^{1}$ direct sum level by the universal property:
$\partial_{X_{i}}: B\left\langle X_{1}, \ldots, X_{n}: D, R, C\right\rangle \rightarrow \ell_{C}^{1}\left(S^{|m|}\left(B^{\substack{\text { eh } \\ \otimes(|m|+1)}}\right)^{\oplus_{C}^{1} n_{X_{i}}(m)} ; m \in M\left(X_{1}, \ldots, X_{n}\right),|m| \geq 1\right)$,
and similarly in the cyclic cases.
In order to for the value to belong to the claimed space, we also need to specify a canonical map $I$ with values in $B_{\otimes 2}\langle X: D, S, C\rangle$. Of course, we want it to send the $j$-th component in the $\oplus_{C}^{1} n_{X_{i}}(m)$ direct sum to the component of the monomial $m_{X_{i}, j}$ which is identical to $m$ but with the $j$-th $X_{i}$ replaced by $Y_{1}$. Since there is a bijection between the disjoint union over monomials of $\{m\} \times \llbracket 1, n_{X_{i}}(m) \rrbracket$ and
the set of monomials in $X$ and $Y_{1}$ linear in $Y_{1}$, it is easy to see that $I$ extends to a complete isomorphism of $\ell_{C}^{1}$ direct sums. We still write $\partial_{X_{i}}$ for $I \circ \partial_{X_{i}}$.

For the cyclic gradient, one can then apply a different cyclic permutation on each term of the direct sum and we gather them in a map $\sigma: B_{\otimes 2 c}\langle X: D, S, \mathbb{C}\rangle \rightarrow$ $B_{\otimes 2 c}\langle X: D, S, \mathbb{C}\rangle$ and a multiplication map $m_{d}: B_{\otimes 2 c}\langle X: D, S, \mathbb{C}\rangle \rightarrow B_{c}\langle X:$ $D, S, \mathbb{C}\rangle$ (based on composition \# at $d$ on the appropriate term of the tensor product and extending $\left.m_{d}(P \otimes Q)=P d Q=(P \otimes Q) \# d\right)$ to get the expected cyclic gradient: $\mathscr{D}_{X_{i}, d}=m_{d} \sigma \partial_{X_{i}}$.

For the free difference quotient, to see there is a canonical map to the range space $B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle \stackrel{\text { eh }}{\otimes} B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$, one applies the following Lemma to each term of the direct sum inductively, and then the universal property of $\ell^{1}$ direct sums to combine them. (We of course apply after mapping $\ell_{C}^{1}$ to $\ell_{D}^{1}$ direct sums). The various relations then follow by construction from the various associativity properties of the compositions and multiplication defined in Proposition A.24. We explain those associated to cyclic gradients. First, we obtain the derivation property of $\partial_{X_{i}}$ and $\partial_{X_{i}}(P Q)=\partial_{X_{i}}(P) Q+P \partial_{X_{i}}(Q)$ so that:

$$
\sigma \partial_{X_{i}}(P Q)=\left[\sigma \partial_{X_{i}}(P)\right] \#(Q \otimes 1)+\left[\sigma \partial_{X_{i}}(Q)\right] \#(1 \otimes P)
$$

and applying $m_{d}$ one gets (39). Similarly, one obtains first the relation

$$
\partial_{X_{i}}(P(Q))=\sum_{j=1}^{n} \partial_{X_{j}} P(Q) \#\left(\partial_{X_{i}} Q_{j}\right)
$$

and then

$$
\sigma \partial_{X_{i}}(P(Q))=\sum_{j=1}^{n}\left[\sigma\left(\partial_{X_{i}} Q_{j}\right)\right] \#\left[\sigma \partial_{X_{j}} P(Q)\right]
$$

and applying $m_{d}$ gives (41).
The following result is a module extended Haagerup variant of [OP97, Lemma 7], the proof is the same using universal property of $\ell^{1}$ direct sums and [M97, Th 3.9]. We leave the details to the reader.

Lemma B.27. Let $E_{1}, E_{2} \in{ }_{D} S O M_{D}, F_{1}, F_{2} \in{ }_{D} S O M_{D}$, let $X=\left(E_{1} \oplus_{D}^{1} E_{2}\right) \stackrel{\text { eh }}{\otimes}{ }_{D}$ $\left(F_{1} \oplus_{D}^{1} F_{2}\right)$. Let $S$ be the closure of the subspace obtained by injectivity of Haagerup tensor product $\left(E_{1} \stackrel{\stackrel{\text { eh }}{\otimes}}{\otimes} F_{1}\right)+\left(E_{2} \stackrel{\text { eh }}{\otimes}{ }_{D} F_{2}\right)$. Then we have:

$$
S \simeq\left(E_{1} \stackrel{\mathrm{eh}}{\otimes} F_{D}\right) \oplus_{D}^{1}\left(E_{2} \stackrel{\stackrel{\mathrm{eh}}{\otimes}}{D}{ }_{D}\right),
$$

completely isometrically.
We will also need a more subtle evaluation result for $B_{\otimes k c}\left\langle X_{1}, \ldots, X_{n}: D, R, \mathbb{C}\right\rangle$ which requires that our variables are nice functions of semi-circular variables.

We write $A_{R, U l t r a A p p}^{n}$ for the set of $X_{1}, \ldots, X_{n} \in A, X_{i}=X_{i}^{*},\left[X_{i}, D\right]=0,\left\|X_{i}\right\| \leq$ $R$ and such that $B, X_{1}, \ldots, X_{n}$ is the limit in $E_{D}$-law (for the $*$-strong convergence of $D)$ of variables in $B_{c}\left\langle X_{1}, \ldots X_{m}: D, 2, \mathbb{C}\right\rangle\left(S_{1}, \ldots, S_{m}\right)$ with $S_{i}$ a family of semicircular variables over $D$, that is of elements in the set of analytic functions evaluated in $S_{1}, \ldots, S_{m}$. Here $m$ is some large enough fixed integer.

Proposition B.28. For any $\left(X_{1}, \ldots, X_{n}\right) \in A_{R, \text { UltraApp }}^{n}$, if $\phi_{j}: B_{D^{\mathrm{Qh} n_{j}}}^{\substack{\mathrm{eh}}} \rightarrow M, j=$ $1, \ldots, p$ are multiplication maps $\phi_{j}(Z)=Z \#\left(X_{1+\sum_{\substack{\text { eh } \\ \text { eh }}}^{j-1} n_{l}}, \ldots, X_{\sum_{l=1}^{j} n_{l}}\right), M=$ $W^{*}\left(B, X_{1}, \ldots, X_{n}\right)$, then $\phi_{1} \otimes_{D} \ldots \otimes_{D} \phi_{p}: B^{\substack{\mathrm{eh} \\ \otimes, c}} \rightarrow \substack{\mathrm{eh} \\ \otimes^{\mathrm{eh}}, \mathrm{p}}$ is a completely bounded map of norm less than $R^{n-p}$ with $n=\sum n_{i}$. As a consequence, any $\left(X_{1}, \ldots, X_{n}\right) \in$ $A_{R, \text { UltraApp }}^{n}$, induces an evaluation map $B_{\otimes k c}\left\langle X_{1}, \ldots, X_{n}: D, R, \mathbb{C}\right\rangle \rightarrow M^{\substack{\text { eb } \\ D, c}}{ }^{(k+1)}$.
Proof. Assuming first $X_{i} \in B_{c}\left\langle X_{1}, \ldots X_{m}: D, 2, \mathbb{C}\right\rangle\left(S_{1}, \ldots, S_{m}\right)$ the result is obvious in a similar way as for composition of corresponding analytic functions and from the evaluation map to $\left(S_{1}, \ldots, S_{m}\right)$ in Proposition A.24.(3). At first, the result is valued
 space of value.

We now consider the more general case with

$$
X_{i} \in C^{*,+}\left(B, S_{1}, \ldots, S_{m}\right):=C^{*}\left(e_{S_{1}, \ldots, S_{m}}\left(B\left\langle X_{1}, \ldots, X_{m}: D, 2, \mathbb{C}\right\rangle\right)\right),
$$

in the $C^{*}$ algebra generated in $W^{*}\left(B, S_{1}, \ldots, S_{m}\right)$ by evaluations of our analytic functions at semicircular variables. There is a map $\phi_{1} \otimes_{D} \ldots \otimes_{D} \phi_{p}$ on the extended Haagerup tensor product by functoriality and nothing is required to get a map on the intersection space $\phi_{1} \otimes_{D} \ldots \otimes_{D} \phi_{p}: B^{\otimes_{e h s c D} n} \rightarrow M^{\otimes_{e h s c D} p}$. To get the stated map and even first a map $\phi_{1} \otimes_{D} \ldots \otimes_{D} \phi_{p}: B^{\otimes_{e h S c D} n} \rightarrow M^{\otimes_{e h S c D} p}$, we have to check various stability properties of kernels appearing in their definition as an intersection space. From the formula below describing the commutation of the cyclic action and various tensor products of the maps $\phi$, this stability of kernels will become obvious. More precisely, let $U \in B^{\otimes_{e h s c D n}}$ for $\sigma \in \mathfrak{C}_{p}$, we write $\hat{\sigma}$ the induced permutations on blocks and $V=J(\hat{\sigma})(U)$ and $n=k l, \sigma(1)=|l|+2,|l|=p-2-|k|$. We want to show for any $X \in\left\langle N, e_{D}\right\rangle \cap L^{1}\left(\left\langle N, e_{D}\right\rangle\right)$ with $N=W^{*}\left(M, S_{1}, \ldots, S_{\kappa}\right)$ :
$\left.\left.\left(\iota_{k} \otimes_{D} \iota_{l}\right)\left(\phi_{1} \otimes_{D} \ldots \otimes_{D} \phi_{p}(U)\right) \# X=X \#\left(\iota_{l} \otimes_{D} \iota_{k}\right)\left(\left(\phi_{\sigma^{-1}(1)} \otimes_{D} \ldots \otimes_{D} \phi_{\sigma^{-1}(p)}(V)\right)\right)\right)\right)$. It suffices to evaluate them to $Y, Z \quad \in \quad\left[B\left\langle X_{1}, \ldots, X_{n} \quad\right.\right.$ : $\left.D, R, \mathbb{C}\rangle\left(X_{1}, \ldots, X_{n}\right)\right]\left\langle S_{1}, \ldots, S_{\kappa}\right\rangle=: C \subset L^{2}(N)$ as in Lemma A.21.(2) and to take $X \in C e_{D} C$, and see equality in $L^{1}(D)$. The statement for $X_{1}, \ldots, X_{n}$ analytic as above gives exactly this in this case. In the evaluated form, the convergence in $E_{D}$-law is clearly enough to get the general case from this one. The evaluation map is then obtained by the universal property of $\ell^{1}$ direct sums. It crucially uses the bound on the norm of the completely bounded map above $R^{n-p}$ that follows from the bounds on canonical evaluations, and the sup norm on $M^{\otimes_{e h S c D} p}, M^{\substack{\mathrm{eh} \\ \mathrm{D}, c}}$.
B.2. Analytic functions with expectations. For $X=\left(X_{1}, \ldots, X_{n}\right)$, the spaces $B_{c}\left\{X: E_{D}, R, \mathbb{C}\right\}, B\left\{X: E_{D}, R\right\}$ have been defined in section 2. To prove various results for them, we need some formal notation to explain several computations combinatorially. First, since those spaces are defined as $\ell^{1}$ direct sums over pairs of monomials $m$ and non-crossing partitions $\sigma \in N C_{2}(2 k)$ (indexing the parenthesizing where conditional expectations are inserted), we can write $\pi_{m, \sigma}$ for the projection on the corresponding component of the $\ell^{1}$ direct sum, and $\epsilon_{m, \sigma}$ for the corresponding injection.

We write $E_{D}$ for the formal conditional expectation characterized for $P \in$ $B_{c, k}\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}$ by $E_{D}(P) \in B_{c, k+1}\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}$ and such that the only-nonzero projections $\pi$ are of the form

$$
\pi_{Y m Y, \hat{\sigma}}\left(E_{D}(P)\right)=\pi_{m, \sigma}(P)
$$

for $\hat{\sigma}=\{\{1,2 i+2\}\} \cup(\sigma+1)$ where the blocks of $\sigma+1$ are $\{a+1, b+1\}$ if $\{a, b\}$ are the blocks of $\sigma$. All other components of $\pi_{m^{\prime}, \sigma^{\prime}}\left(E_{D}(P)\right)$ are 0 . $E_{D}$ is obviously $D-D$ bimodular and completely bounded.

The scalar case $D=\mathbb{C}$ was considered in [Ceb13]; in this case we note the density of $\mathbb{C}\left\{X_{1}, \ldots, X_{n}\right\} \supset \operatorname{Span}\left\{P_{0} \operatorname{tr}\left(P_{1}\right) \ldots \operatorname{tr}\left(P_{k}\right), P_{i} \in \mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle\right\}$.

For $P \in \mathbb{C}\left\{X_{1}, \ldots, X_{n}\right\}$ and a linear form $\tau \in\left(\mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle\right)^{*}$ there is a canonical element $P(\tau) \in \mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle$ defined by extending linearly $\left[P_{0} \operatorname{tr}\left(P_{1}\right) \ldots \operatorname{tr}\left(P_{k}\right)\right](\tau)=$ $P_{0} \tau\left(P_{1}\right) \ldots \tau\left(P_{k}\right)$. In this way, one embeds

$$
\mathbb{C}\left\{X_{1}, \ldots, X_{n}\right\} \hookrightarrow C^{0}\left(\left(\mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle\right)^{*}, \mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle\right)
$$

(where the continuity is coefficientwise on the range and for the weak-* topology induced by $\mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle$ on the source).

Similarly, for $P \in B\left\{X_{1}, \ldots, X_{n} ; E_{D}, R\right\}$ and a unital $D$ bimodular completely bounded linear map $E \in U C B_{D-D}\left(B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle, D\right)$, there is a canonical element $P(E) \in B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle$. Since $P \mapsto P(E)$ will be completely bounded $D-D$ bimodular on monomials, by the universal property of $\ell^{1}$ direct sums, it suffices to define it for monomials $P=\pi_{m, \sigma}(P), \sigma \in N C_{2}(2 k)$. It is defined by induction on $k$. Write $\sigma_{-} \in N C_{2}(2(k-1))$ the unique pair partition obtained by removing from $\sigma$ the pair $\{i, i+1\}$ of smallest index $i$ and re-indexing by the unique increasing bijection $\llbracket 1,2 k \rrbracket-\{i, i+1\} \rightarrow \llbracket 1,2(k-1) \rrbracket$. Let also $j(i)$ the index in the word $m$ of the i-th $Y$ (this being 1 if $i=1$ and $m$ starts by $Y$ ). Then $P=\pi_{m, \sigma}(P) \in B^{\substack{\text { eh } \\ \otimes, c}}(|m|+1)$, then

$$
P(E)=\left[\epsilon_{m^{\prime}, \sigma_{-}}\left[1^{\otimes j(i)} \otimes E \circ \epsilon_{m^{\prime \prime}} \otimes 1^{\otimes|m|-j(i+1)+1}\right](P)\right](E)
$$

with $m^{\prime}=m_{1} \ldots m_{j(i)-1} m_{j(i+1)+1} \ldots m_{|m|}, m^{\prime \prime}=m_{j(i)+1} \ldots m_{j(i+1)-1}$. Indeed the letters between the index $j(i)$ and $j(i+1)$ in $m^{\prime \prime}$ are only $X$ 's and we can thus apply $E$ identifying $B^{\substack{\text { eh } \\ D^{\mathrm{A}}}}{ }^{(i+1)-j(i)}$ via $\epsilon_{m^{\prime \prime}}$ with the corresponding subspace of $B\left\langle X_{1}, \ldots, X_{n}\right.$ : $D, R\rangle$. Since $E$ is $D-D$ bimodular $\left[\epsilon_{m^{\prime}, \sigma_{-}}\left[1^{\otimes j(i)} \otimes E \circ \epsilon_{m^{\prime \prime}} \otimes 1^{\otimes|m|-j(i+1)+1}\right]\right]$ is well defined and we can apply $E$ inductively.

In this way, we have a canonical map
$B\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\} \rightarrow C^{0}\left(U C B_{D-D}\left(B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle, D\right), B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle\right)$.
where the topology on $U C B_{D-D}\left(B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle, D\right)$ is the topology of pointwise normwise convergence of $i d_{M_{I}} \otimes E$ on all $M_{I}\left(B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle\right.$ ) (for $I$ a cardinal smaller than the cardinal of $B$ ).

To state the algebraic and differential properties we will use, we also need the following variant (for $C=\mathbb{C}$ or $C=D$ ):
$B_{o p(l)}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, C\right\}$
$:=\ell_{C}^{1}\left(R^{|m|_{X}} B_{D}^{\stackrel{\mathrm{eh}}{\otimes}(|m|+1)} ; m \in M_{2 k}^{\prime}\left(X_{1}, \ldots, X_{n} ; Z_{1}, \ldots, Z_{l} ; Y\right), \pi \in N C_{2}(2 k), k \geq 0\right)$,
where $M_{2 k}^{\prime}\left(X_{1}, \ldots, X_{n} ; Z_{1}, \ldots, Z_{l} ; Y\right)$ is the set of monomials linear in each $Z_{i}$, without constraint on the order of appearance of $Z_{1}, \ldots, Z_{n}$ and of order $2 k$ in $Y$ The blocks in $Z_{i}$ are made to evaluate a variable in $D^{\prime} \cap N$. We call $B_{\otimes(l)}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, C\right\}$ the subspace involving monomials with $Z_{k}$ ordered in increasing order of $k$ and with all variables $Z_{i}$ having an even number of $Y$ before them and with their pair partitions unions of those restricted to the intervals between them (thus $Z_{i}$ 's are interpreted as not being inside conditional expectations.) We write $B_{\otimes(l) c}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, C\right\}$ the cyclic variant generalizing $B_{\otimes(l) c}\left\langle X_{1}, \ldots, X_{n}: E_{D}, R, C\right\rangle$.

The following result is clear:
Proposition B.29. Let $X=\left(X_{1}, \ldots, X_{n}\right)$. (a) The spaces $B_{c}\left\{X: E_{D}, R, \mathbb{C}\right\}$, $B\left\{X: E_{D}, R, \mathbb{C}\right\}$ are Banach ${ }^{*}$-algebras for usual adjoint and multiplication, extending the ones of $B\langle X: D, R, \mathbb{C}\rangle . B\left\{X: E_{D}, R, \mathbb{C}\right\}$ is a dual Banach space and the smallest algebra generated by $B, X$ and stable by $E_{D}$ is weak-* dense in it.
(b) $B\left\{X: E_{D}, R\right\}$ is a Banach algebra. $B\left\{X: E_{D}, R\right\}$ is a dual Banach space and the smallest algebra generated by $B, X$ and stable by $E_{D}$ is weak-* dense in it.
(c) There is a composition rule, for $P \in B\left\{X: E_{D}, R\right\}, Q_{1}, \ldots, Q_{n} \in D^{\prime} \cap B\{X$ : $\left.E_{D}, S, \mathbb{C}\right\}$, such that $\left\|Q_{i}\right\| \leq R$, then there is a composition $P\left(Q_{1}, \ldots, Q_{n}\right) \in B\{X$ : $\left.E_{D}, S\right\}$ extending the composition on $B\langle X: D, S\rangle$. There are similar cyclic variants compatible with canonical maps and with the evaluation map below.
(d) For finite von Neumann algebras $N \supset B, P \in B\left\{X: E_{D}, R\right\}$ defines a map $\left(D^{\prime} \cap N\right)_{R}^{n} \rightarrow N$ by evaluation, with $P(X):=P\left(E_{X, D}\right)(X) \in W^{*}(B, X)$, thus extending the value on $B\langle X: D, R\rangle$ and where $E_{X, D} \in U C B_{D-D}(B\langle X: D, R\rangle, D)$ comes from the conditional expectation.
(e) Similarly there is a canonical evaluation $\operatorname{ev}_{o p}\left(P, E_{X, D}, X\right) \in C B\left(\left(D^{\prime} \cap\right.\right.$ $\left.N)^{\otimes{ }_{h} l}, N\right), P \in B_{\text {opl }}\left\{X: E_{D}, R\right\}$, where $N$ are evaluated in the $Z_{i}$ 's and then each pair of $Y$ 's is replaced by a conditional expectation.
(f) There are also canonical continuous compositions (in the $Z_{i}$ variables) commuting with evaluation (with variants for $B_{\otimes(l) c}\left\{X: E_{D}, R, C\right\}, B_{\otimes(l)}\{X$ : $\left.\left.E_{D}, R, C\right\}\right):$
$\cdot \circ(\cdot, \ldots, \cdot): B_{o p(k)}\left\{X: E_{D}, R\right\} \times \prod_{i=1}^{k} B_{o p\left(l_{i}\right)}\left\{X: E_{D}, R, \mathbb{C}\right\} \rightarrow B_{o p\left(\sum_{i} l_{i}\right)}\left\{X: E_{D}, R\right\}$.
(g) For $\left(X_{1}, \ldots, X_{n}\right) \in A_{R, U l t r a A p p}^{n}$ we in particular have an evaluation map $B_{\otimes(l) c}\left\{X: E_{D}, R, C\right\} \rightarrow M^{\substack{\text { eh } \\ D, c}}(l+1)$ with $M=W^{*}\left(B, X_{1}, \ldots, X_{n}\right)$ as in Proposition B. 28 .
B.2.1. Various derivatives of analytic functions with expectations.

Proposition B.30. For $C=\mathbb{C}$ or $C=D$ and any $S<R$, (a) The free difference quotient (FDQ) derivations give rise to bounded maps

$$
\begin{aligned}
\partial_{i}: B\left\{X: E_{D}, R, C\right\} & \rightarrow B_{\otimes(1)}\left\{X: E_{D}, S, C\right\} \\
& \rightarrow B\left\{X: E_{D}, S\right\} \stackrel{\text { eh }}{\otimes} B\left\{X: E_{D}, S\right\}
\end{aligned}
$$

extending the free difference quotient from $B\langle X: D, R, C\rangle$ and determined by weak* continuity of the first line and by the requirement that the composition with the formal $E_{D}$ is zero: $\partial_{i} E_{D}=0$.
(b) The iterated $F D Q \partial_{\left(i_{1}, \ldots, i_{k}\right)}^{k}: B_{c}\{X: D, R, \mathbb{C}\} \rightarrow B_{\otimes(k) c}\{X: D, S, \mathbb{C}\}$ and $\partial_{\left(i_{1}, \ldots, i_{k}\right)}^{k}: B\{X: D, R, \mathbb{C}\} \rightarrow B_{\otimes k}\{X: D, S, \mathbb{C}\}$ are also bounded maps.
(c) Let d:B\{X:E $\left.E_{D}, R, C\right\} \rightarrow B_{o p}\left\{X: E_{D}, S, C\right\}^{n}$ and the operator variant $d: B_{o p(l)}\left\{X: E_{D}, R, C\right\} \rightarrow B_{o p(l+1)}\left\{X: E_{D}, R, C\right\}^{n}$ be the formal differentiation, i.e. a derivation uniquely determined among weak-* continuous maps by

$$
d\left(B\left\langle X, Z_{1}, \ldots Z_{l}: D, R\right\rangle\right)=0
$$

and for any monomial $P \in B_{o p(l)}\left\{X: E_{D}, R\right\} \quad$ (possibly $l=0$ ):

$$
\left.d E_{D}(P)=E_{D}\left(d_{X} P\right), \quad d_{X} P:=d P+\left(\partial_{i}(P) \# Z_{l+1}\right)\right)_{i}
$$

and $d_{X\left(i_{1}, \ldots, i_{l}\right)}^{l}=d_{X i_{l} \ldots d_{X i_{1}}}: B\left\{X: E_{D}, R, C\right\} \rightarrow B_{o p(l)}\left\{X: E_{D}, S, C\right\}$. Then $d$ and $d^{l}$ are bounded maps.
(d) We define the cyclic gradients on $B_{c}\left\{X: E_{D}, R, \mathbb{C}\right\} \rightarrow B_{c}\left\{X: E_{D}, S, \mathbb{C}\right\}$ for $d \in B_{c}\left\{X: E_{D}, S, \mathbb{C}\right\}, S<R$ as a natural continuous extension of the cyclic gradient on $B_{c}\langle X: D, R, \mathbb{C}\rangle$, satisfying $\mathscr{D}_{X_{i}, d}\left(X_{j}\right)=d 1_{i=j}$, (39) and for $P, Q$ monomials and for $d, P$ monomials

$$
\mathscr{D}_{i, d}\left(E_{D}(P)\right)=\mathscr{D}_{i, E_{D}(d)}(P) .
$$

(e) The following relation with compositions (40), (41) holds:

$$
\begin{align*}
& d_{X\left(j_{1}, \ldots, j_{k}\right)}^{k}(P(Q))=\sum_{l=1}^{k} \sum_{n_{1}, \ldots, n_{l}} \sum_{1 \leq i_{1}<\ldots<i_{l}=k l_{1,1}=1, l_{m-1,1}<l_{m, 1}<\ldots<l_{m, i_{m}-i_{m-1} \leq k}} \\
& \left(d_{X\left(n_{1}, \ldots, n_{l}\right)}^{l}(P)\right)(Q) \circ\left(d_{X\left(j_{l_{1,1}}, \ldots, j_{\left.l_{1, i_{1}}\right)}^{i_{1}}\right)} Q_{n_{1}}, d_{X\left(j_{l_{2,1}}, \ldots, j_{\left.l_{\left.2, i_{2}-i_{1}\right)}\right)}^{i_{2}-i_{1}}\right.} Q_{n_{2}}, \ldots, d_{X\left(j_{l, 1}, \ldots, j_{\left.l, k-l_{l-1}\right)}\right.}^{k-i_{l-1}} Q_{n_{l}}\right) \tag{42}
\end{align*}
$$

and in particular:

$$
d_{X}\left(P\left(Q_{1}, \ldots Q_{n}\right)\right)=\sum_{i=1}^{n}\left(\left(d_{X}(P)\right)\left(Q_{1}, \ldots, Q_{n}\right)\right)_{i} \circ d_{X}\left(Q_{i}\right)
$$

[Note the sum of $l_{i, j}$ in formula (42) is only a sum over partitions, the first term of the first set being written $l_{1,1}$, the first term of the second set in the partition $l_{2,1}$, the ordering between sets in the partition being by the ordering of the smallest element]
Proof. For the most part, we only have to give a combinatorial formula for the derivations acting on monomials. Then by the bimodularity of the formula and explicit uniform bounds, the universal property of the $\ell^{1}$ sum will extend them to module $\ell^{1}$ direct sums. They will be moreover weak-* continuous as soon as they are weak-* continuous when restricted to monomial components since the $c_{0}$ sum of predual maps will then give a predual map. The derivation properties then determine $d, \partial$ on the $E_{D}$-algebra generated by $B, X_{1}, \ldots, X_{n}$ which is weak-* dense in the $\ell^{1}$ direct sum (actually in each monomial space by properties of the extended Haagerup product and then, the finite sum of monomial spaces are normwise dense), thus weak-* continuity determine those maps everywhere.

For $\sigma \in N C_{2}(2 k), m \in M_{2 k}\left(X_{1}, \ldots, X_{n}, Y\right)$, let us say a submonomial $m^{\prime} \subset$ $m$ (with a fixed starting indexed, $m^{\prime}$ is thus formally a pair of the monomial and the starting index) is compatible with $\sigma$ and write $m^{\prime} \in C(\sigma, m)$ if $m^{\prime} \in M_{2 l}\left(X_{1}, \ldots, X_{n}, Y\right), l \leq k$ and $l^{\prime}$ the index in $m$ of the first $Y$ in $m^{\prime}$, then $\left.\sigma\right|_{m^{\prime}}:=\left.\sigma\right|_{\llbracket l^{\prime}, l^{\prime}+2 l-1 \rrbracket} \subset \sigma$ (which means there is no pairing in $m$ broken in $m^{\prime}$ by our extraction of $\left.m^{\prime}\right)$. We then write $S u b\left(\sigma, m^{\prime}\right) \in N C_{2}(2 l)$ the partition $\left.\sigma\right|_{\llbracket l^{\prime}, l^{\prime}+2 l-1 \rrbracket}$ reindexed.

Then we define:

$$
\partial_{i}\left(\epsilon_{m, \sigma}(P)\right)=\sum_{\substack{m=m^{\prime} X_{i} m^{\prime \prime}, m^{\prime}, m^{\prime \prime} \in C(\sigma, m)}}\left(\epsilon_{m^{\prime}, s u b\left(\sigma, m^{\prime}\right)} \otimes_{D} \epsilon_{m^{\prime \prime}, \operatorname{sub}\left(\sigma, m^{\prime \prime}\right)}\right)(P)
$$

Of course the sum is 0 if its indexing set is empty, this in particular explains $\partial_{i} E_{D}=0$ and the remaining properties are easy.

The definition of $d$ is complementary. When $m^{\prime}$ or $m^{\prime \prime}$ are not both in $C(\sigma, m)$ and $m=m^{\prime} X_{i} m^{\prime \prime}$ (some $i$ ), we write $\left(m^{\prime}, m^{\prime \prime}\right) \in I C(\sigma, m)$ (and this corresponds to a differentiation of $X_{i}$ below a conditional expectation).

Then we define

$$
d\left(\epsilon_{m, \sigma}(P)\right)=\left(\sum_{\substack{m=m^{\prime} X_{i} m^{\prime \prime},\left(m^{\prime}, m^{\prime \prime}\right) \in I C(\sigma, m)}}\left(\epsilon_{m^{\prime} Z_{1} m^{\prime \prime}, \sigma}\right)(P)\right)_{i}
$$

For $\sigma_{1}, \sigma_{2} \in N C_{2}\left(2 k_{i}\right)$ we define for $i \in \llbracket 0,2 k_{1} \rrbracket$ the obvious insertion $\sigma_{1} \#_{i} \sigma_{2}=\sigma$ such that $\left.\sigma\right|_{\llbracket i+1, i+k_{2} \rrbracket}=\sigma_{2},\left.\sigma\right|_{\llbracket i+1, i+k_{2} \rrbracket^{c}}=\sigma_{1}$ the equalities being understood after increasing reindexing. Likewise $\rho_{i}\left(\sigma_{1}\right)=\left\{\left\{i_{j}+i, i_{k}+i\right\}:\left\{i_{j}, i_{k}\right\} \in \sigma_{1}\right\}$ addition being understood modulo $2 k_{1}$ so that $\rho_{2 k_{1}}=\rho_{0}=i d$, and write also $\rho_{i}$ the corresponding permutation $\rho_{i}(k)=k+i$ modulo $2 k_{1}$.

We now define the cyclic gradient as follows:
and the relations are then easy. We give details for two of them involving cyclic gradients.

Let us explain (39) on spaces of monomials. We have to compute $\mathscr{D}_{i, \epsilon_{M, \Sigma}(d)}\left(\epsilon_{m, \sigma}(P) \epsilon_{\mu, \pi}(Q)\right)$. First note that $\epsilon_{m, \sigma}(P) \epsilon_{\mu, \pi}(Q)=\epsilon_{m \mu, \sigma \cup \pi}(P Q)$. Here $\sigma \cup \pi$ is merely the concatenation of non-crossing partitions and $P Q$ the product of tensors defined in Proposition A.24.(1). Note that the sum over $m \mu=m^{\prime} X_{i} m^{\prime \prime}$ splits into two sums depending on whether $X_{i}$ comes from $m$ or $\mu$. This gives the following computation (using relations on rotation and product such as $\rho_{\left|m^{\prime \prime} \mu\right|} \cdot(P Q)=$

$$
\begin{aligned}
& \left.\left.\rho_{\left|m^{\prime \prime}\right| \cdot} \cdot(P)\right) \# \#_{\left|m^{\prime \prime}\right|}(Q \otimes 1)\right): \\
& \mathscr{D}_{i, \epsilon_{M, \Sigma}(d)}\left(\epsilon_{m, \sigma}(P) \epsilon_{\mu, \pi}(Q)\right) \\
& \quad=\sum_{m=m^{\prime} X_{i} m^{\prime \prime}} \epsilon_{m^{\prime \prime} \mu M m^{\prime}, \rho_{\left|m^{\prime \prime} \mu\right| Y}(\sigma \pi) \#_{\left|m^{\prime \prime}\right|_{Y}} \Sigma}\left(\left(\rho_{\left|m^{\prime \prime} \mu\right|} \cdot P Q\right) \#_{\left|m^{\prime \prime} \mu\right|} d\right) \\
& \\
& +\sum_{\mu=m^{\prime} X_{i} m^{\prime \prime}} \epsilon_{m^{\prime \prime} M m m^{\prime}, \rho_{\left|m^{\prime \prime}\right| Y}(\sigma \pi) \#_{\left|m^{\prime \prime}\right|_{Y} \Sigma}\left(\left(\rho_{\left|m^{\prime \prime}\right|} \cdot P Q\right) \#_{\left|m^{\prime \prime}\right|} d\right)} \quad=\sum_{m=m^{\prime} X_{i} m^{\prime \prime}} \epsilon_{m^{\prime \prime} \mu M m^{\prime}, \rho_{\left|m^{\prime \prime}\right|_{Y}}(\sigma) \#_{\left|m^{\prime \prime}\right|_{Y}}(\pi \Sigma)}\left(\left(\rho_{\left|m^{\prime \prime}\right|} \cdot(P)\right) \#_{\left|m^{\prime \prime}\right|}(Q d)\right) \\
& \\
& \quad+\sum_{\mu=m^{\prime} X_{i} m^{\prime \prime}} \epsilon_{m^{\prime \prime} M m m^{\prime}, \rho_{\left|m^{\prime \prime}\right| Y}(\pi) \#_{\left|m^{\prime \prime}\right|_{Y}(\Sigma \sigma)}\left(\left(\rho_{\left|m^{\prime \prime}\right|} \cdot Q\right) \# \|_{\left|m^{\prime \prime}\right|}(d P)\right)} \quad=\mathscr{D}_{i, \epsilon_{\mu, \pi}(Q) \epsilon_{M, \Sigma}(d)}\left(\epsilon_{m, \sigma}(P)\right)+\mathscr{D}_{i, \epsilon_{M, \Sigma}(d) \epsilon_{m, \sigma}(P)}\left(\epsilon_{\mu, \pi}(Q)\right) .
\end{aligned}
$$

Let us finally explain (41). By linearity (in $P$ ) and continuity (in $P$ and $Q$ ), it suffices to consider the case of finite sums

$$
Q_{k}=\sum_{i} \epsilon_{M_{k, i}, \sigma_{k, i}}\left(Q_{k, i}\right), \quad k=1, \ldots, n
$$

and where $P$ is replaced by a monomial $\epsilon_{m, \sigma}(P)$. Then write $Q_{X_{k}, i}=Q_{k, i}$ and $Q_{Y, i}=1 \otimes 1, M_{Y, k}=Y, M_{X_{l}, k}=M_{l, k}$ and note that
$\left[\epsilon_{m, \sigma}(P)\right](Q)=\sum_{i_{1}, \ldots, i_{|m|}} \epsilon_{M_{m_{1}, i_{1}} \ldots M_{m_{|m|}, i_{|m|} \mid}, \sigma \#^{m}\left(\sigma_{\left.m_{1}, i_{1}, \ldots, \sigma_{m_{|m|}, i^{\prime}|m|}\right)}\left(P \#\left(Q_{m_{1}, i_{1}}, \ldots, Q_{m_{|m|}, i_{|m|} \mid}\right)\right), ~\right) ~}$
where if $m_{j_{1}}, \ldots, m_{j_{2 l}}$ is the set of $Y$ 's in $m, \sigma \in N C(2 l), \sigma_{X_{k}, l}=\sigma_{k, l}$ and

$$
\begin{aligned}
\sigma \#^{m}\left(\sigma_{m_{1}, i_{1}}, \ldots, \sigma_{m_{|m|}, i_{|m|}}\right)= & \left(\ldots \left(\left(\sigma \#_{2 l}\left(\sigma_{m_{j_{2 l}+1}, i_{j_{2 l}+1}} \cdots \sigma_{m_{|m|}, i_{|m|}}\right)\right)\right.\right. \\
& \left.\left.\#_{2 l-1}\left(\sigma_{m_{j_{2 l-1}}, i_{j_{2 l-1}}} \cdots \sigma_{m_{j_{2 l}-1}, i_{j_{2 l}-1}}\right)\right) \ldots \#_{0}\left(\sigma_{m_{1}, i_{1}} \cdots \sigma_{m_{j_{1}-1}, i_{j_{1}-1}}\right)\right)
\end{aligned}
$$

Thus one gets in writing for short $M_{m, i, L,+}=M_{m_{L+1}, i_{L+1}} \ldots M_{m_{|m|}, i_{|m|}}$ :

$$
\begin{aligned}
& \mathscr{D}_{j, \epsilon_{M, \Sigma}(d)}\left[\epsilon_{m, \sigma}(P)\right](Q)=\sum_{L=1 \ldots|m|, m_{L} \neq Y} \sum_{M_{m_{L}, i_{L}}=m^{\prime} X_{j} m^{\prime \prime}} \sum_{i_{1}, \ldots, i_{|m|}} \\
& \epsilon_{m^{\prime \prime} M_{m, i, L,+} M M_{m_{1}, i_{1}} \ldots M_{m_{L-1}, i_{L-1}} m^{\prime}, \rho_{\left|m^{\prime \prime} M_{m, i, L,+}\right| Y}\left(\sigma \#^{m}\left(\sigma_{m_{1}, i_{1}}, \ldots, \sigma_{m|m|, i_{|m|} \mid}\right) \#_{\left|m^{\prime \prime} M_{m, i, L,+}\right| Y} \Sigma\right.} \\
& \left(\left(\rho_{\left|m^{\prime \prime} M_{m, i, L,+}\right|} \cdot\left(P \#\left(Q_{m_{1}, i_{1}}, \ldots, Q_{m_{|m|}, i_{|m|} \mid}\right)\right)\right) \#_{\left|m^{\prime \prime} M_{m, i, L,+}\right|} d\right) .
\end{aligned}
$$

Then note the following combinatorial identities. We fix $m=M^{\prime} X_{j} M^{\prime \prime}$ with $\left|M^{\prime}\right|=L-1, \bar{m}=M^{\prime \prime} X_{j} M^{\prime}$

$$
\begin{aligned}
& \rho_{\left|m^{\prime \prime} M_{m, i, L,+}\right|_{Y}}\left(\sigma \#^{m}\left(\sigma_{m_{1}, i_{1}}, \ldots, \sigma_{\left.m_{|m|}, i_{|m|}\right)}\right) \#_{\left|m^{\prime \prime} M_{m, i, L,+}\right| Y} \Sigma\right. \\
& =\rho_{\left|m^{\prime \prime}\right|_{Y}}\left(\sigma_{m_{L}, i_{L}}\right) \# \mid m_{m^{\prime \prime} \mid}\left(\left[\rho_{\left|M^{\prime \prime}\right|_{Y}}(\sigma)\right] \#^{\bar{m}}\left(\sigma_{m_{L+1}, i_{L+1}}, \ldots, \sigma_{m_{|m|}, i_{|m|}}, \Sigma, \sigma_{m_{1}, i_{1}}, \ldots, \sigma_{m_{L-1}, i_{L-1}}\right)\right)
\end{aligned}
$$

and similarly:

$$
\begin{aligned}
& \left(\left(\rho_{\left|m^{\prime \prime} M_{m, i, L,+}\right|} \cdot\left(P \#\left(Q_{m_{1}, i_{1}}, \ldots, Q_{m_{|m|}, i_{|m|}}\right)\right)\right) \#_{\left|m^{\prime \prime} M_{m, i, L,+}\right|} d\right)= \\
& \left(\rho_{\left|m^{\prime \prime}\right|} \cdot Q_{\left.m_{L}, i_{L}\right)}\right) \#\left|m^{\prime \prime}\right| \\
& \left(\left(\rho_{\left|M^{\prime \prime}\right|}(P)\right) \#\left(Q_{m_{L+1}, i_{L+1}}, \ldots, Q_{m_{|m|}, i_{|m|}}, d, Q_{m_{1}, i_{1}}, \ldots, Q_{m_{L-1}, i_{L-1}}\right)\right) .
\end{aligned}
$$

An inspection shows that gathering these terms leads to the definition of the right hand side in (41) as expected.

Finally, we will need a second order operator and its commutation with cyclic gradients.
Proposition B.31. There are continuous maps $\Delta, \delta_{\Delta}$ on $B\{X$ : $\left.E_{D}, R\right\} \rightarrow B\left\{X: E_{D}, S\right\}$ for $S<R$ uniquely defined as weak-* continuous map by the following properties (a) and (b):
(a) For $P \in B\left\{X: E_{D}, R\right\}$ monomial

$$
\Delta(P)=\sum_{i} m \circ\left(1 \otimes E_{D} \otimes 1\right) \partial_{i} \otimes 1 \partial_{i}(P)
$$

and $\Delta E_{D}=0$
(b) $\delta_{\Delta}$ is a derivation, $\delta_{\Delta}(P)=0$ for any $P \in B\langle X: D, R\rangle$, and for $Q$ monomial in $B\left\{X: E_{D}, R\right\}, \delta_{\Delta}\left(E_{D}(Q)\right)=E_{D}\left(\left(\Delta+\delta_{\Delta}\right)(Q)\right)$.
(c) Moreover,

$$
\begin{equation*}
\mathscr{D}_{i}\left(\Delta+\delta_{\Delta}\right)=\left(\Delta+\delta_{\Delta}\right) \mathscr{D}_{i} . \tag{43}
\end{equation*}
$$

(d) Likewise, for any $V \in B\langle X: D, R\rangle$, the map $\Delta_{V}=\Delta+\sum_{i} \partial_{i}() \.# \mathscr{D}_{i} V$ produces a derivation $\delta_{V}$ such that $\delta_{V}(P)=0$ for $P \in B\langle X: D, R\rangle$ and for $Q$ monomial in $B\left\{X: E_{D}, R\right\}, \delta_{V}\left(E_{D}(Q)\right)=E_{D}\left(\left(\Delta_{V}+\delta_{V}\right)(Q)\right)$. Moreover, for any $g \in B\langle X: D, R\rangle:$

$$
\mathscr{D}_{i}\left(\Delta_{V}+\delta_{V}\right)(g)=\left(\Delta_{V}+\delta_{V}\right) \mathscr{D}_{i}(g)+\sum_{j=1}^{n} \mathscr{D}_{i, \mathscr{D}_{j} g} \mathscr{D}_{j} V
$$

Proof. Again it suffices to define those $D-D$ bimodular maps on monomials spaces, i.e., at the level of extended Haagerup tensor products. Then the universal property of the direct sum will extend them as weak-* continuous maps as soon as each component map is weak-* continuous. The algebraic relation then determines the maps on the $E_{D}$ algebra generated by $B, X_{1}, \ldots, X_{n}$ and weak-* density of this algebra implies the uniqueness of the weak-* continuous extension. For $\Delta$ we use the formula above. Let $\sigma \in N C_{2}(2 k), m \in M_{2 k}\left(X_{1}, \ldots, X_{n}, Y\right)$.

For $m=n X_{i} n^{\prime} X_{i} n^{\prime \prime}, n^{\prime} \in C(\sigma, m)$ with the notation of the previous proof, we define

$$
\begin{aligned}
\operatorname{Add}\left(\sigma, n, n^{\prime}, n^{\prime \prime}\right) & =\left\{\left\{|n|_{Y}+1,|n|_{Y}+\left|n^{\prime}\right|_{Y}+2\right\}\right\} \\
& \cup\left\{\{i+1, j+1\}:\{i, j\} \in \sigma,|n|_{Y}<i<j \leq|n|_{Y}+\left|n^{\prime}\right|_{Y}\right\} \\
& \cup\left\{\{i, j+2\}:\{i, j\} \in \sigma, i \leq|n|_{Y}<|n|_{Y}+\left|n^{\prime}\right|_{Y}<j\right\} \\
& \cup\left\{\{i, j\}:\{i, j\} \in \sigma, i<j \leq|n|_{Y}\right\} \\
& \cup\left\{\{i+2, j+2\}:\{i, j\} \in \sigma,|n|_{Y}+\left|n^{\prime}\right|_{Y}<i<j\right\} \in N C_{2}(2 k+2) .
\end{aligned}
$$

Then we define for a monomial $\epsilon_{m, \sigma}(P)$ :

$$
\left(\Delta+\delta_{\Delta}\right)\left(\epsilon_{m, \sigma}(P)\right)=\sum_{j=1}^{n} \sum_{m=n X_{j} n^{\prime} X_{j} n^{\prime \prime}, n^{\prime} \in C(\sigma, m)} \epsilon_{n Y n^{\prime} Y n^{\prime \prime}, A d d\left(\sigma, n, n^{\prime}, n^{\prime \prime}\right)}(P)
$$

All properties but the last equation (43) are easy. By definition, we have:

$$
\begin{aligned}
& \mathscr{D}_{i}\left(\left(\Delta+\delta_{\Delta}\right)\left(\epsilon_{m, \sigma}(P)\right)\right. \\
& =\sum_{j=1}^{n} \sum_{m=n X_{j} n^{\prime} X_{j} n^{\prime \prime}, n^{\prime} \in C(\sigma, m)} \sum_{n Y n^{\prime} Y n^{\prime \prime}=m^{\prime} X_{i} m^{\prime \prime}} \epsilon_{m^{\prime \prime} m^{\prime}, \rho_{\left|m^{\prime \prime}\right| Y}\left(\operatorname{Add}\left(\sigma, n, n^{\prime}, n^{\prime \prime}\right)\right)}\left(\left(\rho_{\left|m^{\prime \prime}\right|} \cdot(P)\right)\right)
\end{aligned}
$$

The sums can be divided into 3 cases depending on whether $X_{i} \in n, n^{\prime}, n^{\prime \prime}$. Similarly, we have

$$
\begin{aligned}
&\left(\Delta+\delta_{\Delta}\right) \mathscr{D}_{i}\left(\epsilon_{m, \sigma}(P)\right)= \sum_{m=M^{\prime} X_{i} M^{\prime \prime}} \sum_{j=1}^{n} \sum_{M^{\prime \prime} M^{\prime}=N X_{j} N^{\prime} X_{j} N^{\prime \prime}, N^{\prime} \in C\left(\rho_{\left|M^{\prime \prime}\right| Y}(\sigma), M^{\prime \prime} M^{\prime}\right)} \\
& \epsilon_{\left.N Y N^{\prime} Y N^{\prime \prime}, \operatorname{Add}\left(\rho_{\left|M^{\prime \prime}\right| Y}(\sigma), N, N^{\prime}, N^{\prime \prime}\right)\right)}\left(\left(\rho_{\left|M^{\prime \prime}\right|} \cdot(P)\right)\right)
\end{aligned}
$$

and there are also 3 cases depending $X_{j}$ 's are both in $M^{\prime \prime}$, in $M^{\prime}$ or one in each. The proof of the equality is combinatorial, we check we have a bijection of the indexing sets of the sum, with equality of the terms summed in each case.

If $X_{i} \in n$, then $n=o X_{i} o^{\prime}$ and $m=o X_{i} o^{\prime} X_{j} n^{\prime} X_{j} n^{\prime \prime}$ this suggests $M^{\prime}=o$, $M^{\prime \prime}=o^{\prime} X_{j} n^{\prime} X_{j} n^{\prime \prime}$ corresponding bijectively to a term where both $X_{j}$ 's are in $M^{\prime \prime}, N=o^{\prime}, N^{\prime}=n^{\prime}, N^{\prime \prime}=n^{\prime \prime} M^{\prime}, m^{\prime}=o, m^{\prime \prime}=o^{\prime} Y n^{\prime} Y n^{\prime \prime}$ so that $m^{\prime \prime} m^{\prime}=N Y N^{\prime} Y N^{\prime \prime}$ as expected, $\left|M^{\prime \prime}\right|=\left|m^{\prime \prime}\right|$ implying the same rotation of $P$ and $\left.\operatorname{Add}\left(\rho_{\left|M^{\prime \prime}\right|_{Y}}(\sigma), N, N^{\prime}, N^{\prime \prime}\right)\right)=\rho_{\left|m^{\prime \prime}\right|_{Y}}\left(\operatorname{Add}\left(\sigma, n, n^{\prime}, n^{\prime \prime}\right)\right)$, as is easily checked with the same condition on $n^{\prime}=N^{\prime}$, implying the final equality. The case $X_{i} \in n^{\prime \prime}$ is similar corresponding bijectively to the case where both $X_{j}$ 's are in $M^{\prime}$.

If $X_{i} \in n^{\prime}, n^{\prime}=o X_{i} o^{\prime}$ and $m=n X_{j} o X_{i} o^{\prime} X_{j} n^{\prime \prime}, m^{\prime}=n Y o, m^{\prime \prime}=o^{\prime} Y n^{\prime \prime}$. This suggests, $M^{\prime}=n X_{j} o, M^{\prime \prime}=o^{\prime} X_{j} n^{\prime \prime}$ corresponding bijectively to a term where one $X_{j}$ is in $M^{\prime \prime}$ the other in $M^{\prime}$ with $N=o^{\prime}, N^{\prime}=n^{\prime \prime} n, N^{\prime \prime}=o$. Since $N^{\prime \prime}$ is related to a complement of $n^{\prime}$, the relations imposed on $n^{\prime}, N^{\prime}$ are equivalent after rotation. We also have $m^{\prime \prime} m^{\prime}=N Y N^{\prime} Y N^{\prime \prime}$ as expected, $\left|M^{\prime \prime}\right|=\left|m^{\prime \prime}\right|$ implying the same rotation of $P$ and $\left.\operatorname{Add}\left(\rho_{\left|M^{\prime \prime}\right|_{Y}}(\sigma), N, N^{\prime}, N^{\prime \prime}\right)\right)=\rho_{\left|m^{\prime \prime}\right|_{Y}}\left(\operatorname{Add}\left(\sigma, n, n^{\prime}, n^{\prime \prime}\right)\right)$, as is easily checked, implying the final equality.

## B.3. Non-commutative $C^{k, l}$-functions and their stability properties.

B.3.1. $C^{k, l}$ norms. As in the main text, we consider several variants $C_{t r, V}^{k, l, \epsilon_{1}, \epsilon_{2}}\left(A, U: B, E_{D}\right), \epsilon_{1} \in\{0,1\}, \epsilon_{2} \in\{-1,0,1,2\}$ :

$$
\left.\begin{array}{l}
\|P\|_{C_{t r, V}^{k, l, \epsilon_{1}, \epsilon_{2}}\left(A, U: B, E_{D}\right)}=\|\iota(P)\|_{k, l, U}+\epsilon_{1}\left\|\left(\Delta_{V}+\delta_{V}\right)(P)\right\|_{C_{t r}^{*}(A, U)} \\
+1_{k \geq \max \left(\epsilon_{2}-1,-\epsilon_{2}\right)} \sum_{p=0}^{l-1+1_{\text {odd }}\left(\left|\epsilon_{2}\right|\right)} \sum_{i=1}^{n} \max \left[\left\|\mathscr{D}_{i, 1}(P)\right\|_{k, p, U}\right.  \tag{44}\\
\left(0 \vee \frac{\epsilon_{2}}{2}\right) \sup _{Q \in\left(C_{t r}^{k, p}\left(A, U^{m-1}: B, E_{D}\right)\right)_{1}}^{m \geq 2}
\end{array}\left\|\mathscr{D}_{i, Q\left(X^{\prime}\right)}(P)\right\|_{k, p, U^{m}}\right] .
$$

We of course also define a first order part seminorm $\|P\|_{C_{t r, V}^{k, l, \epsilon_{1}, \epsilon_{2}}\left(A, U: B, E_{D}\right), \geq 1}$ only replacing the first term in the sum by $\|\iota(P)\|_{k, l, U \geq 1}$. Note that $\|P\|_{C_{t r, V}^{k, l, 1_{k} \geq 2,2^{2}}\left(A, U: B, E_{D}\right)}=\|P\|_{C_{t r, V}^{k, l}\left(A, U: B, E_{D}\right)}$ enables to include our previous case in an ad-hoc way. We may write $C_{t r, V}^{k, l ; 0, \epsilon_{2}}\left(A, U: B, E_{D}\right)=C_{t r}^{k, l ; 0, \epsilon_{2}}\left(A, U: B, E_{D}\right)$ since there is no more dependence in $V$ in this case. [Note that we wrote $C_{t r}^{k, l ; \epsilon_{2}}\left(A, U: B, E_{D}\right)=C_{t r, V}^{k, l, 0, \epsilon_{2}}\left(A, U: B, E_{D}\right)$ for short in the text before the appendices since we only used this case $\epsilon_{1}=0$.]

In the last seminorm we considered $P$ in variable $X=\left(X_{1}, \ldots, X_{n}\right)$ and $Q$ in variable $X^{\prime}=\left(X_{(1)}^{\prime}, \ldots, X_{(m-1)}^{\prime}\right) \in U^{m-1}$ and $U^{m} \subset A_{R}^{m n}=\left(A_{R}^{n}\right)^{m}$. In order
to get a consistent definition, we still have to check the last term is finite for $P \in B_{c}\left\{X_{1}, \ldots, X_{n} ; E_{D}, R, \mathbb{C}\right\}$. We gather this and a complementary estimate in the following lemma. A variant explains the inclusion $C_{c}^{k, l} \subset C_{t r, V, c}^{k, l}$ at the end of Subsection 2.4 with norm equivalent to the restricted norm (explaining why the completions are included in one another).

Lemma B.32. Assume $U \subset A_{R, \text { app } B-E_{D}}^{n}$. For any $P \in B_{c}\left\{X_{1}, \ldots, X_{n} ; E_{D}, R, \mathbb{C}\right\}$, we have

$$
\sup _{Q \in\left(C_{t r}^{k, p}\left(\underset{\substack{U^{m-1} \\ m \geq 2}}{ } \| E_{D}\right)\right)_{1}}\left\|\mathscr{D}_{i, Q\left(X^{\prime}\right)}(P)\right\|_{k, p, U^{m}}<\infty
$$

and moreover if $P \in B_{c}\left\langle X_{1}, \ldots, X_{n} ; D, R, \mathbb{C}\right\rangle$, for any $p \geq 0$ we have:
so that we have extensions of the identity which give injective bounded linear maps:

$$
\begin{aligned}
C_{c}^{k+l}(A, U: B, D) & \rightarrow C_{t r, V}^{k, l}\left(A, U: B, E_{D}\right) \\
C_{c}^{k+l+1}(A, U: B, D) & \rightarrow C_{t r, V}^{k, l ; 0,1}\left(A, U: B, E_{D}\right),
\end{aligned}
$$

and we have for some $C>0$ :

$$
\|P\|_{C_{t r, V}^{k, l}\left(A, U: B, E_{D}\right), \geq 1} \leq C\|P\|_{k+1, l-1, U, c, \geq 1}
$$

Proof. We can assume $Q \in B_{c}\left\{X_{(1) 1}^{\prime}, \ldots, X_{(1) n}^{\prime}, \ldots, X_{(m) 1}^{\prime}, \ldots, X_{(m) n}^{\prime} ; E_{D}, R^{+}, \mathbb{C}\right\}, m \geq$ $1 X^{\prime}=X_{(1) 1}^{\prime}, \ldots, X_{(1) n}^{\prime}, \ldots, X_{(m) 1}^{\prime}, \ldots, X_{(m) n}^{\prime}$. We detail only the second estimate, since the first one mainly needs $P$ monomial and is an easy extension.

To compute differentials we introduce partial differentials $d_{\left(X, X^{\prime}\right)\left(r_{1}, \ldots, r_{s}\right)}^{s}$ so that a full differential is

$$
\sum_{r \in[1,(m+1) n]^{s}} d_{\left(X, X^{\prime}\right)\left(r_{1}, \ldots, r_{s}\right)}^{s} \mathscr{D}_{i, Q\left(X^{\prime}\right)}(P)\left(X, X^{\prime}\right) \cdot\left(H_{1}^{r_{1}}, \ldots, H_{s}^{r_{s}}\right) .
$$

Recall this $d_{\left(X, X^{\prime}\right)}^{s}$ is the full differential so that $d_{X}^{s}$ applied to $P \in$ $B_{c}\left\langle X_{1}, \ldots, X_{n} ; D, R, \mathbb{C}\right\rangle$ is a certain expression involving free difference quotients but is not necessarily 0 (unlike $d^{s}$ by its definition).

It suffices to compute on monomials, for $s, l \leq k-1$

$$
\begin{align*}
d_{\left(X, X^{\prime}\right)\left(r_{1}, \ldots, r_{s}\right)}^{s} & \left(\partial_{\left(j_{1}, \ldots, j_{k}\right)}^{l} \mathscr{D}_{i, Q\left(X^{\prime}\right)}(P)\right) \\
& =\sum_{0 \leq o \leq p \leq l}\left[d_{X R}^{\# R}\left(\rho^{-(l-p+1)} . \partial_{\left(j_{p+1}, \ldots, j_{l}, i, j_{1}, \ldots, j_{o}\right)}^{(o+l-p+1)}(P)\right)\right] \# d_{X^{\prime} R^{\prime}}^{\# R^{\prime}} \partial_{\left(j_{o+1}, \ldots, j_{p}\right)}^{(p-o)}(Q) \tag{45}
\end{align*}
$$

where $R=\left(r_{i_{1}}, \ldots, r_{i_{\# R}}\right)$ with the underlying set $u R=\left\{r_{i_{1}}, \ldots, r_{i_{\# R}}\right\}=\left\{r_{i}, r_{i} \in\right.$ $[1, n]\}, i_{1}<\ldots<i_{\# R}$ and $R^{\prime}=\left(r_{j_{1}}-n, \ldots, r_{j_{\# R^{\prime}}}-n\right)$ with $\left\{r_{j_{1}}, \ldots, r_{j_{\# R^{\prime}}}\right\}=$ $\left\{r_{1}, \ldots, r_{s}\right\}-u R j_{1}<\ldots<j_{\# R^{\prime}}$ so that $d_{\left(X, X^{\prime}\right)\left(R^{\prime}+n\right)}=d_{X^{\prime} R^{\prime}}$, and note there is no real sum to split the derivatives between $P, Q$ (the sum can contain only one non-zero term) since the variables of $Q$ and $P$ are not the same.

Using this remark and the natural bound on products defined in Proposition A.24, one gets the term in the seminorm to estimate for a fixed order $s$ of differentials $d^{s}$ :

$$
\begin{aligned}
& \left(\left\|\sum_{r \in[1,(m+1) n]^{s}} d_{\left(X, X^{\prime}\right)\left(r_{1}, \ldots, r_{s}\right)}^{s} \mathscr{D}_{i, Q\left(X^{\prime}\right)}(P)\left(X, X^{\prime}\right) .\left(H_{1}^{r_{1}}, \ldots, H_{s}^{r_{s}}\right)\right\|_{A}+\sum_{l=1}^{k}\right. \\
& \left.\sum_{j \in[1, n(m+1)]^{l}}\left\|\sum_{r \in[1,(m+1) n]^{s}} d_{\left(X, X^{\prime}\right)\left(r_{1}, \ldots, r_{s}\right)}^{s} \partial_{j}^{l} \mathscr{D}_{i, Q\left(X^{\prime}\right)}(P)\left(X, X^{\prime}\right) \cdot\left(H_{1}^{r_{1}}, \ldots, H_{s}^{r_{s}}\right)\right\| \underset{\substack{\text { eh } \\
A^{D, c}(l+1)}}{ }\right) \\
& \leq k \sum_{\substack{V \subset[1, s] \\
V=\left\{i_{1}, \ldots, i_{v}\right\} \\
V^{c}=\left\{j_{1}, \ldots, j_{s-v}\right\}}}\left(\left\|d_{X}^{v} \partial_{i} P\right\|_{\substack{\text { eh } \\
A^{D, c}}}+\sum_{l=1}^{k} \sum_{j \in[1, n]^{l}}\left\|d_{X}^{v} \partial_{(i, j)}^{l+1}(P)(X) \cdot\left(H_{i_{1}}, \ldots, H_{i_{v}}\right)\right\| \begin{array}{c}
\substack{\text { eh } \\
A^{D, c}} \\
(l+2) \\
A^{2}
\end{array}\right) \\
& \times\left(\left\|d_{X^{\prime}}^{s-v} Q\left(X^{\prime}\right)\left(H_{j_{1}}, \ldots, H_{j_{s-v}}\right)\right\|_{A}+\sum_{l=1}^{k} \sum_{j \in[1, n m]^{l}}\left\|d_{X^{\prime}}^{s-v} \partial_{j}^{l}(Q)\left(X^{\prime}\right) .\left(H_{j_{1}}, \ldots, H_{j_{s-v}}\right)\right\|_{\substack{\text { eh } \\
A^{D}, c}}(l+1) .\right.
\end{aligned}
$$

The factor $k$ appears for a the same reason as the sum over $V$, because in the sum over $j$ (resp. over $r$ ) the position of differentials $X, X^{\prime}$ need to be determined by a starting point for the block of $X^{\prime}$ variables (resp. a set of $X$ variables) and in the first case the number is less than $l \leq k$.

Thus taking suprema in the definition of seminorms, one gets the concluding result for any $p$ :

$$
\left\|\mathscr{D}_{i, Q\left(X^{\prime}\right)}(P)\right\|_{k-1, p, U^{m+1}, c} \leq(k-1) 2^{p}\|P\|_{k, p, U, c}\|Q\|_{k-1, p, U^{m}, c}
$$

and similarly

$$
\left\|\mathscr{D}_{i, Q\left(X^{\prime}\right)}(P)\right\|_{k-1, p, U^{m+1}} \leq(k-1) 2^{p}\|P\|_{k, p, U, c}\|Q\|_{k-1, p, U^{m}}
$$

The definition of the two bounded linear maps are then straightforward and injectivity comes from the fact that the bounds enable us to get equivalent norms on the image so that the separation completion defining the first space can be computed in the second.
B.3.2. Composition of functions. To understand the relationship between the Laplacian and composition of functions we need the following basic remark. Let $P, Q_{1}, \ldots, Q_{n} \in \cup_{R>0} B_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}$. Then:

$$
\begin{aligned}
\Delta(P \circ Q) & =\sum_{i, j} m \circ\left(1 \otimes E_{D} \otimes 1\right) \partial_{i} \otimes 1\left(\left(\partial_{j} P\right) \circ Q \# \partial_{i}\left(Q_{j}\right)\right) \\
& =\sum_{i, j}\left(\left(\partial_{j} P\right) \circ Q \# m \circ\left(1 \otimes E_{D} \otimes 1\right)\left(\partial_{i} \otimes 1 \partial_{i}\left(Q_{j}\right)\right)\right) \\
& +\sum_{i, j, k} m \circ\left(1 \otimes E_{D} \otimes 1\right)\left(\left(\partial_{k} \otimes 1 \partial_{j} P\right) \circ Q \#\left(\partial_{i}\left(Q_{k}\right), \partial_{i}\left(Q_{j}\right)\right)\right.
\end{aligned}
$$

Thus we have a lack of stability of the form of the second order term so that it is natural to introduce for $P \in B\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}, \mathcal{R}=\left(\mathcal{R}^{k l}\right)=\sum_{K}\left(R_{1, K}^{k l} \otimes\right.$ $\left.R_{2, K}^{k l}\right)_{k l} \in\left[\left(D^{\prime} \cap A^{\stackrel{\text { eh }}{\otimes 2} 2}\right) \widehat{\otimes}\left(D^{\prime} \cap A^{\stackrel{\text { eh }}{\otimes 2} 2}\right)\right]^{n^{2}}$ the following expression:
$\Delta_{\mathcal{R}}(P)=\sum_{i, j, K} m \circ\left(1 \otimes E_{D} \otimes 1\right)\left[\partial_{i} \otimes 1 \partial_{j}(P) \#\left(R_{1, K}^{i j}, R_{2, K}^{i j}\right)\right] \in A\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}$, and similarly

$$
(\partial(Q) \otimes \partial(Q)) \# R)^{k j}=\sum_{K, l, i}\left[\left(\partial_{i}\left(Q_{k}\right) \#\left(R_{1, K}^{i l}\right)\right] \otimes\left[\partial_{l}\left(Q_{j}\right)\right) \#\left(R_{2, K}^{i l}\right) .\right]
$$

In this way one gets

$$
\begin{equation*}
\Delta_{\mathcal{R}}(P \circ Q)=\left(\partial_{\Delta_{\mathcal{R}}(Q)} P\right) \circ Q+\Delta_{(\partial(Q) \otimes \partial(Q)) \# \mathcal{R}}(P) \circ Q \tag{46}
\end{equation*}
$$

As before we can also define $\delta_{\mathcal{R}}$ as a derivation

$$
\delta_{\mathcal{R}}: B\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\} \rightarrow A\left\{X_{1}, \ldots, X_{n}: E_{D}, R\right\}
$$

by requiring that it vanishes on $B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle \ni P$ and satisfies

$$
\delta_{\mathcal{R}}(P)=0, \quad \delta_{\mathcal{R}}\left(E_{D}(Q)\right)=E_{D}\left(\left(\Delta_{\mathcal{R}}+\delta_{\mathcal{R}}\right)(Q)\right)
$$

We consider the variants $C_{t r,(2)}^{k, l ; \epsilon_{1}, \epsilon_{2}}\left(A, U: B, E_{D}\right), \epsilon_{1} \in\{-1,0,1\}, \epsilon_{2} \in$ $\{-1,0,1,2\}, o \in \llbracket 0, \max (0, l-2) \rrbracket:$

$$
\begin{aligned}
& \|P\|_{C_{t r,(2, o)}^{k, l, \epsilon_{1}, \epsilon_{2}}\left(A, U: B, E_{D}\right)}=\|\iota(P)\|_{k, l, U}+1_{k \geq \max \left(\epsilon_{2}-1,-\epsilon_{2}\right)}^{l} \sum_{p=0}^{l-1+1_{\text {odd }}\left(\left|\epsilon_{2}\right|\right)} \sum_{i=1}^{n} \\
& \max \left[\left\|\mathscr{D}_{i, 1}(P)\right\|_{k, p, U},\right. \\
& \left.\left.\left(0 \vee \frac{\epsilon_{2}}{2}\right)^{\sup _{Q \in\left(C_{t r}^{k, p}\left(A, U^{m-1}: B, E_{D}\right)\right)_{1}}^{m \geq 2}} \right\rvert\,\left\|\mathscr{D}_{i, Q\left(X^{\prime}\right)}(P)\right\|_{k, p, U^{m}}\right]
\end{aligned}
$$

$$
\begin{aligned}
& \left.\left(0 \vee\left(-\epsilon_{1}\right)\right)\left\|\left(\Delta+\delta_{\Delta}\right)(P)\right\|_{0, o, U}\right] .
\end{aligned}
$$

Finally to deal with our universal norms we need to consider in what space of variables our functions are valued to handle composition properly. For this consider $U \subset A_{R}^{n}, V \subset A_{S}^{n}$ sets, $S \geq R$ and $C$ a class of functions on $U$ as before or one defined later, $B_{C}$ the space of analytic function (either $B_{c}\left\{X_{1}, \ldots, X_{n} ; E_{D}, R^{+}, \mathbb{C}\right\}$ for classes with index $\operatorname{tr}$ or $B_{c}\langle X: D, R, \mathbb{C}\rangle$ or $\cap_{T>R} C_{b}^{l+1}\left(A_{R}^{n}, B_{c}\left\langle X_{1}, \ldots, X_{n}\right.\right.$ : $D, T, \mathbb{C}\rangle$ ) for classes with index $u$ etc.) used to define it as a separation-completion with canonical map $\iota: B_{C} \rightarrow C$. We define two candidates of sets admissible for composition

$$
\begin{gathered}
\operatorname{Comp}(U, V, C)=\left\{Q=\left(Q_{1}, \ldots, Q_{n}\right) \in C^{n}, \forall X \in U, Q(X) \in V\right\} \\
\operatorname{Comp}^{-}(U, V, C)=\operatorname{Comp}(U, V, C) \cap{\left.\overline{\operatorname{Comp}}(U, V, C) \cap\left(\iota\left(B_{C}\right)\right)^{n}\right)}^{C^{n}}
\end{gathered}
$$

which are subspaces of $\operatorname{Comp}\left(U, A_{S}^{n}, C\right)$. We first define composition on the dense subspace of $Q_{i} \in \cap_{T>R} C_{b}^{l+1}\left(U, B_{c}\langle X: D, T, \mathbb{C}\rangle\right)$, with $Q(X) \in V$ for all $X \in U$, for $P \in \cap_{T>S} C_{b}^{l+1}\left(V, B_{c}\langle X: D, T, \mathbb{C}\rangle\right)$ by

$$
P\left(Q_{1}, \ldots, Q_{n}\right): X \in U \mapsto P\left[\left(Q_{1}(X), \ldots, Q_{n}(X)\right)\right]\left(Q_{1}[X], \ldots, Q_{n}[X]\right)
$$

where $P\left[\left(Q_{1}(X), \ldots, Q_{n}(X)\right)\right] \in \cap_{T>S} B_{c}\left\langle X: E_{D}, S, \mathbb{C}\right\rangle$ is then composed with $Q_{i}[X] \in B_{c}\left\langle X: E_{D}, R\right\rangle$, since $\left\|Q_{i}[X]\right\| \leq T$ for some $T \geq S$ one can apply the definition of composition at analytic level from Propositions B.25, B.29.

If $P \in B_{c}\left\{X_{1}, \ldots, X_{n} ; E_{D}, S^{+}, \mathbb{C}\right\}, P$ defines $X \mapsto P\left(E_{D, X}\right)$ on any $V \subset A_{S}^{n}$, so that we can define $P\left(Q_{1}, \ldots, Q_{n}\right)$ assuming only $\left\|Q_{i}(X)\right\|<S$ (case $V=A_{S}^{n}$ above).

We can now extend these maps. We first deal with the cases of stability by compositions and then deal with the variants we used in the main texts obtained via various compositions with canonical maps.

Lemma B.33. Fix $V, U$ as above with $U \subset V$ (with $V \subset A_{R, U l t r a A p p}^{n}$ as soon as a space with index $c$ is involved). The above map $\left(P, Q_{1}, \ldots, Q_{n}\right) \mapsto P\left(Q_{1}, \ldots, Q_{n}\right)$ extends continuously to $Q_{1}, \ldots, Q_{n} \in \operatorname{Comp}^{-}\left(U, V, C_{u}^{k, l}\left(A, U: B, E_{D}\right)\right)$ to give a map

$$
C_{u}^{k, l}\left(A, V: B, E_{D}\right) \times \operatorname{Comp}^{-}\left(U, V,\left(C_{u}^{k, l}\left(A, U: B, E_{D}\right)\right)\right) \rightarrow C_{u}^{k, l}\left(A, U: B, E_{D}\right),
$$

for $k \geq l$. Moreover, for any $(k, l) \in I N^{2}$, it also extends continuously consistently to

$$
\begin{gathered}
C_{t r}^{k, l}\left(A, V: B, E_{D}\right) \times \operatorname{Comp}\left(U, V,\left(C_{t r}^{k, l}\left(A, U: B, E_{D}\right)\right)\right) \rightarrow C_{t r}^{k, l}\left(A, U: B, E_{D}\right), \\
C_{t r, c}^{k, l}\left(A, V: B, E_{D}\right) \times \operatorname{Comp}\left(U, V,\left(C_{t r, c}^{k, l}\left(A, U: B, E_{D}\right)\right)\right) \rightarrow C_{t r, c}^{k, l}\left(A, U: B, E_{D}\right), \\
C_{t r}^{k, l ; 0, \epsilon_{2}}\left(A, V: B, E_{D}\right) \times \operatorname{Comp}\left(U, V,\left(C_{t r}^{k, l ; 0,1 \vee \epsilon_{2}}\left(A, U: B, E_{D}\right)\right)\right) \rightarrow C_{t r}^{k, l ; 0, \epsilon_{2}}\left(A, U: B, E_{D}\right), \\
C_{t r,(2, o)}^{k, l ; 1, \epsilon_{2}}\left(A, V: B, E_{D}\right) \times \operatorname{Comp}\left(U, V,\left(C_{t r,(2, o)}^{k, l ; \epsilon_{1}, 1 \vee \epsilon_{2}}\left(A, U: B, E_{D}\right)\right)\right) \rightarrow C_{t r,(2, o)}^{k, l ; \epsilon_{1}, \epsilon_{2}}\left(A, U: B, E_{D}\right),
\end{gathered}
$$

$\epsilon_{1} \in\{-1,1\}, \epsilon_{2} \in\{-1,0,1,2\}, o=0$ and with the constraint $k, l \geq 1$ in case $\epsilon_{1}=1$. Finally, for $P \in C_{u}^{k, l+1}\left(A, V: B, E_{D}\right)\left(Q_{1}, \ldots, Q_{n}\right) \mapsto P\left(Q_{1}, \ldots, Q_{n}\right)$ is Lipschitz on bounded sets of $C o m p^{-}\left(U, V, C_{u}^{k, l}\left(A, U: B, E_{D}\right)\right)$ with corresponding statements on all other spaces in adding to the $P$ variable only 1 more derivative to $l$ and to o. Moreover, the Lipschitz property is uniform on bounded sets for $P$ in the space it can be taken.

Although the case $o \in \llbracket 1, \max (0, l-1) \rrbracket$ is not needed in this paper, it can be treated similarly but this is left to the reader.

Proof. Note first that for composition on $C o m p^{-}$we can extend the first definition of composition since then we have approximate $Q \in \iota(B)^{n}$ with $Q(X) \in V$. For all extension to Comp we use the second definition since we can start from $P \in B_{c}\left\{X_{1}, \ldots, X_{n} ; E_{D}, S^{+}, \mathbb{C}\right\}$ by density in the corresponding spaces. As we will see, we will always extend first in $Q$, and for $P$ fixed as above this extension can be done with $V=A_{S}^{n}$, using $\operatorname{Comp}\left(U, A_{S}^{n}, C\right)=\operatorname{Comp}^{-}\left(U, A_{S}^{n}, C\right)$ (since $A_{S}^{n}$ open and using compatibility with the topology of considered $C$ ) and then restrict this first extension to our space $\operatorname{Comp}(U, V, C) \subset \operatorname{Comp}\left(U, A_{S}^{n}, C\right)$. We have to estimate various norms using (40) and (42) (and its variant which is the elementary
differentiation of composition of functions):

$$
\begin{align*}
& d_{X\left(r_{1}, \ldots, r_{s}\right)}^{s}\left(\partial_{\left(j_{1}, \ldots, j_{k}\right)}^{k} P\left(Q_{1}, \ldots Q_{n}\right)\right) \\
& =\sum_{l=1}^{k} \sum_{n_{1}, \ldots, n_{l}} \sum_{1 \leq i_{1}<\ldots<i_{l}=k} d_{X\left(r_{1}, \ldots, r_{s}\right)}^{s}\left[\left(\partial_{\left(n_{1}, \ldots, n_{l}\right)}^{l}(P)\right)\left(Q_{1}, \ldots Q_{n}\right)\right. \\
& \left.\#\left(\partial_{\left(j_{1}, \ldots, j_{i_{1}}\right)}^{i_{1}} Q_{n_{1}}, \partial_{\left(j_{i_{1}+1}, \ldots, j_{2}\right)}^{i_{2}-i_{1}} Q_{n_{2}}, \ldots, \partial_{\left(j_{i_{l-1}+1}, \ldots, j_{k}\right)}^{k-i_{l-1}} Q_{n_{l}}\right)\right] \\
& =\sum_{l=1}^{k} \sum_{n_{1}, \ldots, n_{l}} \sum_{1 \leq i_{1}<\ldots<i_{l}=k} \sum_{V=\left\{\left\{t_{0,1}<\ldots<t_{0, u_{0}}\right\}, \ldots\left\{t_{l, 1}<\ldots<t_{1, u_{l}}\right\} \in \operatorname{Part}([1, s])\right\}} \\
& \sum_{m=1}^{u_{0}} \sum_{o_{1}, \ldots, o_{m}} \sum_{1 \leq j_{1}<\ldots<j_{m}=u_{0}}  \tag{47}\\
& \sum_{L \in \operatorname{Part}\left(\left[1, u_{0}\right]\right): L_{1,1}=1, L_{.-1,1}<L_{., 1}}\left[\left[d_{X\left(o_{1}, \ldots, o_{m}\right)}^{m}\left(\partial_{\left(n_{1}, \ldots, n_{l}\right)}^{l}(P)\right)\left(Q_{1}, \ldots Q_{n}\right)\right.\right. \\
& \left.\left.\circ\left(d_{X\left(r_{t_{0, L}, 1}, \ldots, r_{\left.t_{0, L} L_{1, j_{1}}\right)}^{j_{1}}\right.}^{j_{o_{1}}},, \ldots, d_{X\left(r_{t_{0, L_{m}, 1}}, \ldots, r_{\left.t_{0, L_{m}, u_{0}-j_{m-1}}\right)}^{u_{0}-j_{m-1}}\right.} Q_{o_{m}}\right)\right)\right] \\
& \left.\#\left(d_{X\left(r_{t_{1,1}}, \ldots, r_{t_{1, u_{1}}}\right)}^{u_{1}} \partial_{\left(j_{1}, \ldots, j_{i_{1}}\right)}^{i_{1}} Q_{n_{1}}, \ldots, d_{X\left(r_{t_{l, 1}}, \ldots, r_{\left.t_{l, u_{l}}\right)}^{u_{l}}\right.}^{u_{l}} \partial_{\left(j_{i_{l-1}+1}, \ldots, j_{k}\right)}^{k-i_{l-1}} Q_{n_{l}}\right)\right]
\end{align*}
$$

(the sum over $V$ runs over partitions of $[1, s]$ (not ordered) and the sum over $L=$ $\left.\left\{\left\{L_{1,1}<\ldots<L_{1, j_{1}}\right\}, \cdots,\left\{L_{m-1,1}<L_{m, 1}<\ldots<L_{m, j_{m}-j_{m-1}}\right\}\right\}\right), L_{.-1,1}<L_{., 1}$ over partitions $\operatorname{Part}\left(\left[1, u_{0}\right]\right)$ of $\left[1, u_{0}\right]$ with the extra inequalities written ordering the blocks of the partitions by the index of the smallest element). Now for $P \in \cap_{T>S} C_{b}^{l+1}\left(A_{S}^{n}, B_{c}\langle X: D, T, \mathbb{C}\rangle\right)$, one checks (using we started from one more derivative on $U$ than necessary, namely $l+1$ instead of $l$ ) that $\left(Q_{1}, \ldots, Q_{n}\right) \mapsto$ $P\left(Q_{1}, \ldots, Q_{n}\right)$ is uniformly continuous (on balls) thus extends by uniform continuity to $C o m p^{-}\left(U, V, C_{u}^{k, l}\left(A, U: B, E_{D}\right)\right)$.

Obviously, if one does not care about constants, we have from the previous computation, a bound of the form

$$
\left\|P\left(Q_{1}, \ldots, Q_{n}\right)\right\|_{k, l, U} \leq C(k, l, n)\|P\|_{k, l, V}\left(1+\max _{i=1, \ldots, n}\left\|Q_{i}\right\|_{k, l, U}\right)^{k+l}
$$

thus $P \mapsto P\left(Q_{1}, \ldots, Q_{n}\right)$ is Lipschitz with value in the space continuous functions with supremum norm on $Q_{i}$ and thus extend to all $P$ in the space $C_{u}^{k, l}(A, V$ : $\left.B, E_{D}\right)$. This concludes to the extension part. Note that one deduces from the computations above the estimate of independent interest :
$\left\|P\left(Q_{1}, \ldots, Q_{n}\right)\right\|_{k, l, U, \geq 1} \leq C(k, l, n)\|P\|_{k, l, V, \geq 1}\left(1+\max _{i=1, \ldots, n}\left\|Q_{i}\right\|_{k, l, U}\right)^{k+l-1} \max _{i=1, \ldots, n}\left\|Q_{i}\right\|_{k, l, U, \geq 1}$
For the Lipschitz property, the only problematic term in the expression above is the composition $d_{X\left(r_{1}, \ldots, r_{s}\right)}^{s}\left[\left(\partial_{\left(o_{1}, \ldots, o_{l}\right)}^{l}(P)\right)\left(Q_{1}, \ldots, Q_{n}\right)\right.$. We note that under the supplementary assumption of differentiability for $P$, it is always differentiable with
differential

$$
\sum_{i} d_{X\left(r_{1}, \ldots, r_{s}, i\right)}^{s+1}\left[\left(\partial_{\left(n_{1}, \ldots, n_{l}\right)}^{l}(P)\right)\left(Q_{1}, \ldots, Q_{n}\right)\left(\cdot, \ldots, \cdot, H_{i}\right)\right.
$$

The conclusion follows by the fundamental Theorem of calculus.
Now, the case of $C_{t r}^{k, l}$ spaces is obvious because $P\left(Q_{1}, \ldots, Q_{n}\right)$ exactly comes from the composition in Proposition B. 29 and the discussion at the beginning of the proof to deal with Comp. $C_{t r, c}^{k, l}$ is also a variant.

We now turn to the spaces $C_{t r}^{k, l ; 0, \epsilon_{2}}$ first with $\epsilon_{2}=1$. For $P$ fixed and analytic, the extension in $Q_{i}$ is the same as before (using the estimate below); it remains to prove the uniform Lipschitz property in $P$. Recall the basic formula (41) and since in our case $\mathscr{D}_{Q_{i}, R}(P)\left(Q_{1}, \ldots, Q_{n}\right) \in C_{t r}^{k, l}\left(A, U^{m-1}: B, E_{D}\right)$ we have the following bound for $p \leq l$ :

$$
\left.\begin{array}{rl}
\sup _{R \in\left(C_{t r}^{k, p}\left(A, U^{m-1}: B, E_{D}\right)\right)_{1}} & \left\|\mathscr{D}_{i, R\left(X^{\prime}\right)}\left(P\left(Q_{1}, \ldots, Q_{n}\right)\right)\right\|_{k, p, U^{m}} \\
& \left.\leq \sum_{j=1}^{n} \sup _{S \in\left(C_{t r}^{k, p}\left(A, U^{m}: B, E_{D}\right)\right)_{1}} \| \mathscr{D}_{i, S\left(X^{\prime \prime}\right)}\left(Q_{j}\right)\right) \|_{k, p, U^{m+1}} \\
& \sup \| \in\left(C_{t r}^{k, p}\left(A, U^{m-1}: B, E_{D}\right)\right)_{1} \tag{49}
\end{array} \mathscr{D}_{Q_{j}, R\left(X^{\prime}\right)}(P)\left(Q_{1}, \ldots Q_{n}\right) \|_{k, p, U^{m}}\right)
$$

where we took the variables $S=\mathscr{D}_{Q_{j}, R\left(X^{\prime}\right)}(P)\left(Q_{1}, \ldots Q_{n}\right), X^{\prime \prime}=\left(X^{\prime}, X\right) \in U^{m}$, and used $\left.\left.\| \mathscr{D}_{i, \mathscr{D}_{Q_{j}, R\left(X^{\prime}\right)}(P)\left(Q_{1}, \ldots Q_{n}\right)}\left(Q_{j}\right)\right)\left\|_{k-1, p, U^{m}} \leq\right\| \mathscr{D}_{i, S\left(X^{\prime \prime}\right)}\left(Q_{j}\right)\right) \|_{k-1, p, U^{m+1}}$. And from a variant with parameter of our previous estimates for the change of variable $\left(Q_{1}(X), \ldots, Q_{n}(X), X^{\prime}\right)$ (based on the fact that no additional sum related to composition is involved for the variables $X^{\prime}$ so that the constant $C(k-1, p, n)$ below only involves the number of variables of $X$ ), the last term is bounded by

$$
\begin{aligned}
\| \mathscr{D}_{Q_{j}, R\left(X^{\prime}\right)} & (P)\left(Q_{1}, \ldots Q_{n}\right) \|_{k, p, U^{m}} \\
& \leq C(k, p, n)\left\|\mathscr{D}_{X_{j}, R\left(X^{\prime}\right)}(P)\right\|_{k, p, V \times U^{m-1}}\left(1+\max _{i=1, \ldots, n}\left(\left\|Q_{i}\right\|_{k, p, U}\right)\right)^{p+k} .
\end{aligned}
$$

This gives the expected Lipschitz bound in $P$ (using $U \subset V$ in taking $Q_{j}(X)=X_{j}$ ) for the part with cyclic gradients. The Lipschitz property in $Q$ is dealt with as before.

We now consider the case $\epsilon_{2}=0$. In this case the norm becomes

$$
\|P\|_{C_{t r, V}^{k, l, \epsilon_{1}, 0}\left(A, U: B, E_{D}\right)}=\|\iota(P)\|_{k, l, U}+\epsilon_{1}\left\|\left(\Delta_{V}+\delta_{V}\right)(P)\right\|_{C_{t r}^{*}(A, U)}+\sum_{p=0}^{l-1} \sum_{i=1}^{n}\left\|\mathscr{D}_{i, 1}(P)\right\|_{k, p, U}
$$

and thus we can use the estimate (49) with $R=1$ to establish the result.
We now turn to the case $\epsilon_{2}=-1$. In this case the norm becomes

$$
\|P\|_{C_{t r, V}^{k, l, \epsilon_{1},-1}\left(A, U: B, E_{D}\right)}=\|\iota(P)\|_{k, l, U}+\epsilon_{1}\left\|\left(\Delta_{V}+\delta_{V}\right)(P)\right\|_{C_{t r}^{*}(A, U)}+1_{k \geq 1} \sum_{p=0}^{l} \sum_{i=1}^{n}\left\|\mathscr{D}_{i, 1}(P)\right\|_{k, p, U}
$$

The term $\sum_{p=0}^{l} \sum_{i=1}^{n}\left\|\mathscr{D}_{i, 1}(P)\right\|_{k, p, U}$ is controlled by the similar term (with summation up to $l$ ) in (44) which gives the norm of $Q$ (noting that $\epsilon_{2} \vee 1=1$ ). The other terms are treated as before.

Finally, we consider the case $\epsilon_{2}=2$. This time $1 \vee \epsilon_{2}=2$ and the summation over $p$ goes up to $l-1$; thus we can use essentially the same estimate as in (49) in this case.

It remains to deal with the case $\epsilon_{1}=1$ with $o=0$. Based on (46)

$$
\begin{aligned}
\left(\Delta_{\mathcal{R}}+\delta_{\mathcal{R}}\right)(P \circ Q) & =\left(d_{Q(X)} P\left(E_{D, Q(X)}\right) \cdot\left(\Delta_{\mathcal{R}}+\delta_{\mathcal{R}}\right)(Q)\right) \\
& +\left[\Delta_{(\partial Q \otimes \partial Q) \# \mathcal{R})}+\delta_{(\partial Q \otimes \partial Q) \# \mathcal{R})}\right](P)\left(E_{D, Q(X)}\right)(Q(X)) .
\end{aligned}
$$

Hence one gets:

$$
\begin{aligned}
& \left\|\mathcal{R}_{\substack{k l}} \sup _{\substack{\text { eh } \\
\left[\left(D^{\prime} \cap A D^{2}\right) \hat{\otimes}\left(D^{\prime} \cap A D^{2}\right)\right]}}^{\substack{\text { eh } \\
\Phi^{2}}} \leq 1 /\left(\Delta_{\mathcal{R}}+\delta_{\mathcal{R}}\right)(P \circ Q)\right\|_{C_{t r}^{*}(A, U)}
\end{aligned}
$$

This enables the extension in $P$ after extension in $Q$ if $k, l \geq 1$ and gives the Lipschitz property in $Q$ on bounded sets as required (replacing $o$ with $o+1$ to deal with the annoying new term). The case $\epsilon_{1}=-1$ is possible because taking $\mathcal{R}^{k l}=1_{k=l}(1 \otimes 1) \otimes(1 \otimes 1)$ recovers the Laplacian and using a general $\mathcal{R}$ on the $P$ variable enables to deal with the particular case (and remove the sup) for $Q, P \circ Q$ variables.

Corollary B.34. In the setting of the previous Lemma (in particular for $U \subset$ $V \subset A_{R, \text { UltraApp }}^{n}$ ), for any $l \geq 1$ (and $k \geq 2$ in any case with $W$ ) the map $\left(P, Q_{1}, \ldots, Q_{n}\right) \mapsto P\left(Q_{1}, \ldots, Q_{n}\right)$ also extends continuously consistently to

$$
\begin{aligned}
& C_{c}^{k+l}(A, V: B, D) \times \operatorname{Comp}\left(U, V,\left(C_{t r, W}^{k, l}\left(A, U: B, E_{D}\right)\right)\right) \rightarrow C_{t r, W}^{k, l}\left(A, U: B, E_{D}\right), \\
& C_{c}^{k+l}(A, V: B, D) \times \operatorname{Comp}\left(U, V,\left(C_{t r, W, c}^{k, l}\left(A, U: B, E_{D}\right)\right)\right) \rightarrow C_{t r, W, c}^{k, l}\left(A, U: B, E_{D}\right), \\
& \quad C_{c}^{l}(A, V: B, D) \times \operatorname{Comp}\left(U, V,\left(C_{c}^{l}(A, U: B, D)\right)\right) \rightarrow C_{c}^{l}(A, U: B, D) \\
& C_{t r}^{k, l ; 0,-1}\left(A, V: B, E_{D}\right) \times \operatorname{Comp}\left(U, V,\left(C_{c}^{k+l+1}(A, U: B, D)\right)\right) \rightarrow C_{t r}^{k, l ; 0,-1}\left(A, U: B, E_{D}\right),
\end{aligned}
$$

Similarly as before if we require one more derivative in $P$ in the l variable, one gets the Lipschitz property on bounded sets in the space for $Q$.

Proof. This is a consequence of the previous result using the canonical maps $: C_{c}^{k+l}(A, V: B, D) \rightarrow C_{t r,(2,0)}^{k, l ; 1,2}\left(A, V: B, E_{D}\right), C_{t r, W}^{k, l}\left(A, U: B, E_{D}\right) \rightarrow$ $C_{t r,(2,0)}^{k, l ;-1,2}\left(A, V: B, E_{D}\right)$, for $k \geq 2, l \geq 1$, and $C_{c}^{k+l+1}(A, U: B, D) \rightarrow C_{t r}^{k, l ; 0,1}(A, U:$ $\left.B, E_{D}\right)$, from Lemma B.32.

The last variant for $C_{c}^{k}(A, U: B, D)$ follows, since it is defined as a subspace with equivalent norm with respect to the previous space (with $l=0$ ) and thus a consequence of stability of analytic functions (without expectation) by composition.

A routine computation shows that

$$
\begin{equation*}
\sum_{i=1}^{n} \tau\left(\mathscr{D}_{i, e}(P)\left(E_{D, X}\right)(X) H_{i}\right)=\tau\left(e\left[d_{X} P\left(E_{D, X}\right) \cdot\left(H_{1}, \ldots, H_{n}\right)\right]\right) \tag{50}
\end{equation*}
$$

Note that (50) extends for $e=1$ to $C_{t r, V}^{k, l ; \epsilon_{1}, \epsilon_{2}}\left(A, U: B, E_{D}\right), X \in U$ as soon as $l \geq 1$.

We will need later the following consequence of Proposition B.31.
Let us define the first space introducing a conjugate variable assumption that will be frequently used in the next subsection:

$$
A_{R, c o n j}^{n}=\left\{X \in A_{R, U l t r a A p p}^{n}, \partial_{i}^{*}(1 \otimes 1) \in W^{*}(X), i=1, \ldots, n\right\}
$$

Lemma B.35. Let $U \subset A_{R, c o n j}^{n}$.
(1) Let $V \in C_{c}^{1}\left(A, A_{R, \text { conj }}^{n}: B, D\right)$. For $g \in B\left\{X_{1}, \ldots, X_{n}: E_{D}, S, \mathbb{C}\right\}, X=$ $\left(X_{1}, \ldots, X_{n}\right) \in A_{R, \text { conj }}^{n}, \xi_{i}=\partial_{i}^{*} 1 \otimes 1, \xi=\left(\xi_{1}, \ldots, \xi_{n}\right)$ the conjugate variables of $X$ relative to $E_{D}$ in presence of $B$, then

$$
\left(\delta_{V}(g)\right)\left(E_{X, D}\right)=d g\left(E_{X, D}\right) \cdot\left(\xi-\mathscr{D} V\left(X_{1}, \ldots, X_{n}\right)\right)
$$

and this extends to $g \in C_{t r, V}^{k, l}(A, U), k \geq 2, l \geq 1$.
(2) Let $k \in\{0,1,2,3\}, V \in C_{c}^{k+1}\left(A, A_{R, c o n j}^{n}: B, D\right)$. For any $g \in C_{t r, V}^{k+2,2}(A, U$ : $\left.B, E_{D}\right)$, we have $h=\left(\Delta_{V}+\delta_{V}\right)(g) \in C_{t r, V}^{k, 0 ; 0,-1}\left(A, U \cap A_{R, \text { conj }}^{n}: B, E_{D}\right),\left(\mathscr{D}_{i} g\right) \in$ $C_{t r}^{k+2,1}\left(A, U \cap A_{R, \text { conj }}: B, E_{D}\right)$ and we have equality in $C_{t r}^{k, 0}\left(A, U \cap A_{R, c o n j}\right.$ : $\left.B, E_{D}\right)$ :

$$
\mathscr{D}_{i} h=\left(\Delta_{V}+\delta_{V}\right)\left(\mathscr{D}_{i} g\right)-\sum_{j=1}^{n} \mathscr{D}_{i, \mathscr{D}_{j} g} \mathscr{D}_{j} V
$$

Proof. (1) Because of the norm continuity of the various maps, by density, the first assertion needs only to be checked for $V=0$ and $g=P$ a monomial. By the standard form of tensor products in extended Haagerup tensor products [M05, (2.4), (2.5)], one can even reduce terms in those tensor products to finite linear combinations of products. Thus it suffices to check this on the algebra generated by $B, X_{1}, \ldots, X_{n}$ where this is then an easy consequence of the definition of conjugate variables. The extension to $C_{t r, V}^{k, l}(A, U), k \geq 2, l \geq 1$ is obvious by norm continuity of the various maps.
(2) We first need to extend (14) to $V \in C_{c}^{k+1}\left(A, A_{R, \text { conj }}^{n}: B, D\right)$, still for $g=P \in$ $B_{c}\left\{X_{1}, \ldots, X_{n}: E_{D}, R, \mathbb{C}\right\}$. If one uses the notation after this formula extending the definition of $\Delta_{V}+\delta_{V}$ to these values of $V$ and notes from the formula (41) for cyclic gradient of compositions above (extended beyond analytic functions since $\left[\Delta_{V_{0}(Z)}+\delta_{V_{0}(Z)}\right](P)$ is a non-commutative analytic function with expectation and we can use the composition lemma as in the proof of Proposition 9), one gets the
expected relation:

$$
\begin{aligned}
& \mathscr{D}_{X_{i}}\left(\left[\Delta_{V_{0}(Z)}+\right.\right.\left.\left.\delta_{V_{0}(Z)}\right](P)(X, \mathscr{D} V(X))\right)=\left(\mathscr{D}_{X_{i}}\left[\Delta_{V_{0}(Z)}+\delta_{V_{0}(Z)}\right](P)\right)(X, \mathscr{D} V(X)) \\
&+\sum_{j=1}^{n}\left(\mathscr{D}_{X_{i}, \mathscr{D}_{Z_{j}}\left(\left[\Delta_{V_{0}(Z)}+\delta_{V_{0}(Z)}\right](P)\right)} \mathscr{D}_{X_{j}} V(X)\right) \\
&=\left(\left[\Delta_{V_{0}(Z)}+\delta_{V_{0}(Z)}\right]\left(\mathscr{D}_{X_{i}} P\right)\right)(X, \mathscr{D} V(X))+\sum_{j=1}^{n}\left(\mathscr{D}_{\left.X_{i}, \mathscr{D}_{X_{j}}(P)\right)} \mathscr{D}_{X_{j}} V(X)\right),
\end{aligned}
$$

where we used (14) for the extra variables $Z$ to get

$$
\begin{aligned}
\mathscr{D}_{Z_{j}}\left(\left[\Delta_{V_{0}(Z)}+\delta_{V_{0}(Z)}\right](P)\right) & =\left[\Delta_{V_{0}(Z)}+\delta_{V_{0}(Z)}\right]\left(\mathscr{D}_{Z_{j}} P\right)+\sum_{k=1}^{n} \mathscr{D}_{Z_{j}, \mathscr{D}_{j} P} \mathscr{D}_{Z_{k}} V_{0}(Z) \\
& =\mathscr{D}_{j} P
\end{aligned}
$$

since $\mathscr{D}_{Z_{j}} P=0$ and similarly

$$
\mathscr{D}_{X_{i}}\left[\Delta_{V_{0}(Z)}+\delta_{V_{0}(Z)}\right](P)=\left[\Delta_{V_{0}(Z)}+\delta_{V_{0}(Z)}\right] \mathscr{D}_{X_{i}}(P),
$$

since $\mathscr{D}_{X_{i}} V_{0}=0$.
It now remains to extend the relation in $P$ to apply it to our $g$.
For the second statement we check that the map $g \mapsto\left(\Delta_{V}+\delta_{V}\right)(g)$ is bounded for $g$ analytic function with expectation between the spaces

$$
\Delta_{V}+\delta_{V}: C_{t r, V}^{k+2,2}\left(A, U: B, E_{D}\right) \rightarrow C_{t r, V}^{k, 0 ; 0,-1}\left(A, U \cap A_{R, c o n j 1}^{n}: B, E_{D}\right)
$$

where the identity has just been checked. We need to bound the $k$-th order free difference quotient of $h$ and $\mathscr{D} h$. We use the fact that $\mathscr{D} g$ is controlled in $C^{k+2,1}\left(A, U: B, E_{D}\right)$ thus by closability we can apply a $k$-th order free difference quotients to the relation for $\mathscr{D} h$ (using Lemma B. 32 for the term with second order derivative on $V$ ). We can also apply a $k$-th order free difference quotient to the formula for $h$, each time using the relation for $\delta_{V}(g)$ in terms of differential. The bounds are now easy using for the term $\partial \delta_{V}$ the identity checked before in (1) in any representation for $\delta_{V}$ and commutation of $\partial$ and $d$.
B.4. Free difference quotient with value in extended Haagerup tensor products. We now consider closability properties of the free difference quotient with value in the extended Haagerup tensor product.

For later use we consider variants of the spaces considered in subsection 3.3: $A_{R, \text { conj0 }}^{n}=A_{R, U l t r a A p p}^{n}, A_{R, c o n j}^{n}=A_{M, c o n j 1}^{n}$ with all conjugate variables relative to $B, E_{D}$ :

$$
\begin{aligned}
& A_{R, \operatorname{conj}(1 / 2)}^{n}=\left\{X \in A_{R, \text { conj0 }}^{n}, \partial_{i}^{*}(1 \otimes 1) \in L^{2}\left(W^{*}(X)\right), i=1, \ldots, n\right\}, \\
& A_{M, \text { conj } 2}^{n}=\left\{X \in A_{R, \text { conj }}^{n}, \partial_{i}^{*}\left(\partial_{i}^{*}(1 \otimes 1) \otimes 1\right) \in W^{*}(X), i=1, \ldots, n\right\}
\end{aligned}
$$

They are motivated by the various cases in the next lemma:
Lemma B.36. Let $M=W^{*}\left(X_{1}, \ldots, X_{n}, B\right)$ for $\left(X_{1}, \ldots, X_{n}\right) \in(A, \tau)$.
(1) If $\left(X_{1}, \ldots, X_{n}\right) \in(A, \tau)$ have conjugate variables $\left(\partial_{1}^{*} 1 \otimes 1, \ldots, \partial_{n}^{*} 1 \otimes 1\right) \in$ $L^{2}(M, \tau)$ relative to $B, E_{D}$ then the unbounded densely defined operator

$$
\partial_{i}: M \rightarrow M \stackrel{\stackrel{\mathrm{eh}}{\otimes}}{\underset{D}{\otimes}} M
$$

is weak-* closable with closure ${\overline{\partial_{i}}}^{\text {eh }}$. Moreover, $\partial_{i} \otimes_{D} 1,1 \otimes_{D} \partial_{i}$ are weak-* closable $M \stackrel{\text { eh }}{\stackrel{\mathrm{eh}}{\otimes}} M \rightarrow M \stackrel{\mathrm{eh}}{\otimes} M \stackrel{\mathrm{eh}}{\otimes} M$, and the closures are derivations for the natural multiplication: for $U \in M \stackrel{\text { eh }}{\otimes}$ D $M, V \in D^{\prime} \cap M \stackrel{\text { eh }}{\otimes} M$, with $U, V \in D\left({\overline{\partial_{i} \otimes_{D} 1}}^{e h}\right)$ (resp. $U, V \in D\left({\overline{1 \otimes_{D} \partial_{i}}}^{e h}\right)$ ) so is $U \# V$ and

$$
{\overline{\partial_{i} \otimes_{D} 1}}^{e h}(U \# V)={\overline{\partial_{i} \otimes_{D} 1}}^{e h}(U) \#_{2} V+U \#{\overline{\partial_{i} \otimes_{D} 1}}^{e h}(V)
$$

$\left(r e s p .{\overline{1 \otimes_{D} \partial_{i}}}^{e h}(U \# V)={\overline{1 \otimes_{D} \partial_{i}}}^{e h}(U) \#_{1} V+U \#{\overline{1 \otimes_{D} \partial_{i}}}^{e h}(V)\right)$.
(2) If $\left(X_{1}, \ldots, X_{n}\right) \in(A, \tau)$ have conjugate variables $\left(\partial_{1}^{*} 1 \otimes 1, \ldots, \partial_{n}^{*} 1 \otimes 1\right) \in$ $L^{2}(M, \tau)$ then $\left(1 \otimes E_{D}\right) \partial_{i}$ extends to a bounded operator from $M$ to $\left.L^{2}(M), \tau\right)$ or from $L^{2}(M, \tau)$ to $L^{1}(M, \tau)$. If moreover $\left(X_{1}, \ldots, X_{n}\right) \in(A, \tau)$ have conjugates variables $\left(\partial_{1}^{*} 1 \otimes 1, \ldots, \partial_{n}^{*} 1 \otimes 1\right) \in M$ and second order conjugate variables $\left(\partial_{1}^{*}\left(1 \otimes \partial_{1}^{*} 1 \otimes 1\right), \ldots, \partial_{n}^{*}\left(1 \otimes \partial_{n}^{*} 1 \otimes 1\right)\right) \in M$ then $\left(1 \otimes E_{D}\right) \partial_{i}$ extends to a bounded operator on $L^{2}(M, \tau)$.
(3) If $\left(X_{1}, \ldots, X_{n}\right) \in(A, \tau)$ have conjugate variables $\left(\partial_{1}^{*} 1 \otimes 1, \ldots, \partial_{n}^{*} 1 \otimes 1\right) \in M$ and second order conjugate variables $\left(\partial_{1}^{*}\left(1 \otimes \partial_{1}^{*} 1 \otimes 1\right), \ldots, \partial_{n}^{*}\left(1 \otimes \partial_{n}^{*} 1 \otimes 1\right)\right) \in M$ then the unbounded densely defined operator $\partial_{i_{1}, \ldots, i_{k}}^{k}: M \rightarrow M_{D}^{\stackrel{\text { eh }}{\otimes(k+1)}}$ is weak-* closable with closure $\overline{\bar{\partial}_{i_{1}, \ldots, i_{k}}^{k}}$ eh , and $\partial_{i_{1}, \ldots, i_{k}}^{k}: L^{2}(M, \tau) \rightarrow L^{2}(M, \tau)^{\otimes_{D}(k+1)}$ is closable with closure $\overline{\partial_{i_{1}, \ldots, i_{k}}^{k}}$.
Moreover, for $k \leq 3$ (resp. $k \leq 2$ ) the conclusions about the eh extension and for $k \leq 2 \quad$ (resp. $k \leq 1$ ) for the $L^{2}$ extension hold assuming only $\left(\partial_{1}^{*} 1 \otimes\right.$ $\left.1, \ldots, \partial_{n}^{*} 1 \otimes 1\right) \in M \quad\left(\operatorname{resp} . L^{2}(M)\right)$.
Finally, if $F \in C_{t r}^{k, 0}\left(A, A_{R, \operatorname{conj}\left(1_{k \geq 1} / 2+1_{k \geq 3} / 2_{1} 1_{k \geq 4}\right)}: B, E_{D}\right)$ and $\left\|X_{i}\right\| \leq R$ then $F(X) \in D\left({\overline{\partial_{i_{1}, \ldots, i_{k}}^{k}}}^{e h}\right)$ and $\overline{\partial_{i_{1}, \ldots, i_{k}}^{k}}$ eh $(F(X))=\left[\partial_{i_{1}, \ldots, i_{k}}^{k}(F)\right](X)$
(4) If $\left(X_{1}, \ldots, X_{n}\right) \in(A, \tau)$ have conjugate variables $\left(\partial_{1}^{*} 1 \otimes 1, \ldots, \partial_{n}^{*} 1 \otimes 1\right) \in M$ then $\partial_{i}^{*}$ is a weak-* continuous bounded operator $D\left({\overline{\partial_{i} \otimes_{D} 1}}^{e h} \oplus{\overline{1 \otimes_{D} \partial_{i}}}^{e h}\right) \rightarrow M$ and if moreover they have second order conjugate variables it extends to $a$ bounded operator $M \stackrel{\text { eh }}{\underset{D}{\otimes}} M \rightarrow L^{2}(M)$.
Proof. (1) Using [Dab15, Prop 14, Th15], we have a canonical weak-* continuous completely contractive map $M \underset{D}{\otimes} M \subset L^{2}(M) \otimes_{D} L^{2}(M)$. Thus closability follows from closability as a map valued in the Hilbert space $L^{2}(M) \otimes_{D} L^{2}(M)$. The densely defined adjoint is then given by Voiculescu's formula $B\left\langle X_{1}, \ldots, X_{n}\right\rangle \otimes_{D}$ $B\left\langle X_{1}, \ldots, X_{n}\right\rangle,:$

$$
\begin{equation*}
\partial_{i}^{*}\left(a \otimes_{D} b\right)=a \partial_{i}^{*}(1 \otimes 1) b-\left(1 \otimes E_{D}\right)\left(\partial_{i}(a)\right) b-a\left(E_{D} \otimes 1\right)\left(\partial_{i}(b)\right) \tag{51}
\end{equation*}
$$

This shows the first result. The reasoning for $\partial_{i} \otimes_{D} 1,1 \otimes_{D} \partial_{i}$ is similar. To check the derivation property it suffices to take bounded nets $U_{n} \rightarrow U, V_{\nu} \rightarrow V$ and to use the weak-* continuity of.$\#_{K}$. obtained in Proposition A. 23 from Theorem A.19.(2) in order to take the limit successively in $n, \nu$ of ${\overline{\partial_{i} \otimes_{D} 1}}^{e h}\left(U_{n} \# V_{\nu}\right)=$ ${\overline{\partial_{i} \otimes_{D} 1}}^{e h}\left(U_{n}\right) \#_{2} V_{\nu}+U_{n} \#{\overline{\partial_{i} \otimes_{D} 1}}^{e h}\left(V_{\nu}\right)$
(2) The second result is the relative variant of [Dab08, Remark 11, Lemma 12].
(3) The third result then follows similarly from the first using also the second result. It always suffices to show weak-* closability from $M$ (or $L^{2}(M)$ ) with value an $L^{2}$ tensor product, for which one needs densely defined adjoints with value $L^{1}(M)$ or $L^{2}(M)$ respectively.

We detail only the case $k=2,3$. From Voiculescu's formula, for $a, b, c, d \in$ $B\left\langle X_{1}, \ldots, X_{n}\right\rangle$, one deduces:

$$
\begin{aligned}
\left(\partial_{i_{1}, i_{2}}^{2}\right)^{*} & \left(a \otimes_{D} b \otimes_{D} c\right)=\partial_{i_{1}}^{*}\left(a \otimes\left[b \partial_{i_{2}}^{*}(1 \otimes 1) c-b E_{D} \otimes 1 \partial_{i_{2}}(c)-1 \otimes E_{D} \partial_{i_{2}}(b) c\right]\right) \\
& \left.=\left[a \partial_{i_{1}}^{*} 1 \otimes 1-1 \otimes E_{D} \partial_{i_{1}}(a)\right]\left[b \partial_{i_{2}}^{*}(1 \otimes 1) c-b\left(E_{D} \otimes 1\right) \partial_{i_{2}}(c)-1 \otimes E_{D} \partial_{i_{2}}(b) c\right]\right) \\
& \left.-a\left(E_{D} \otimes 1\right) \partial_{i_{1}}\left[b \partial_{i_{2}}^{*}(1 \otimes 1) c-b\left(E_{D} \otimes 1\right) \partial_{i_{2}}(c)-1 \otimes E_{D}\right) \partial_{i_{2}}(b) c\right]
\end{aligned}
$$

where the second line is in $M$ and the third in $L^{2}(M)$ by the second point as soon as the first order conjugate variables are in $M$ (resp. both in $L^{1}(M)$ by the second point as soon as the first order conjugate variables are in $\left.L^{2}(M)\right)$. This gives the various statements in case $k=2$.

Likewise, we have :

$$
\begin{aligned}
& \left(\partial_{i_{0}, i_{1}, i_{2}}^{3}\right)^{*}\left(a \otimes_{D} b \otimes_{D} c \otimes_{D} d\right) \\
& \quad=\left[a \partial_{i_{1}}^{*} 1 \otimes 1-1 \otimes E_{D} \partial_{i_{1}}(a)\right]\left(\partial_{i_{1}, i_{2}}^{2}\right)^{*}(b \otimes c \otimes d)-a\left(E_{D} \otimes 1 \partial_{i_{0}}\right)\left(\partial_{i_{1}, i_{2}}^{2}\right)^{*}(b \otimes c \otimes d)
\end{aligned}
$$

and the first term is in $L^{2}(M)$, the second in $L^{1}(M)$ by the second point and what we just proved, as soon as the first order conjugate variable are in $M$ (resp. both in $L^{2}(M)$ if we have first and second conjugate variables in $M$ ).

The higher order terms are then similar to this last case when we have both first and second conjugate variables in $M$. All the higher adjoints are then valued in $L^{2}(M)$ on basic tensors from $B\left\langle X_{1}, \ldots, X_{n}\right\rangle$.

For the compatibility with $C^{k}$ spaces, the non-commutative analytic functionals are clearly in the domain and the extension by density is straightforward (even with norm instead of weak-* convergence which is used at the analytic function level though).
(4) For the fourth statement the $M$ valued extension only involves application of canonical maps associated to Haagerup tensor product to mimic the formula above. For the second part of the fourth statement, we extend each term of the formula above. First we know that $a \otimes_{D} b \rightarrow a \xi_{i} b$ can be extended to $M \stackrel{\text { eh }}{\otimes} M$ since $\xi_{i} \in D^{\prime} \cap M$ (see e.g. [Dab15, Lemma 43.(2)]). We next write down explicit bounds for the last $L^{2}(M)$ valued extension. From the Cauchy-Schwarz inequality for Hilbert modules one gets $\left(\sum_{j} a_{j} \xi_{i} b_{j}\right)^{*} \sum_{j} a_{j} \xi_{i} b_{j} \leq\left\|\sum_{j} a_{j} a_{j}^{*}\right\|\left(\sum_{j} b_{j}^{*} \xi_{i}^{*} \xi_{i} b_{j}\right)$ so that

$$
\left\|\sum_{j} a_{j} \xi_{i} b_{j}\right\|_{2}^{2} \leq\left\|\sum_{j} a_{j} a_{j}^{*}\right\|\left\|\xi_{i}\right\|_{2}^{2}\left\|\sum_{j} b_{j} b_{j}^{*}\right\|
$$

and moreover

$$
\left\|\sum_{j} a_{j} \xi_{i} b_{j}\right\|^{2} \leq\left\|\sum_{j} a_{j} a_{j}^{*}\right\|\left\|\xi_{i}\right\|^{2}\left\|\sum_{j} b_{j}^{*} b_{j}\right\|
$$

Likewise we get,

$$
\begin{aligned}
\left\|\sum_{j} a_{j}\left(E_{D} \otimes 1\right) \partial_{i}\left(b_{j}\right)\right\|_{2}^{2} & \leq\left\|\sum_{j} a_{j} a_{j}^{*}\right\| \sum_{j} \|\left(E_{D} \otimes 1\right)\left(\partial_{i}\left(b_{j}\right) \|_{2}^{2}\right. \\
& \leq\left\|\sum_{j} a_{j} a_{j}^{*}\right\|\left\|\left(E_{D} \otimes 1\right) \partial_{i}\right\|^{2} \sum_{j}\left\|b_{j}\right\|_{2}^{2}
\end{aligned}
$$

and replacing $b_{j}$ by $a_{j}^{*}, a_{j}$, by $b_{j}^{*}$ :

$$
\left\|\sum_{j}\left(1 \otimes E_{D}\right)\left(\partial_{i}\left(a_{j}\right)\right) b_{j}\right\|_{2}^{2} \leq\left\|\sum_{j} b_{j}^{*} b_{j}\right\|\left\|\left(E_{D} \otimes 1\right) \partial_{i}\right\|^{2} \sum_{j}\left\|a_{j}\right\|_{2}^{2}
$$

giving the last claimed extension (using the canonical expression for elements in the extended Haagerup product in [M05]).
We finally recall Voiculescu's extension result for free products:
Lemma B.37. Assume that the conjugate variables to $X_{1}, \ldots, X_{n}$ exist. Consider the unique extension $\hat{\partial}_{i}$ on $B\left\langle X_{1}, \ldots, X_{n}, S_{t}, t>0\right\rangle$ of the free difference quotient derivations $\partial_{i}$ satisfying the Leibniz rule and $\hat{\partial}_{i}\left(S_{t}\right)=0$. Then $\hat{\partial}_{i}^{*}(1 \otimes 1)=\partial_{i}^{*}(1 \otimes 1)$.

Let $U \subset A_{R, c o n j}^{n}, \mathscr{A}=A *_{D}\left(D \otimes W^{*}\left(S_{t}^{(i)}, i=1, \ldots, n, t \geq 0\right)\right)$, and recall that we defined in subsection 2.5: $U_{A}=\left\{X \in \mathscr{A}_{R}^{n}, X \in U\right\} \subset A_{R, \text { conj }}^{n}$. Given any inclusion $i: \mathscr{A} \rightarrow A$ set $U_{A}^{\prime}=\left\{X \in \mathscr{A}_{R}^{n}, i(X) \in U\right\}$. If $U$ is invariant under trace preserving isomorphisms (as will be the case for us), the space $U_{A}^{\prime}$ does not depend on the choice of the inclusion $i$.

For all spaces with cyclic variants here, $\mathscr{A}^{\substack{\text { eh } \\ D}}$ is replaced by $\mathscr{M}^{\substack{\text { eh } \\ D, c}}$, with $\mathscr{M}=$ $W^{*}\left(B, X_{1}, \ldots, X_{n}, S_{t}, t>0\right)$ so that Proposition B. 28 can be applied to all the variables $X_{1}, \ldots, X_{n}, S_{t}$.
B.5. Conditional expectations and $C^{k, l}$ functions. Recall the spaces $C_{t r, V}^{k, l}(A, U: \mathscr{B}, D: \mathscr{S}), C_{t r}^{k, l}\left(A, U: \mathscr{B}, D: \mathscr{S}_{\geq u}\right)$, etc. from subsection 2.5. They are convenient spaces to define semigroups thanks to the following result. The composition maps are variants of the previous subsection and the new conditional expectations are based of the behaviour for extended Haagerup products of free difference quotients of our previous Lemma B.36.

Proposition B.38. (1) Let $k, l(k \geq l$ when required in the definition of the space) and $U \subset A_{R, \text { conj0 }}^{n}$ (resp. $U \subset A_{R, \operatorname{conj(1/2)}}^{n}$ if $k \geq 1$, resp. $U \subset A_{R, \text { conj1 }}^{n}$, if $k \geq 3$ resp. $U \subset A_{R, \text { conj2 } 2}^{n}$, if $\left.k \geq 4\right)$. Then $E_{B}: \mathscr{B}=B *_{D}\left(D \otimes W^{*}\left(S_{t}^{(i)}, i=\right.\right.$ $1, \ldots, n, t \geq 0)) \rightarrow B$ gives rise to contractions

$$
\begin{gathered}
E_{0}:\left(C_{t r}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right),\|\cdot\|_{k, l, U}\right) \rightarrow\left(C_{t r}^{k, l}\left(A, U: B, E_{D}\right),\|\cdot\|_{k, l, U}\right) \\
E_{0}: C_{t r, V}^{k, l ; \epsilon_{1}, \epsilon_{2}}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right) \rightarrow C_{t r, V}^{k, l, \epsilon_{1}, \epsilon_{2}}\left(A, U: B, E_{D}\right) \\
E_{0}: C_{t r, V}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right) \rightarrow C_{t r, V}^{k, l}\left(A, U: B, E_{D}\right), \quad k \geq 2
\end{gathered}
$$

and likewise for cyclic variants : $C_{t r, c}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right) \rightarrow C_{t r, c}^{k, l}(A, U:$ $\left.B, E_{D}\right), C_{t r, V, c}^{k, l ; \epsilon_{1}, \epsilon_{2}}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right) \rightarrow C_{t r, V, c}^{k, l, \epsilon_{1}, \epsilon_{2}}\left(A, U: B, E_{D}\right), C_{t r, V, c}^{k, l}(A, U:$ $\left.\mathscr{B}, E_{D}: \mathscr{S}\right) \rightarrow C_{t r, V, c}^{k, l}\left(A, U: B, E_{D}\right)$. They are also contractions for the seminorms $\|\cdot\|_{k, l, U \geq 1}$ and $\|\cdot\|_{C_{t r, V}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right), \geq 1}$.

We also have similarly for $u>0$

$$
\begin{aligned}
E_{u}: C_{t r}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right) & \rightarrow C_{t r}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}_{u}\right), \\
E_{u}: C_{t r, V}^{k, l, \epsilon_{1}, \epsilon_{2}}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right) & \rightarrow C_{t r, V}^{k, l, \epsilon_{1}, \epsilon_{2}}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}_{u}\right), \\
E_{u}: C_{t r, V}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right) & \rightarrow C_{t r, V}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}_{u}\right),
\end{aligned}
$$

such that $E_{0} \circ E_{u}=E_{0}$ and $E_{0}=E_{u} \circ \theta_{u}^{\prime}=E_{0} \circ \theta_{u}^{\prime}$.
(2) Moreover, the extension result of Corollary $B .34$ is also valid for any $U \subset$ $A_{R, \text { conj0 }}^{n}, V \subset A_{S, \text { conj0 }}^{n}$ giving composition maps $\circ$ :

$$
\begin{aligned}
\circ: C_{c}^{k+l}(A, V: B, D) & \times \operatorname{Comp}\left(U_{A}, V_{A}^{\prime}, C_{t r, W}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right)\right) \\
& \rightarrow C_{t r, W}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right) \\
\circ: C_{t r}^{k, l}(A, V: B, D) & \times \operatorname{Comp}\left(U_{A}, V_{A}^{\prime}, C_{t r}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right)\right) \\
& \rightarrow C_{t r}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right)
\end{aligned}
$$

(here and in the next also for $(k, l) \in I N^{2}$ ),

$$
\begin{aligned}
\circ: C_{t r}^{k, l ; 0, \epsilon_{2}}(A, V: B, D) & \times \operatorname{Comp}\left(U_{A}, V_{A}^{\prime}, C_{t r}^{k, l ; 0,1}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right)\right) \\
& \rightarrow C_{t r}^{k, l ; 0, \epsilon_{2}}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right), \\
\circ: C_{c}^{k}(A, V: B, D) & \times \operatorname{Comp}^{\left(U_{A}, V_{A}^{\prime}, C_{c}^{k}(A, U: \mathscr{B}, D: \mathscr{S})\right)} \\
& \rightarrow C_{c}^{k}(A, U: \mathscr{B}, D: \mathscr{S}),
\end{aligned}
$$

and as in Lemma B.32 a map $\left.\iota^{\prime}: C_{c}^{k+l}(A, U: \mathscr{B}, D: \mathscr{S})\right) \rightarrow C_{t r, W, c}^{k, l}(A, U:$ $\left.\left.\mathscr{B}, E_{D}: \mathscr{S}\right), \iota^{\prime}: C_{c}^{k+l+1}(A, U: \mathscr{B}, D: \mathscr{S})\right) \rightarrow C_{t r, W, c}^{k, l, \epsilon_{1}, \epsilon_{2}}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right)$. We also have $(.) \circ \theta_{u}^{\prime}()=.\theta_{u}^{\prime}((.) \circ()$.$) on the above spaces.$
(3) Finally, we also have a similar composition map $\circ_{u}$ for any $u>0$ for $(k, l) \in$ $I N^{2}$ :

$$
\begin{aligned}
\left.C_{t r}^{k, l}\left(A, V: \mathscr{B}, E_{D}: \mathscr{S}_{\geq u}\right)\right) \times & C o m p\left(U_{A}, V_{A}^{\prime}, C_{t r}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}_{u}\right)\right) \\
& \rightarrow C_{t r}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right),
\end{aligned}
$$

$$
\left.C_{t r}^{k, l ; 0, \epsilon_{2}}\left(A, V: \mathscr{B}, E_{D}: \mathscr{S}_{\geq u}\right)\right) \times \operatorname{Comp}\left(U, V,\left(C_{t r}^{k, l ; 0,1}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}_{u}\right)\right)\right.
$$

$$
\left.\rightarrow C_{t r}^{k, l ; 0, \epsilon_{2}}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right)\right)
$$

$\epsilon_{2} \in\{-1,0,1\}$ and we have : $(.) \circ\left[(.) \circ_{u}().\right]=[(.) \circ().] \circ_{u}($.$) and E_{B}(.) \circ()=$. $\left.E_{u}\left(\theta_{u}^{\prime}(.) \circ_{u}().\right): C_{t r}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}\right)\right) \times \operatorname{Comp}\left(U_{A}, V_{A}^{\prime}, C_{t r}^{k, l}\left(A, U: \mathscr{B}, E_{D}:\right.\right.$ $\left.\left.\mathscr{S}_{u}\right)\right) \rightarrow C_{t r}^{k, l}\left(A, U: \mathscr{B}, E_{D}: \mathscr{S}_{u}\right)$.
Proof. By density, it suffices to prove contractivity restricting to the polynomial variant of the space $C_{b, t r}^{0}\left(U, B\left\langle X_{1}, \ldots, X_{n}: D, R\right\rangle\right)$. But if $P$ is in the partial evaluation $\eta_{S}\left(B_{c}\left\{X_{1}, \ldots, X_{n}, S_{t_{1}}, \ldots, S_{t_{m}}-S_{t_{m-1}}: \mathscr{B}, E_{D}, \max \left[R, \max _{i=2, n} 2\left(t_{i}-\right.\right.\right.\right.$ $\left.\left.\left.\left.\left.t_{i-1}\right)\right] \mathbb{C}\right\}\right)\right\}$, it is easy to see by definition of free semicircular variables with amalgamation that $E_{A}\left(P\left(E_{D, X}\right)\right)=Q\left(E_{D, X}\right)$ for some $Q \in B\left\{X_{1}, \ldots, X_{n}: B, E_{D}, R\right\}$. $Q$ is the same as $P$ where Brownian variables are replaced by sums over formal conditional expectations.

More precisely, let $P=\epsilon_{m, \sigma}\left(P^{\prime}\right)$, for

$$
m \in M_{2 k}\left(X_{1}, \ldots, X_{n}, Z_{1}=S_{t_{1}}, \ldots, Z_{m}=S_{t_{m}}-S_{t_{m-1}}, Y\right), \sigma \in N C_{2}(2 k)
$$

with $P^{\prime} \in B^{\substack{\text { eh } \\ \otimes, c}}|m|+1$, a typical monomial in the direct sum for analytic functions with expectation in the component indexed by $(m, \sigma)$. Recall that $Y$ variables and the pairing $\sigma$ indicate the position of conditional expectations. Let $\pi_{m}: N C_{2}\left(2 k+|m|_{Z}\right) \rightarrow N C(2 k)$ the restriction to the indices of $Y$ variables in the monomial $m\left(X_{1}=1, \ldots, X_{n}=1, Z_{1}, \ldots, Z_{m}, Y\right)$ and $\pi_{m, i, k}: N C_{2}\left(2 k+|m|_{Z}\right) \rightarrow$ $N C\left(|m|_{\left.\left(Z_{i}\right)^{(k)}\right)}\right), i=1, \ldots, m, k=1, \ldots, n$ the restriction to indices of the variables in position $\left(Z_{i}\right)^{(k)}$. Note that this is valued in pair partitions when $\left(Z_{i}\right)^{(k)}$ variables are only paired within themselves.

Then, the conditional expectation is obtained by replacing with pairings and conditional expectations the brownian variables in an appropriate way so that we define with for convenience $t_{0}=0$ :
$E_{B}(P)=Q:=\sum_{\substack{\pi \in N C_{2}(2 k+|m| z) \\ \pi_{m}(\pi)=\sigma \\ \pi_{m, i, k}(\pi) \in N C_{2}\left(|m| \\ m_{i}\right)}} \epsilon_{m\left(X_{1}, \ldots, X_{n}, Z_{1}=Y, \ldots Z_{m}=Y, Y\right), \pi}\left(P^{\prime}\right) \prod_{i=1}^{m}\left(t_{i}-t_{i-1}\right)^{|m| z_{i} / 2}$,
so that the relation above $E_{A}\left(P\left(E_{D, X}\right)(X)\right)=\left(E_{B}(P)\right)\left(E_{D, X}\right)(X), X \in A_{R}^{n}$ is easy to check from the definition of free Brownian motion. Note that

$$
\begin{equation*}
\left(\Delta+\delta_{\Delta}\right)\left(E_{0}(P)\right)=E_{0}\left(\left(\Delta+\delta_{\Delta}\right)(P)\right) \tag{52}
\end{equation*}
$$

(where of course $\Delta$ only applies on $X_{i}$ variables) since, using the definition in the proof of Proposition B.31, both expressions correspond to having a supplementary sum over pairs of $X_{i}$ variables giving a partition not crossing the previous ones and replaced by a formal $E$.

Using relation (50) with $e, H_{i}$ in the smaller algebra $A$, one sees that for $e \in A$,

$$
\begin{equation*}
E_{A}\left[\mathscr{D}_{i, e}(P)\left(E_{D, X}(X)\right]=\mathscr{D}_{i, e}(Q)\left(E_{D, X}(X)\right)\right. \tag{53}
\end{equation*}
$$

and we can extend this directly to the cyclic gradient of Proposition B.30. For $e \in B\left\{X_{1}, \ldots, X_{n}: B, E_{D}, R\right\}$ we have

$$
\begin{equation*}
E_{0}\left[\mathscr{D}_{i, e}(P)\right]=\mathscr{D}_{i, e}\left(E_{0}(P)\right) . \tag{54}
\end{equation*}
$$

Indeed, for $e, P$ monomials, since $e$ has no dependence in $S_{t}$ 's, there is a bijection between pairs of $S_{t}$ 's appearing in each monomial after and before applying $\mathscr{D}_{i, e}$. Since cyclic permutations globally preserve the set of non-crossing partitions the result is thus a combinatorial rewriting.

It thus remains to check contractivity estimates to extend $E_{0}$ to spaces of $C^{k}$ functions.

For $X \in U, P$ as before $\partial_{i}^{l}(Q)\left(E_{D, X}\right)(X)={\overline{\partial_{i}^{l}}}^{e h}\left[Q\left(E_{D, X}\right)(X)\right]$ by Lemma B. 36 (we only use it when $k \geq 1$, the various conditions on $U$ also when $k \geq 4$ comes from this application), and by duality from Lemma B.37, one gets it equal to ${\overline{\partial_{i}^{l}}}^{e h}\left[E_{A}\left(P\left(E_{D, X}\right)(X)\right)\right]=\left(E_{A}^{\otimes_{e h} l+1}\right)\left({\overline{\partial_{i}^{l}}}^{e h}\left[\left(P\left(E_{D, X}\right)(X)\right)\right]\right)$ and hence by functoriality of the Haagerup tensor product. we get:

$$
\left\|\partial_{i}^{l}\left(E_{0}(P)\right)(X)\right\|_{A^{\otimes_{e h D(l+1)}}} \leq\left\|\left(\partial_{i}^{l}(P)\right)(X)\right\|_{A^{\otimes_{e h D(l+1)}}} .
$$

Here it is crucial to note that for all cyclic variants that by Proposition A.24.(3) if $\bar{\partial}_{i}^{e h}\left[\left(P\left(E_{D, X}\right)(X)\right)\right]$ is in a cyclic extended Haagerup tensor product, it remains there after application of $\left(E_{A}^{\otimes_{e h} l+1}\right)$.

Likewise, the full differential commutes with conditional expectation (which is a linear bounded map, we thus get the bound for all parts of the seminorm involving free difference quotients and full differentials. We thus proved contractivity on $C_{t r}^{k, l}$-spaces.

Since $\left(\Delta_{V}+\delta_{V}\right)(P)=\left(\Delta_{0}+\delta_{\Delta}\right)(P)+d_{X} P .\left(\mathscr{D}_{1} V, \ldots, \mathscr{D}_{n} V\right)$ the previous results give $\left(\Delta_{V}+\delta_{V}\right)\left(E_{B}(P)\right)=E_{B}\left(\left(\Delta_{V}+\delta_{V}\right)(P)\right)$ so that since in this case $k \geq 2$, the choice of the seminorm chosen with this term is compatible with contractivity. The contractivity of the term with cyclic gradients is also easy with the previous established commutation relation, so that one gets the stated contractivity on $C_{t r, V^{-}}^{k, l}$ spaces. Obtaining multiplication maps is as easy as before in this context and by arguments of stability of subspaces for $C_{c}^{k}$-spaces.

The variant $E_{u}$ and its relations are obvious.
B.6. Regular change of variables for conjugate variables. The computation of conjugate variables along change of variables we used to identify conjugate variables of our transport maps are explained in Lemma B. 39 with the differentiation along a path of such change of variables.

Let $M=W^{*}\left(X_{1}, \ldots, X_{n}, B\right)$ for $\left(X_{1}, \ldots, X_{n}\right) \in(A, \tau)$. We will soon assume those variables have enough conjugate variables relative to $D$ in presence of $B$.

Lemma B.39. Assume $W^{*}\left(B, X_{1}, \ldots, X_{n}\right)=M$ is such that $X \mapsto\left\langle e_{D}, X \# e_{D}\right\rangle$ is a trace on $D^{\prime} \cap M \stackrel{\text { eh }}{\otimes} M$.

Let $\left(X_{1}, \ldots, X_{n}\right) \in U^{\prime} \subset A_{S, \text { conj }}^{n}, S>0$ and thus have conjugates variables $\left(\partial_{1}^{*} 1 \otimes\right.$ $\left.1, \ldots, \partial_{n}^{*} 1 \otimes 1\right) \in M^{n}$ relative to $B, E_{D}$. Take $F=F^{*} \in\left(C_{t r, c}^{k, l}\left(A, U^{\prime}\right)\right)^{n}$, with $k \geq 2$.

Then $\left(Y_{1}, \ldots, Y_{n}\right)=F\left(X_{1}, \ldots, X_{n}\right)$ have conjugate variables in $M$ as soon as $\|1-\mathscr{J} F\|_{M_{n}(M \underset{\substack{\otimes, c \\ D, c}}{\text { eh }},}<1$, with $(\mathscr{J} F)_{i j}=\partial_{j, X} Y_{i}$. Moreover, we have, setting $C(F)=\frac{D}{1-\|1-\mathscr{J} F\|_{M_{n}\left(M_{\substack{\text { eh } \\ D, c}}^{\text {en }}\right.}}:$

$$
\begin{aligned}
& \left\|\partial_{j, Y}^{*} 1 \otimes 1\right\| \leq C(F)\left\|\partial_{j}^{*} 1 \otimes 1\right\|+C(F)^{2}\left(\sum_{k \neq j}\left\|\sigma\left[(\mathscr{J} F)_{k j}\right]\right\|_{M \otimes_{e h D} M}\right) \sum_{k \neq j}\left\|\partial_{k}^{*} 1 \otimes 1\right\| \\
& +C(F)^{2} \sum_{\substack{k, l, m \in[1, n] \\
(\epsilon, \eta) \in\{(1,0),(0,1)\}}}\left\|{\overline{\mathbb{Q}_{D} \epsilon} \otimes_{D} \partial_{k} \otimes_{D} 1^{\otimes_{D} \eta}}^{e h}\left(\sigma\left[(\mathscr{J} F)_{l m}\right]\right)\right\| \begin{array}{c}
\text { eh } \\
M D^{\Delta}
\end{array} . \\
& (\epsilon, \eta) \in\{(1,0),(0,1)\}
\end{aligned}
$$

Proof. This proof is a variant relative to $D$ of Lemma 3.1 in [GS12].
Take $P \in B\left\langle X_{1}, \ldots, X_{n}, D, R, \mathbb{C}\right\rangle, R \geq \max \left(S, \sup _{X \in U^{\prime}}\left\|F_{i}(X)\right\|\right)$, then $P(Y)$ satisfies the natural extension of formula (45) from the proof of Lemma B. 33 and so we get the equation in $D^{\prime} \cap M \stackrel{\text { eh }}{\otimes} M$ :

$$
\partial_{i, X} P(Y)=\sum_{j=1}^{n}\left(\partial_{j}(P)\right)(Y) \# \partial_{i, X} Y_{j}
$$

Note that from the assumption on $(\mathscr{J} F)_{i j}=\partial_{j, X} Y_{i}$, one deduces that $\mathscr{J} F$ is invertible in $M_{n}(M \underset{D, c}{\stackrel{\mathrm{eh}}{\otimes}} M)$ so that one gets:

$$
\partial_{i}(P)(Y)=\sum_{j=1}^{n} \partial_{j, X} P(Y) \#\left[(\mathscr{J} F)^{-1}\right]_{j i}
$$

Thus applying the weak-* continuity of Theorem A.19.(2) to introduce $E_{D^{\prime}}$ (and then remove it in the next-to-last line), the assumed traciality and applying (36) to $X=\left[(\mathscr{J} F)^{-1}\right]_{j i}^{*}, Y=E_{D^{\prime}}\left(\partial_{j, X} P(Y)\right)$, we get:

$$
\begin{aligned}
\left\langle e_{D},\left(\partial_{i}(P)\right)(Y) \# e_{D}\right\rangle & =\sum_{j=1}^{n}\left\langle e_{D}, E_{D^{\prime}}\left(\partial_{j, X} P(Y)\right) \#\left[(\mathscr{J} F)^{-1}\right]_{j i} \# e_{D}\right\rangle \\
& =\sum_{j=1}^{n} \tau\left(\left(\left[(\mathscr{J} F)^{-1}\right]_{j i}^{*}\right)^{*} E_{D^{\prime}}\left[\partial_{j, X} P(Y)\right]\right) \\
& \left.=\sum_{j=1}^{n}\left\langle\left[(\mathscr{J} F)^{-1}\right]_{j i}^{*}\right) \# e_{D}, E_{D^{\prime}}\left[\partial_{j, X} P(Y)\right] \# e_{D}\right\rangle \\
& =\sum_{j=1}^{n}\left\langle\left(\left[(\mathscr{J} F)^{-1}\right]_{j i}^{*}\right) \# e_{D},{\overline{\partial_{j, X}}}^{L^{2}}(P(Y))\right\rangle
\end{aligned}
$$

Thus if we check that $\left(\left[(\mathscr{J} F)^{-1}\right]_{j i}^{*}\right) \# e_{D} \in D\left({\overline{\partial_{j, X}}}^{*}\right)$ we will deduce the existence of the conjugate variable and the equality

$$
\partial_{i, Y}^{*}\left(1 \otimes_{D} 1\right)=\sum_{j=1}^{n} \partial_{j, X}{ }^{*}\left[\left(\left[(\mathscr{J} F)^{-1}\right]_{j i}^{*}\right) \# e_{D}\right] .
$$

Note that in any representation with $X \in U$ as above
${\overline{\partial_{i, X}}}^{e h} F_{j}(X)=\left[\left(\partial_{i, X}(\iota(F))\right](X)=\left[\left(\partial_{i, X}\left(\iota(F)^{*}\right)\right](X)=\left(\partial_{i, X}(\iota(F))\right](X)^{\star}=\left[{\overline{\partial_{i, X}}}^{e h} F_{j}(X)\right]^{\star}\right.\right.$
where the last $\star$ is the one of $M \underset{D, c}{\stackrel{\mathrm{eh}}{\otimes}} M$, and one uses natural properties of evaluation extended using the one on polynomials since $X \in A_{S, U l t r a A p p}^{n}$.

Now, since $(\mathscr{J} F)_{i j} \in M \underset{D, c}{\stackrel{\text { eh }}{\otimes}} M$ one can note that $\left(\sigma(\mathscr{J} F)_{i j}\right)$ is well defined in $D^{\prime} \cap M \stackrel{\text { eh }}{\stackrel{\text { eh }}{\otimes}} M$ and $(\mathscr{J} F)_{i j}^{*}=\sigma\left[(\mathscr{J} F)_{i j}^{\star}\right]=\left[\sigma\left((\mathscr{J} F)_{i j}\right)\right](X)$ and thus from Lemma B.36.(3), the assumption $\sigma\left((\mathscr{J} F)_{i j}\right) \in D\left({\overline{\partial_{k} \otimes 1}}^{e h} \oplus{\overline{1 \otimes \partial_{k}}}^{e h}\right)$, Neumann series and from the derivation property in (1) of the same Lemma, so does $(\sigma(\mathscr{J} F))_{i j}^{-1}$ and for instance, one gets as expected
\left.\left.${\overline{\partial_{k} \otimes 1}}^{e h}\left[(\sigma(\mathscr{J} F))_{i j}^{-1}\right]=-\sum_{l, m}\left(\sigma(\mathscr{J} F)_{i l}^{-1}\right)\right) \#\left[{\overline{\partial_{k} \otimes 1}}^{e h}\left((\sigma(\mathscr{J} F))_{l m}\right)\right] \#_{2}(\sigma(\mathscr{J} F))_{m j}^{-1}\right)$.
Thus from part (4) of the same Lemma, one gets that $\partial_{i, Y}^{*}\left(1 \otimes_{D} 1\right)$ exists and is in $M$ and the expected bound easily follows from the proof of this statement giving
the appropriate extension of Voiculescu's formula. Only note that for $j \neq i$

$$
\begin{aligned}
& {\left[\left(\left[\sigma(\mathscr{J} F)^{-1}\right]_{j i}\right)\right] \# \partial_{j, X}{ }^{*}(1 \otimes 1)} \\
& \left.\left.=\sum_{N=1}^{\infty} \sum_{n=0}^{N-1} \sum_{k \neq i}\left[\left(\sigma(\mathscr{J} F-1)^{N-n-1}\right)_{j k}\right] \#[\sigma(\mathscr{J} F)]_{k i}\right)\right] \#\left[\sigma(\mathscr{J} F-1)_{i i}\right]^{n} \# \partial_{j, X}{ }^{*}(1 \otimes 1) .
\end{aligned}
$$

B.7. Various continuity properties. We start by checking the continuity in $\alpha$ of our various maps. Recall that $A_{R / 3}^{n} \subset A_{R, \alpha}^{n}$ independently of $\alpha \in[0,1]$.

Lemma B.40. If we assume the Assumption of Lemma 6 with $V, W \in$ $C_{c}^{k+2}(A, 2 R: \mathscr{B}, D), U \subset A_{R / 3}^{n}$, then $X: \alpha \mapsto X_{t}(\alpha)$ is continuous on $[0,1]$ with value $C^{0}\left([0, T], C_{c}^{k}(A, U: \mathscr{B}, D: \mathscr{S})\right)$.
Proof. For the continuity in $\alpha$ of $X$, we have :

$$
\begin{aligned}
& X_{t}(\alpha)-X_{t}\left(\alpha^{\prime}\right)=-\frac{1}{2} \int_{0}^{t} d u\left[\mathscr{D} V_{\alpha}-\mathscr{D} V_{\alpha^{\prime}}\right]\left(X_{u}\left(\alpha^{\prime}\right)\right) \\
& -\frac{1}{2} \int_{0}^{t} d u\left[\int_{0}^{1} d \beta \partial \mathscr{D} V_{\alpha}\left(\beta X_{u}(\alpha)+(1-\beta) X_{u}\left(\alpha^{\prime}\right)\right)\right] \#\left[X_{u}(\alpha)-X_{u}\left(\alpha^{\prime}\right)\right]
\end{aligned}
$$

Using the argument in Lemma 4 with $\partial \mathscr{D} V_{\alpha}\left(X_{u}\right)$ replaced by

$$
\left[\int_{0}^{1} d \beta \partial \mathscr{D} V_{\alpha}\left(\beta X_{u}(\alpha)+(1-\beta) X_{u}\left(\alpha^{\prime}\right)\right)\right] \geq c I d
$$

with the positivity coming since our notion of positivity is a closed convex cone, one gets:

$$
\left\|X_{t}(\alpha)-X_{t}\left(\alpha^{\prime}\right)\right\| \leq e^{-c t / 2} \int_{0}^{t} d u e^{c u / 2}\left(\sum_{i}\left\|\left[\mathscr{D}_{i} V_{\alpha}-\mathscr{D}_{i} V_{\alpha^{\prime}}\right]\left(X_{u}\left(\alpha^{\prime}\right)\right)\right\|^{2}\right)^{1 / 2}
$$

This converges uniformly on $[0, T]$ to 0 when $\alpha \rightarrow \alpha^{\prime}$ using the corresponding continuity of $V_{\alpha}$.

Similarly, one gets bounds inductively using (24) in decomposing the higher order term

$$
\begin{aligned}
\partial_{j} \mathscr{D}_{i} V_{\alpha}\left(X_{u}(\alpha)\right) & \#\left(\partial_{\left(j_{1}, \ldots, j_{k}\right)}^{k} X_{u}^{(j)}(\alpha)\right)-\partial_{j} \mathscr{D}_{i} V_{\alpha^{\prime}}\left(X_{u}\left(\alpha^{\prime}\right)\right) \#\left(\partial_{\left(j_{1}, \ldots, j_{k}\right)}^{k} X_{u}^{(j)}\left(\alpha^{\prime}\right)\right) \\
& =\left(\partial_{j} \mathscr{D}_{i} V_{\alpha}-\partial_{j} \mathscr{D}_{i} V_{\alpha^{\prime}}\right)\left(X_{u}(\alpha)\right) \#\left(\partial_{\left(j_{1}, \ldots, j_{k}\right)}^{k} X_{u}^{(j)}(\alpha)\right) \\
& +\left[\partial_{j} \mathscr{D}_{i} V_{\alpha^{\prime}}\left(X_{u}(\alpha)\right)-\partial_{j} \mathscr{D}_{i} V_{\alpha^{\prime}}\left(X_{u}\left(\alpha^{\prime}\right)\right)\right]\left(\partial_{\left(j_{1}, \ldots, j_{k}\right)}^{k} X_{u}^{(j)}(\alpha)\right) \\
& +\left(\partial_{j} \mathscr{D}_{i} V_{\alpha^{\prime}}\left(X_{u}\left(\alpha^{\prime}\right)\right) \#\left(\partial_{\left(j_{1}, \ldots, j_{k}\right)}^{k} X_{u}^{(j)}(\alpha)\right)-\left(\partial_{\left(j_{1}, \ldots, j_{k}\right)}^{k} X_{u}^{(j)}\left(\alpha^{\prime}\right)\right)\right)
\end{aligned}
$$

The last line is treated by Lemma 4, the first line and lower order terms tend to zero uniformly on compacta by continuity of $\alpha \mapsto V_{\alpha}$ or inductively, in the second line (and corresponding terms for lower order terms), $V_{\alpha}$ is approximated (uniformly in $\alpha$ ) by analytic functions to get a Lipschitz function, and use the previous bound on $\left\|X_{t}(\alpha)-X_{t}\left(\alpha^{\prime}\right)\right\|$. Note that the Lipschitz property could have been treated by explicit bounds on derivatives except for the lowest order term having highest derivative in $V$, namely $k+2$, for which it is crucial that our definition of
$C_{c}^{k+2}$ implies uniform continuity of the highest derivative via uniform approximation by analytic functions as explained. This concludes the uniform convergence statement in $\alpha$.

We also obtain the corresponding result for semigroups.
Lemma B.41. If we assume the Assumption of Proposition 8 with $V, W \in$ $C_{c}^{k+l+2}(A, 2 R: B, D)(k \in\{2,3\}, l \geq 1)$ then for every $T>0$ each $P \in$ $C_{c}^{k+l}\left(A, A_{R, \text { conj }}^{n}: B, E_{D}\right), \varphi^{\prime}(P): \alpha \mapsto \varphi^{\alpha \prime}(P)$ is continuous on $[0,1]$ with value

$$
C^{0}\left([0, T], C_{t r, V_{0}}^{k, l}\left(A, A_{R / 3, c o n j}^{n}: B, E_{D}\right)\right)
$$

Proof. Recall that $C_{t r, V_{0}}^{k, l}\left(A, A_{R / 3, c o n j}^{n}: B, E_{D}\right)=C_{t r, V_{\alpha}}^{k, l}\left(A, A_{R / 3, c o n j}^{n}: B, E_{D}\right)$ with equivalent norms for $k \geq 2, l \geq 1$. The result follows by composing the composition map and expectations of Proposition B. 38 with our previous Lemma since for $X \in A_{R / 3, c o n j}^{n}, X_{t}(X) \in A_{R, c o n j}^{n}$ for all $t$ so that the composition condition is satisfied.
B.8. Conjugate variables along free SDE's. The following result is an adaptation in free probability of (a special case of) Lemma 4.2 in [RT02], except that we have to use the Itô Formula for the proof instead of the Girsanov Theorem, which is not (yet) available in free probability. This is also an extension to our new classes of $C^{2}$ functions of a result first explained by the first author in [Dab10a].

Proposition B.42. Assume the Assumption of Proposition 5(a) with $V \in$ $C_{c}^{4}(A, R: B, D)$. Assume moreover that, for $M=W^{*}\left(B, X_{0}\right) *_{D}\left(D \otimes W^{*}\left(S_{t}, t>0\right)\right.$, $\tau=\left\langle e_{D}, . \# e_{D}\right\rangle$ is a trace on $D^{\prime} \cap M \stackrel{\mathrm{D}}{\mathrm{eh}} M$ as in the conclusion of Theorem A.20.(3) and Proposition A.24.(2).

Consider on $[0, T]$ the unique solution obtained there:

$$
X_{t}\left(X_{0}\right)=X_{0}+S_{t}-\frac{1}{2} \int_{0}^{t} \mathscr{D} V\left(X_{u}\left(X_{0}\right)\right) d u
$$

Then $X_{t}^{1}, \ldots, X_{t}^{n}$ have bounded conjugate variables in presence of $B$ relative $E_{D}$, and the corresponding $i$-th conjugate variable is given by
$\xi_{s}^{i}=\frac{1}{s} E_{W^{*}\left(B, X_{s}^{1}, \ldots, X_{s}^{n}\right)}\left(X_{s}^{i}-X_{0}^{i}-\int_{0}^{s} d t \frac{t}{2} F_{\mathscr{D}_{i} V}\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)\right)+\frac{1}{2} \mathscr{D}_{i} V\left(X_{s}^{1}, \ldots, X_{s}^{n}\right)$,
where for $W \in C_{c}^{2}(A, R: B, D)$ we defined $: F_{W}(X)=\frac{1}{2} \Delta_{V}(W)(X)$.
Proof. Step 1: Obtaining a differential equation from Itô formula.
We have to prove that $\tau\left(\left\langle 1 \otimes_{D} 1, \partial P\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)\right\rangle\right)=\tau\left(\xi_{t}^{i} P\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)\right)$ for an ordinary $B$-non-commutative polynomial $P$ (in the algebra generated by $B, X_{1}, \ldots, X_{n}$ ). Let us write $\delta_{s}$ the following (Malliavin) Derivation operator defined on $B$-non-commutative polynomials in $X_{u}^{i}$ 's (as usual one can assume them algebraically free without loss of generality):

$$
\delta_{s}\left(P\left(X_{s_{1}}^{i_{1}}, \ldots, X_{s_{n}}^{i_{n}}\right)\right)=\sum_{j}\left(\partial_{(j)}(P)\right)\left(X_{s_{1}}^{i_{1}}, \ldots, X_{s_{n}}^{i_{n}}\right)\left(s \wedge s_{j}\right)
$$

where $\partial_{(j)}$ is the $B-E_{D}$-free difference quotient in the $j$-th variable for $P$ (send$\operatorname{ing} X_{s_{j}}^{i_{j}}$ to $\left(1 \otimes_{D} 1\right)_{i_{j}}$ having only an $i_{j}$-th non-zero component). Obviously, $\delta_{t} P\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)=t \partial P\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)$ so that it suffices to show:

$$
\tau\left(\left\langle\left(1 \otimes_{D} 1\right)_{i}, \delta_{s} P\left(X_{s}^{1}, \ldots, X_{s}^{n}\right)\right\rangle\right)-\tau\left(\Xi_{s}^{i} P_{s}\right)=0
$$

for $\Xi_{s}^{i}=X_{s}^{i}-X_{0}^{i}-\int_{0}^{s} d t \frac{t}{2} F_{\mathscr{D}_{i} V}\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)+\frac{s}{2} \mathscr{D}_{i} V\left(X_{s}^{1}, \ldots, X_{s}^{n}\right)$, and any noncommutative polynomial $P_{s}=P\left(X_{s}^{1}, \ldots, X_{s}^{n}\right)$. We will first prove using the Itô formula a differential equation for the above differences.

Applying Itô's formula, one gets ( $\partial_{j}$ the ordinary difference quotient):

$$
\begin{aligned}
P_{t}=P\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)= & P\left(X_{0}^{1}, \ldots, X_{0}^{n}\right)+\int_{0}^{t} d s \frac{1}{2} \Delta_{V}(P)\left(X_{s}^{1}, \ldots, X_{s}^{n}\right) \\
& +\int_{0}^{t} \partial(P)\left(X_{s}^{1}, \ldots, X_{s}^{n}\right) \# d S_{s}
\end{aligned}
$$

Let us write for short $\beta_{s}=\frac{1}{2} \Delta_{V}(P)\left(X_{s}^{1}, \ldots, X_{s}^{n}\right)$.
Thus, let us compute likewise :

$$
\begin{aligned}
\tau\left(P_{t}\left(X_{t}^{i}-X_{0}^{i}\right)\right)= & \int_{0}^{t} d s \tau\left(P_{s}\left(-\frac{1}{2} \mathscr{D}_{i} V\left(X_{s}\right)\right)+\beta_{s}\left(X_{s}^{i}-X_{0}^{i}\right)+\left\langle 1 \otimes_{D} 1, \partial_{i}(P)\left(X_{s}^{1}, \ldots, X_{s}^{n}\right)\right\rangle_{B\langle X\rangle}\right) . \\
\tau\left(P_{t} t \mathscr{D}_{i} V\left(X_{t}\right)\right)= & \int_{0}^{t} d s \tau\left(P_{s} \mathscr{D}_{i} V\left(X_{s}\right)+P_{s} s F_{\mathscr{D}_{i} V}\left(X_{s}^{1}, \ldots, X_{s}^{n}\right)+\beta_{s} s \mathscr{D}_{i} V\left(X_{s}\right)\right) \\
& +\int_{0}^{t} d s \tau\left(\left\langle\partial\left(P^{*}\right)\left(X_{s}^{1}, \ldots, X_{s}^{n}\right), \partial\left(s \mathscr{D}_{i} V\left(X_{s}\right)\right)\right\rangle\right)
\end{aligned}
$$

Thus

$$
\begin{aligned}
\tau\left(P_{t} \Xi_{t}^{i}\right)= & \int_{0}^{t} d s\left(\tau\left(\beta_{s} \Xi_{s}^{i}\right)+\tau\left(\left\langle 1 \otimes_{D} 1, \partial_{i}(P)\left(X_{s}^{1}, \ldots, X_{s}^{n}\right)\right\rangle\right)\right) \\
& -\int_{0}^{t} d s \tau\left(\left\langle\partial\left(P^{*}\right)\left(X_{s}^{1}, \ldots, X_{s}^{n}\right), \partial\left(\frac{s}{2} V_{i}\left(s, X_{s}\right)\right)\right\rangle\right)
\end{aligned}
$$

Using similarly Itô's formula on tensor products:

$$
\begin{aligned}
\tau\left(\left\langle\left(1 \otimes_{D} 1\right)_{i}, \delta_{t} P\right\rangle\right) & =\int_{0}^{t} d s \tau\left(\left\langle\left(1 \otimes_{D} 1\right), \partial_{i}(P)\left(X_{s}\right)\right\rangle_{L^{2}\left(B\left\langle X_{s}\right\rangle, E_{D}\right)}\right) \\
& +\frac{s}{2} \tau\left(\left\langle\left(1 \otimes_{D} 1\right)_{i},\left(\Delta_{V} \otimes 1+1 \otimes \Delta_{V}\right) \partial P\left(X_{s}\right)\right\rangle\right) \\
& =\int_{0}^{t} d s \tau\left(\left\langle\left(1 \otimes_{D} 1\right), \partial_{i}(P)\left(X_{s}\right)\right\rangle_{L^{2}\left(B\left\langle X_{s}\right\rangle, E_{D}\right)}\right) \\
& +\tau\left(\left\langle\left(1 \otimes_{D} 1\right)_{i}, \delta_{s} \beta_{s}-\sum_{j} \partial_{j}\left(P\left(X_{s}\right)\right) \# \frac{1}{2} \delta_{s} \mathscr{D}_{j} V\left(X_{s}\right)\right\rangle\right)
\end{aligned}
$$

where we used the elementary relation applied to a polynomial $P$ :

$$
\left(\Delta_{V} \otimes 1+1 \otimes \Delta_{V}\right) \partial(.)=\partial \Delta_{V}(.)-\sum_{j} \partial_{j}(.) \# \partial \mathscr{D}_{j} V
$$

But of course we can use the fundamental property for cyclic gradients $\partial_{i} \mathscr{D}_{j} V\left(X_{s}\right)=\rho\left(\partial_{j} \mathscr{D}_{i} V\left(X_{s}\right)\right)=\left(\partial_{j} \mathscr{D}_{i} V\left(X_{s}\right)\right)^{*}$ with the rotation $\rho(a \otimes b)=b \otimes a$ extended to cyclic Haagerup tensor products and using $V=V^{*}$. Thus, one gets:

$$
\tau\left(\left\langle\left(1 \otimes_{D} 1\right)_{i}, \sum_{j} \partial_{j}\left(P\left(X_{s}\right)\right) \# \delta_{s} \mathscr{D}_{j} V\left(X_{s}\right)\right\rangle\right)=\sum_{j} s \tau\left(\left\langle\left(1 \otimes_{D} 1\right), \partial_{j}\left(P\left(X_{s}\right)\right) \#\left(\partial_{j} \mathscr{D}_{i} V\left(X_{s}\right)\right)^{*}\right\rangle\right)
$$

Rewritten with the notation of Theorem A.17-A. 20 so that one can use our traciality assumption, this is

$$
\begin{aligned}
& \sum_{j} s\left\langle e_{D}, \partial_{j}\left(P\left(X_{s}\right)\right) \#\left(\partial_{j} \mathscr{D}_{i} V\left(X_{s}\right)\right)^{*} \# e_{D}\right\rangle \\
& =\sum_{j} s\left\langle e_{D}, E_{D^{\prime}}\left(\partial_{j}\left(P\left(X_{s}\right)\right)\right) \#\left(\partial_{j} \mathscr{D}_{i} V\left(X_{s}\right)\right)^{*} \# e_{D}\right\rangle \\
& =\sum_{j} s\left\langle e_{D},\left(\partial_{j} \mathscr{D}_{i} V\left(X_{s}\right)\right)^{*} \# E_{D^{\prime}}\left(\partial_{j}\left(P\left(X_{s}\right)\right)\right) \# e_{D}\right\rangle \\
& =\sum_{j} s\left\langle\left(\partial_{j} \mathscr{D}_{i} V\left(X_{s}\right)\right) \# e_{D}, \partial_{j}\left(P\left(X_{s}\right)\right) \# e_{D}\right\rangle
\end{aligned}
$$

Note that we introduced in the second line the projection on the commutant using the weak-* continuity obtained in Theorem A.19.(2). In the next-to-last line, after using traciality, we used (36). In the last line we removed the conditional expectation using the fact that $\left(\partial_{j} \mathscr{D}_{i} V\left(X_{s}\right)\right) \# e_{D}$ commutes with $D$. Finally, we have $\left(\partial_{j}\left(P\left(X_{s}\right)\right) \# e_{D}\right)^{*}=\partial_{j}\left(P^{*}\left(X_{s}\right)\right) \# e_{D}$ and $\left[\left(\partial_{j} \mathscr{D}_{i} V\left(X_{s}\right)\right) \# e_{D}\right]^{*}=\left(\partial_{j} \mathscr{D}_{i} V\left(X_{s}\right)\right) \# e_{D}$ since $V=V^{*}$ and thus

$$
\left\langle\left(\partial_{j} \mathscr{D}_{i} V\left(X_{s}\right)\right) \# e_{D}, \partial_{j}\left(P\left(X_{s}\right)\right) \# e_{D}\right\rangle=\left\langle\partial_{j}\left(P^{*}\left(X_{s}\right)\right) \# e_{D},\left(\partial_{j} \mathscr{D}_{i} V\left(X_{s}\right)\right) \# e_{D}\right\rangle
$$

We have thus obtained:

$$
\begin{aligned}
& \tau\left(\left\langle\left(1 \otimes_{D} 1\right)_{i}, \delta_{t} P\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)\right\rangle\right)=\int_{0}^{t} d s \tau\left(\left\langle 1 \otimes_{D} 1, \partial_{i} P\left(X_{s}^{1}, \ldots, X_{s}^{n}\right)\right\rangle\right) \\
& \quad+\int_{0}^{t} d s \tau\left(\left\langle\left(1 \otimes_{D} 1\right)_{i}, \delta_{s} \beta_{s}\right\rangle\right)-\int_{0}^{t} d s \tau\left(\left\langle\partial\left(P^{*}\right)\left(X_{s}^{1}, \ldots, X_{s}^{n}\right), \delta_{s} V_{i}\left(s, X_{s}\right)\right\rangle\right)
\end{aligned}
$$

Summing up, we have obtained our "differential equation":

$$
\begin{equation*}
\tau\left(P_{t} \Xi_{t}^{i}\right)-\tau\left(\left\langle S_{i}, \delta_{t} P\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)\right\rangle_{B\left\langle X_{s}\right\rangle}\right)=\int_{0}^{t} d s \tau\left(\beta_{s} \Xi_{s}^{i}\right)-\tau\left(\left\langle S_{i}, \delta_{s} \beta_{s}\right\rangle_{B\left\langle X_{s}\right\rangle}\right) \tag{55}
\end{equation*}
$$

Step 2: Case with $V \in B\left\langle X_{1}, \ldots, X_{n}: D, R, \mathbb{C}\right\rangle$ of finite degree $p+1$ (i.e. "usual" polynomial with all terms in the $\ell^{1}$ direct sum of order higher than $p+2$ vanishing).

Let us write

$$
M_{n}:=n \max _{i}\left\|\mathscr{D}_{i} V\right\|_{B\left\langle X_{1}, \ldots, X_{n}: D, 1, \mathbb{C}\right\rangle}=E n
$$

Let $p$ be the maximum degree of $\mathscr{D}_{i} V$. Let $R \geq \sup _{s \in[0, T], i}\left\|X_{t}^{i}\right\|$.
Let $\tilde{M}_{n}:=M_{n}+2 n\left(\frac{R^{p}}{R^{p}-1}\right)^{2}=D n$. Finally, let $\theta$ a time such that for all monomials $P$, all $t \leq \theta$ we have already established what we want (for instance at the beginning $\theta=0$ ):

$$
\tau\left(P_{t} \Xi_{t}^{i}\right)-\tau\left(\left\langle S_{i}, \delta_{t} P\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)\right\rangle_{B\left\langle X_{s}\right\rangle}\right)=0
$$

Let us show quickly using (55) that for $P$ monomial of degree less than $n=k p$ (with coefficient in extended Haagerup norm less than 1 i.e. of norm less that 1 in $B\left\langle X_{1}, \ldots, X_{n}: D, 1, \mathbb{C}\right\rangle$ ), we have for $t \geq \theta$ (since by definition the left hand side is 0 before) :

$$
\begin{aligned}
& \tau\left(P_{t} \Xi_{t}^{i}\right)-\tau\left(\left\langle S_{i}, \delta_{t} P\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)\right\rangle_{B\left\langle X_{s}\right\rangle}\right) \\
& \quad \leq \frac{(t-\theta)^{l}(C+p T) F^{l}(k+2 l)^{2 l+1}}{2^{l}(l!)^{2}} R^{(k+l) p}=: A_{l}(t, k),
\end{aligned}
$$

where $C=\sup _{[0, T]}\left\|\Xi_{t}^{i}\right\|<\infty$ and $F=\max \left(\frac{p^{2}}{R-1}, E p\right)$.
We prove this by induction on $l$. Initialization at $l=0$ is obvious by boundedness of $X_{t}$ by $R \geq 1$.

To prove induction step, note that $\beta_{s}=\frac{1}{2} \Delta_{V}(P)\left(X_{s}^{1}, \ldots, X_{s}^{n}\right)$ contain two types of terms. The term coming from the first order part is a finite sum monomials of degree less than $(k+1) p$. Each of these terms will be bounded by the induction Assumption at level $l$ by $A_{l}(s, k+1)$ times the norm of the coefficient in the extended Haagerup tensor product, which all sums up to $\max _{i}\left\|\mathscr{D}_{i} V\right\|_{B\left\langle X_{1}, \ldots, X_{n}: D, 1, \mathbb{C}\right\rangle} \leq$ $M_{n} / n=E$. Finally the number of sums due to derivation can always be crudely bounded by $n=k p$, the degree of $P$. We thus obtain a bound $F k A_{l}(s, k+1)$ for this first order term.

The other terms come from the second order derivative, we have of course at most $n(n-1) / 2$ pairs of terms selected by the derivative, but we have to pay attention to their degrees. For sure we have at most $n$ terms with a given space $l \leq n$ between the two $1 \otimes 1$ inserted by the derivative, in that case the degree is at most $k p-l$ after taking the conditional expectation $E_{D}$, and we have a bound by $R^{l}$ to bound the coefficient induced by this conditional expectation (corresponding to the variables $X_{s}$ inside, below $E_{D}$ ). Let us gather terms by taking only into account the integer part $i$ of $l / p$. We have thus at most $n p$ terms with such an integer part, all of degree at most $(k-i) p$, with $R^{i p}$ plus a factor $1, R, \ldots, R^{p-1}$ depending of the exact degree in the group. At the end one obtains:

$$
\begin{aligned}
& \tau\left(P_{t} \Xi_{t}^{i}\right)-\tau\left(\left\langle S_{i}, \delta_{t} P\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)\right\rangle\right) \\
& \quad \leq \int_{\theta}^{t} d s A_{l}(s, k+1) F k+\sum_{i=0}^{k} A_{l}(s, i) n p R^{p(k-i)} \frac{R^{p}-1}{R-1} \\
& \quad \leq \int_{\theta}^{t} d s A_{l}(s, k+1) F k+\sum_{i=0}^{k} A_{l}(s, i) k R^{p(k-i)} F R^{p} .
\end{aligned}
$$

We have just used our induction Assumption and we reorder a bit our expression to factorize powers of R and replace $A_{l}$ by its value to get:

$$
\begin{aligned}
& \tau\left(P_{t} \Xi_{t}^{i}\right)-\tau\left(\left\langle S_{i}, \delta_{t} P\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)\right\rangle_{B\left\langle X_{s}\right\rangle}\right) \\
& \quad \leq F k R^{p(k+1)} \int_{\theta}^{t} d s \frac{A_{l}(s, k+1)}{R^{p(k+1)}}+\sum_{i=0}^{k} \frac{A_{l}(s, i)}{R^{p i}} \\
& \quad \leq F k R^{p(k+1+l)} \int_{\theta}^{t} d s \sum_{i=0}^{k+1}(i+2 l)^{2 l+1} \frac{(s-\theta)^{l}(C+p T) F^{l}}{2^{l}(l!)^{2}} .
\end{aligned}
$$

We can now use comparison of the integral to a Riemann sum:

$$
\sum_{i=0}^{k+1}(i+2 l)^{2 l+1} \leq \sum_{i=1}^{k+1+2 l} i^{2 l+1} \leq \frac{(k+2+2 l)^{2 l+2}}{2 l+2}
$$

Computing the integral, we have therefore proved:

$$
\begin{aligned}
& \tau\left(P_{t} \Xi_{t}^{i}\right)-\tau\left(\left\langle S_{i}, \delta_{t} P\left(X_{t}^{1}, \ldots, X_{t}^{n}\right)\right\rangle_{B\left\langle X_{s}\right\rangle}\right) \\
& \quad \leq F k R^{p(k+1+l)} \frac{(k+2+2 l)^{2 l+2}}{2 l+2} \frac{(t-\theta)^{l+1}(C+p T) F^{l}}{2^{l}(l!)((l+1)!)} \leq A_{l+1}(t, k)
\end{aligned}
$$

Let us finally estimate

$$
A_{l}(t, k)=2 l(C+p T) R^{k p} \frac{((k / 2 l)+1)^{2 l+1}(l)^{2 l}}{(l!)^{2}}\left(4 R^{p} F(t-\theta) / 2\right)^{l}
$$

Note that

$$
((k / 2 l)+1)^{2 l+1} \leq \exp ((2 l+1) k / 2 l) \leq \exp 2 k
$$

and by Stirling's formula

$$
(l)^{2 l} /(l!)^{2} \sim e^{2 l} /(2 \pi l)
$$

we conclude that as soon as $4 R^{p} F(t-\theta) e^{2} / 2<1$, i.e. when $t-\theta<2 / e^{2} 4 R^{p} F$ (independent of $k$ ), $A_{l}(t, k) \rightarrow_{l \rightarrow \infty} 0$, so that one easily deduces by induction one can take $\theta=T$.
Step 3: Case of general $V$.
Take a sequence $V_{n}$ as in step 2 converging to $V$ in $C_{c}^{4}(A, R: B, D)$. Note that we can assume the $V_{n}$ to be $\left(c^{\prime}, R\right)$ h-convex for some $c^{\prime}<c$. Let us write $X_{t}\left(V_{n}\right), X_{t}(V)$ the solutions given by Proposition 5, and call $\Xi_{t}\left(V_{n}\right), \Xi_{t}(V)$ the formulas from step (1) and let us show that

$$
\sup _{t \in[0, T]} \max \left(\left\|X_{t}\left(V_{n}\right)-X_{t}(V)\right\|,\left\|\Xi_{t}\left(V_{n}\right)-\Xi_{t}(V)\right\|\right) \rightarrow_{n \rightarrow \infty} 0
$$

This is roughly the same argument as in the previous subsection for continuity in $\alpha$. Note that

$$
\begin{aligned}
& X_{t}\left(V_{n}\right)-X_{t}(V)=-\frac{1}{2} \int_{0}^{t} d u\left[\mathscr{D} V_{n}-\mathscr{D} V\right]\left(X_{u}(V)\right) \\
& -\frac{1}{2} \int_{0}^{t} d u\left[\int_{0}^{1} d \beta \partial \mathscr{D} V_{n}\left(\beta X_{u}\left(V_{n}\right)+(1-\beta) X_{u}(V)\right)\right] \#\left[X_{u}\left(V_{n}\right)-X_{u}(V)\right]
\end{aligned}
$$

Using the argument in Lemma 4 with $\partial \mathscr{D} V_{\alpha}\left(X_{u}\right)$ replaced by

$$
\left[\int_{0}^{1} d \beta \partial \mathscr{D} V_{n}\left(\beta X_{u}\left(V_{n}\right)+(1-\beta) X_{u}(V)\right)\right] \geq c^{\prime} I d
$$

with the positivity coming since our notion of positivity is a closed convex cone, one gets:

$$
\left\|X_{t}\left(V_{n}\right)-X_{t}(V)\right\| \leq e^{-c^{\prime} t / 2} \int_{0}^{t} d u e^{c^{\prime} u / 2}\left(\sum_{i}\left\|\left[\mathscr{D}_{i} V_{n}-\mathscr{D}_{i} V\right]\left(X_{u}(V)\right)\right\|^{2}\right)^{1 / 2}
$$

This converges uniformly on $[0, T]$ to 0 when $n \rightarrow \infty$ using the corresponding limit $V_{n} \rightarrow V$ and the a priori bounds on the norm of the process $X_{u}(V)$ on $[0, T]$. (Doing this for small $T$ first, this in particular ensures a bound for $X_{t}\left(V_{n}\right)$ for $t$
huge enough without assuming the assumption of Proposition 5(b) for $V_{n}$. ) The convergence of $\Xi\left(V_{n}\right)$ is then straightforward by the explicit formula. We can then take the limit in the conjugate variable equation to conclude.
B.9. Examples of h-convex potentials. We first produce an elementary example in 1 variable.

Lemma B.43. If $v\left(X_{1}\right)=\mu \frac{X_{1}^{2}}{2}+\lambda \frac{X_{1}^{3}}{3}+\nu \frac{X_{1}^{4}}{4} \in \mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle \subset$ $B_{c}\left\langle X_{1}, \ldots, X_{n} ; D, R, \mathbb{C}\right\rangle$ for $\nu>0, \lambda^{2} \leq 8 \mu \nu / 3$, then for any $B, D, v=v^{*} \in$ $C_{c}^{2}(A, R: B, D)$ is $(0, R)$-convex for any $R$.

Proof. From the computation on algebraic tensor products inside cyclic tensor products, in the proof of Proposition A.24, it is clear that $v\left(X_{1}\right) \in$ $B_{c}\left\langle X_{1}, \ldots, X_{n} ; D, R, \mathbb{C}\right\rangle$. Note that
$H\left(X_{1}\right)=\partial_{1} \mathscr{D}_{1} v$
$=\nu\left(X_{1}^{2} \otimes 1+X_{1} \otimes X_{1}+1 \otimes X_{1}^{2}\right)+\lambda\left(X_{1} \otimes 1+1 \otimes X_{1}\right)+\mu 1 \otimes 1$
$=\left(X_{1}+\frac{\lambda}{2 \nu}\right)^{2} \otimes \frac{\nu}{2}+\frac{\nu}{2} \otimes\left(X_{1}+\frac{\lambda}{2 \nu}\right)^{2}+\frac{\nu}{2}\left(X_{1} \otimes 1+1 \otimes X_{1}+\frac{\lambda}{2 \nu} 1 \otimes 1\right)^{2}$ $+\left(\mu-\frac{3 \lambda^{2}}{8 \nu}\right) 1 \otimes 1$.
Thus let $B \subset(M, \tau)$, fix $X_{1}=X_{1}^{*} \in D^{\prime} \cap M$ and let us observe that

$$
e^{-t H\left(X_{1}\right)}=\sum_{k=0}^{\infty} \frac{(-t \nu)^{k}}{k!} e^{-t\left(\nu X_{1}^{2}+\lambda X_{1}+\mu / 2\right)}\left(X_{1}^{k} \otimes X_{1}^{k}\right) e^{-t\left(\nu X_{1}^{2}+\lambda X_{1}+\mu / 2\right)}
$$

belongs to $M \stackrel{\mathrm{D}}{\mathrm{D}} \mathrm{D} M \subset M \stackrel{\mathrm{eh}}{\otimes}{ }_{D} M$.
Of course, the sum even converges in a projective tensor product, and we want to estimate its norm. Recall that

$$
M \stackrel{\mathrm{eh}}{\otimes} M \subset C B_{M^{\prime}, M^{\prime}}\left(D^{\prime} \cap B\left(L^{2}(M)\right), B\left(L^{2}(M)\right) \subset C B\left(B\left(L^{2}(M)\right), B\left(L^{2}(M)\right)\right.\right.
$$

completely isometrically.
We now get an alternative integral formula. For convenience, we let

$$
Y_{1}=\left(X_{1}+\frac{\lambda}{2 \nu}\right) \frac{\sqrt{\nu}}{\sqrt{2}}
$$

Using Cauchy product formula of absolutely converging series, one gets:

$$
\begin{aligned}
e^{-t H\left(X_{1}\right)} & =e^{-\left(\mu-\frac{3 \lambda^{2}}{8 \nu}\right) t} e^{-t Y_{1}^{2}} \sum_{k=0}^{\infty} \frac{\left[-t \nu\left(X_{1} \otimes 1+1 \otimes X_{1}+\frac{\lambda}{2 \nu}\right)^{2} / 2\right]^{k}}{k!} e^{-t Y_{1}^{2}} \\
& =e^{-\left(\mu-\frac{3 \lambda^{2}}{8 \nu}\right) t} \int_{\mathbb{R}} d \sigma e^{-\sigma^{2} / 2} e^{-t Y_{1}^{2}} \sum_{k=0}^{\infty} \frac{\left[i \sqrt{t \nu} \sigma\left(X_{1} \otimes 1+1 \otimes X_{1}+\frac{\lambda}{2 \nu}\right)\right]^{k}}{k!} e^{-t Y_{1}^{2}} \\
& =\frac{e^{-\left(\mu-\frac{3 \lambda^{2}}{8 \nu}\right) t}}{\sqrt{2 \pi}} \int_{\mathbb{R}} d \sigma e^{-\sigma^{2} / 2} e^{-t Y_{1}^{2}} e^{i \sqrt{t \nu} \sigma\left(X_{1} \otimes 1+1 \otimes X_{1}+\frac{\lambda}{2 \nu}\right)} e^{-t Y_{1}^{2}} \\
& =\frac{e^{-\left(\mu-\frac{3 \lambda^{2}}{8 \nu}\right) t}}{\sqrt{2 \pi}} \int_{\mathbb{R}} d \sigma e^{-\sigma^{2} / 2} e^{-t Y_{1}^{2}+i \sqrt{t \nu} \sigma\left(X_{1}+\frac{\lambda}{4 \nu}\right)} \otimes e^{-t Y_{1}^{2}+i \sqrt{t \nu} \sigma\left(X_{1}+\frac{\lambda}{4 \nu}\right)}
\end{aligned}
$$

where the second line is obtained using moments of standard gaussian variables (and Fubini Theorem). Using Hermite polynomials $H_{n}(x)=\frac{(-1)^{n}}{\sqrt{n!}} e^{x^{2} / 2} \frac{d}{d x} e^{-x^{2} / 2}$ as orthonormal basis, and $\xi_{i} \in L^{2}(M)$, one obtains by using the orthogonal decomposition in $L^{2}(d \gamma), d \gamma(\sigma)=e^{-\sigma^{2} / 2} d \sigma / \sqrt{2 \pi}$,

$$
\left\langle\xi_{1}, e^{-t Y_{1}+i \sqrt{t \nu} \sigma\left(X_{1}+\frac{\lambda}{4 \nu}\right)} \xi_{2}\right\rangle=\sum_{n=0}^{\infty} H_{n}(\sigma)\left\langle\xi_{1}, c_{n}\left(X_{1}\right) \xi_{2}\right\rangle
$$

which yields

$$
\begin{aligned}
e^{-t H\left(X_{1}\right)} & =e^{-\left(\mu-\frac{3 \lambda^{2}}{8 \nu}\right) t} \sum_{n=0}^{\infty} c_{n}\left(X_{1}\right) \otimes c_{n}\left(X_{1}\right), \\
c_{n}\left(X_{1}\right) & =\frac{1}{\sqrt{2 \pi}} \int_{\mathbb{R}} d \sigma e^{-\sigma^{2} / 2} H_{n}(\sigma) e^{-t Y_{1}^{2}+i \sqrt{t \nu} \sigma\left(X_{1}+\frac{\lambda}{4 \nu}\right)} .
\end{aligned}
$$

Indeed, to make this identification in $M \otimes_{e h} M=C B_{M^{\prime}, M^{\prime}}\left(K\left(L^{2}(M), B\left(L^{2}(M)\right)\right)\right.$ (see [BP91] for the equality), we first identify the two sides after evaluation on a finite rank operator, say in using the orthogonal decomposition recalled earlier

$$
\begin{aligned}
& \int_{\mathbb{R}} d \gamma(\sigma)\left\langle\xi_{1}, e^{-t Y_{1}^{2}+i \sqrt{t \nu} \sigma\left(X_{1}+\frac{\lambda}{4 \nu}\right)} \xi_{2}\right\rangle\left\langle\xi_{3}, e^{-t Y_{1}^{2}+i \sqrt{t \nu} \sigma\left(X_{1}+\frac{\lambda}{4 \nu}\right)} \xi_{4}\right\rangle \\
& =\sum_{n=0}^{\infty}\left\langle\xi_{1}, c_{n}\left(X_{1}\right) \xi_{2}\right\rangle\left\langle\xi_{3}, c_{n}\left(X_{1}\right) \xi_{4}\right\rangle
\end{aligned}
$$

Then, if both sides extend to compact operators, one obtains the claimed equality. We already said the left hand side does (for instance by our previous bound on $e^{-t H\left(X_{1}\right)}$ obtained from the series expansion) and the right hand side will by our next bound giving the contractivity property.

Thus, for instance from [M05], when $\mu \geq \frac{3 \lambda^{2}}{8 \nu}$ :

$$
\left\|e^{-t H\left(X_{1}\right)}\right\|_{\substack{M \stackrel{\text { eh }}{\otimes} M}} \leq\left\|\sum_{n=0}^{\infty} c_{n}\left(X_{1}\right) c_{n}\left(X_{1}\right)^{*}\right\| .
$$

But note that for $\xi \in L^{2}(M)$, with $\left(e_{j}\right)_{j \in \mathbb{N}}$ an orthonormal basis of this space, we first get using Parseval's equality and the Tonelli-Fubini Theorem to switch the sum over $j$ :

$$
\begin{aligned}
& \int_{\mathbb{R}} d \gamma(\sigma)\left\langle e^{-t Y_{1}^{2}+i \sqrt{t \nu} \sigma\left(X_{1}+\frac{\lambda}{4 \nu}\right)} \xi, e^{-t Y_{1}^{2}+i \sqrt{t \nu} \sigma\left(X_{1}+\frac{\lambda}{4 \nu}\right)} \xi\right\rangle \\
& =\sum_{j} \int_{\mathbb{R}} d \gamma(\sigma)\left\langle e^{-t Y_{1}^{2}+i \sqrt{t \nu} \sigma\left(X_{1}+\frac{\lambda}{4 \nu}\right)} \xi, e_{j}\right\rangle\left\langle e_{j}, e^{-t Y_{1}^{2}+i \sqrt{t \nu} \sigma\left(X_{1}+\frac{\lambda}{4 \nu}\right)} \xi\right\rangle \\
& =\sum_{j} \sum_{n}\left|\left\langle e_{j}, c_{n}\left(X_{1}\right) \xi\right\rangle\right|^{2} \\
& =\sum_{n} \sum_{j}\left|\left\langle e_{j}, c_{n}\left(X_{1}\right) \xi\right\rangle\right|^{2}=\sum_{n}\left\|c_{n}\left(X_{1}\right) \xi\right\|^{2}=\left\langle\xi, \sum_{n=0}^{\infty} c_{n}\left(X_{1}\right)^{*} c_{n}\left(X_{1}\right) \xi\right\rangle
\end{aligned}
$$

where the third line is obtained by using Parseval's equality again, this time on $L^{2}(d \gamma)$, and again the Fubini-Tonelli and Parseval's equalities. Thus, since $\nu>0$ :

$$
\begin{aligned}
\sum_{n=0}^{\infty} c_{n}\left(X_{1}\right)^{*} c_{n}\left(X_{1}\right) & =\frac{1}{\sqrt{2 \pi}} \int_{\mathbb{R}} d \sigma e^{-\sigma^{2} / 2}\left(e^{-t Y_{1}^{2}+i \sqrt{t \nu} \sigma\left(X_{1}+\frac{\lambda}{4 \nu}\right)}\right)^{*} e^{-t Y_{1}^{2}+i \sqrt{t \nu} \sigma\left(X_{1}+\frac{\lambda}{4 \nu}\right)} \\
& =\frac{1}{\sqrt{2 \pi}} \int_{\mathbb{R}} d \sigma e^{-\sigma^{2} / 2} e^{-2 t Y_{1}^{2}}
\end{aligned}
$$

is a contraction and so is $\sum_{n=0}^{\infty} c_{n}\left(X_{1}\right) c_{n}\left(X_{1}\right)^{*}$. Finally, from (35), it is easy to see by truncating the series that $\sigma\left(e^{-t H\left(X_{1}\right)}\right)=e^{-t H\left(X_{1}\right)}$ and this gives:

$$
\left\|e^{-t H\left(X_{1}\right)}\right\|_{\substack{\text { eh } \\ D, c}} \leq 1
$$

In order to deduce a more general example, we need to describe more explicitly the norm structure we put on $M_{n}(M \underset{D, c}{\stackrel{\text { eh }}{\otimes}} M)$ to obtain various contractive maps.

Lemma B.44. There is a completely contractive map

$$
\ell^{\infty}(\llbracket 1, n \rrbracket, M \underset{D, c}{\stackrel{\mathrm{eh}}{\otimes}} M) \rightarrow C B\left(\ell^{2}\left(\llbracket 1, n \rrbracket, M^{\substack{\mathrm{eh} \\ \mathrm{D}, c}} \mathrm{~m}^{\mathrm{D}}\right), \ell^{2}\left(\llbracket 1, n \rrbracket, M^{\substack{\mathrm{eh} \\ \otimes, c \\ D, c}}\right)\right)
$$

corresponding to action by diagonal matrices. Especially, there is a contractive diagonal embedding $\left(\ell^{\infty}(\llbracket 1, n \rrbracket, M \underset{D, c}{\stackrel{\mathrm{eh}}{\otimes}} M)\right) \rightarrow M_{n}(M \underset{D, c}{\stackrel{\mathrm{eh}}{\otimes}} M)$.

Proof. First recall that in $[\mathbf{P}]$, the operator space structure of $\ell^{2}\left(\llbracket 1, n \rrbracket, M^{\substack{\text { eh } \\ \boldsymbol{D}, c}} m^{2}\right)$ is described as the interpolation of $\ell^{\infty}(\llbracket 1, n \rrbracket) \otimes_{\min } M^{\substack{\mathrm{eh} \\ \otimes_{D, c}}}=\ell^{\infty}(\llbracket 1, n \rrbracket) \otimes_{h} M^{\substack{\mathrm{eh} \\ \mathrm{D}, c}} m$ and $\ell^{1}(\llbracket 1, n \rrbracket) \hat{\otimes} M^{\stackrel{\mathrm{eh}}{\otimes, c} m}=\ell^{1}(\llbracket 1, n \rrbracket) \otimes_{h} M^{\substack{\mathrm{eh} \\ \mathrm{Q}, c}}$ (the first equality comes from the fact both operator space product are injective and [ER00, Lemma 9.2.4, Prop 9.3.1] that imply the same result with $\ell^{\infty}(\llbracket 1, n \rrbracket)$ replaced by $M_{n}(\mathbb{C})$, the second equality reduces to the first one after taking duals, the computation of dual of the Haagerup tensor product is known in this case from [ER00, Cor 9.4.8] and for the projective tensor product see [ER00, Prop 8.1.2, 8.1.8]). From the interpolation result of Haagerup tensor products $[\mathbf{P}$, Th 5.22$]$, one deduces the complete isometry $\ell^{2}\left(\llbracket 1, n \rrbracket, M^{\substack{\mathrm{eh} \\ D, c}}\right)=\ell_{o h}^{2}(\llbracket 1, n \rrbracket) \otimes_{h} M^{\substack{\mathrm{eh} \\ \mathrm{D}, c^{\circ} m}}$.

We will start from this description to get our map. From the universal property of the projective tensor product (and agreement of Haagerup and extended Haagerup tensor products in the finite dimensional case), it suffices to get a canonical completely contractive map

To reach this goal, we compose several known complete contractions. First we start with the shuffle map from [Dab15, Lemma 8]:

$$
\begin{aligned}
& \left(\ell^{\infty}(\llbracket 1, n \rrbracket) \otimes_{h} M^{\stackrel{\text { eh }}{\otimes, c} 2}\right) \widehat{\otimes}\left(\ell_{o h}^{2}(\llbracket 1, n \rrbracket) \otimes_{h} M^{\begin{array}{c}
\text { eh } \\
\otimes, c
\end{array}} m\right.
\end{aligned}
$$

We compose this map with a canonical multiplication map $\ell_{o h}^{2}(\llbracket 1, n \rrbracket) \otimes_{h}$ $\ell^{\infty}(\llbracket 1, n \rrbracket) \rightarrow \ell_{o h}^{2}(\llbracket 1, n \rrbracket)$. It is obtained by interpolation from the map $\ell^{\infty}(\llbracket 1, n \rrbracket) \otimes_{h}$ $\ell_{c}^{2}(\llbracket 1, n \rrbracket) \rightarrow \ell_{c}^{2}(\llbracket 1, n \rrbracket)$ from $[\mathbf{B L M}, 3.1 .3$, Prop 3.1.7] and the symmetric map $\ell_{r}^{2}(\llbracket 1, n \rrbracket) \otimes_{h} \ell^{\infty}(\llbracket 1, n \rrbracket) \rightarrow \ell_{r}^{2}(\llbracket 1, n \rrbracket)$ which we interpolate after noticing that $\ell_{c}^{2}(\llbracket 1, n \rrbracket) \otimes_{h} \ell^{\infty}(\llbracket 1, n \rrbracket)=\ell_{c}^{2}(\llbracket 1, n \rrbracket) \otimes_{\min } \ell^{\infty}(\llbracket 1, n \rrbracket)=\ell^{\infty}(\llbracket 1, n \rrbracket) \otimes_{\min } \ell_{c}^{2}(\llbracket 1, n \rrbracket)=$ $\ell^{\infty}(\llbracket 1, n \rrbracket) \otimes_{h} \ell_{c}^{2}(\llbracket 1, n \rrbracket)$. This multiplication of course gives the expected diagonal matrix action.

The multiplication map we finally want $M^{\substack{\mathrm{eh} \\ D, c}} \widehat{\otimes} \widehat{M^{\mathrm{eh}} \underset{\mathrm{D}, c}{ } m} \rightarrow M^{\substack{\mathrm{eh} \\ D, c}}$ is of course the one we built in Proposition A.24.(1). By density of the algebraic tensor product, it suffices to get a contractivity on basic tensors. Since the target norm is induced form $M^{\otimes_{e s h c D m}}$, it suffices to get the contractivity with this target space. This decomposes in various contractivity for each flip (using the fonctoriality of nuclear

 complete contractivity of composition of $C B$ maps.

Lemma B.45. Let $A=\left(A_{i, j}\right) \in M_{n}(\mathbb{R})$ a positive matrix with $A \geq c I_{n}$ and $\left(\lambda_{i, j}\right) \in M_{n, k}(\mathbb{R}), \mu \in\left[0, \infty\left[^{k}, v_{j}(x)=\nu_{j, 2} \frac{x^{2}}{2}+\nu_{j, 3} \frac{x^{3}}{3}+\nu_{j, 4} \frac{x^{4}}{4}\right.\right.$ for $\nu_{j, 4}>0, \nu_{j, 3}^{2} \leq$ $8 \nu_{j, 2} \nu_{j, 4} / 3$. Let

$$
V(X)=\sum_{j=1}^{k} \mu_{j} v_{j}\left(\sum_{i=1}^{n} \lambda_{i, j} X_{i}\right)+\sum_{i, j=1}^{n} A_{i, j} X_{i} X_{j}
$$

Then,for any $B, D, V(X) \in \mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle \subset B_{c}\left\langle X_{1}, \ldots, X_{n} ; D, R, \mathbb{C}\right\rangle, V=V^{*} \in$ $C_{c}^{6}(A, R: B, D)$ is $(c, R)$-h-convex for any $R$.

Moreover, let $P=P^{*} \in \mathbb{C}\left\langle u_{1}, \ldots, u_{n}\right\rangle a *$-polynomial in unitary variables, and define for $\varepsilon>0$

$$
\mathcal{V}(X)=V(X)+\varepsilon P\left(\frac{\sqrt{-1}+X_{1}}{\sqrt{-1}-X_{1}}, \cdots, \frac{\sqrt{-1}+X_{n}}{\sqrt{-1}-X_{n}}\right)
$$

Then, for any $R>0$ and any $c^{\prime} \in[0, c)$, there exists $\varepsilon_{R}>0$ so that for $\varepsilon \in$ $\left[-\varepsilon_{R}, \varepsilon_{R}\right], W \in C_{c}^{6}(A, R: B, D)$ is $\left(c^{\prime}, R\right) h$-convex.

Proof. From the additivity of positivity, the positivity elements form a cone, so that it suffices to consider $k=1$ and even to show that $W(X)=v_{1}\left(\sum_{i=1}^{n} \lambda_{i, 1} X_{i}\right)$
is $(0, R)$ convex. But with the notation of the previous proof

$$
\partial_{i} \mathscr{D}_{j} W=\lambda_{j, 1} \lambda_{i, 1} H\left(\sum_{i=1}^{n} \lambda_{i, 1} X_{i}\right) .
$$

Let us call $P=\sum_{i} \lambda_{i, 1}^{2}>0$. From the previous proof of Lemma B.43, one deduces $\left\|e^{-t H\left(\sum_{i=1}^{n} \lambda_{i, 1} X_{i}\right)}\right\|_{\substack{\text { ch } \\ D, c}}^{\text {eh } M} \leq 1$. Let us fix an orthogonal matrix $O$ with $O_{j, 1}=\lambda_{j, 1} / \sqrt{P}$ and write the matrix $A=\left(\partial_{i} \mathscr{D}_{j} W\right)_{j, i}$ as $A=O\left(O^{*} A O\right) O^{*}$. Note that $\left(O^{*} A O\right)_{j, i}=0$ except for $\left(O^{*} A O\right)_{1,1}=P H\left(\sum_{i=1}^{n} \lambda_{i, 1} X_{i}\right)$. Thus $e^{-t A}=$ $O e^{-t\left(O^{*} A O\right)} O^{*}$. To conclude, note that $O, O^{*}$ are contractions in $M_{n}(M \underset{D, c}{\otimes} M)$ since their action coincides with $O^{\epsilon} \otimes 1$ on $\ell^{2}\left(\llbracket 1, n \rrbracket, M^{\substack{\mathrm{eh} \\ \otimes, c}}\right)=\ell_{o h}^{2}(\llbracket 1, n \rrbracket) \otimes_{h} M^{\stackrel{\mathrm{eh}}{\mathrm{D}, c} m}$. Finally, $e^{-t\left(O^{*} A O\right)}=\operatorname{Diag}\left(e^{-t P H\left(\sum_{i=1}^{n} \lambda_{i, 1} X_{i}\right)}, 1, \ldots, 1\right)$ and each term in the diagonal matrix is a contraction, so that one can apply Lemma B. 44 to conclude to $\left\|e^{-t\left(O^{*} A O\right)}\right\|_{M_{n}(M \underset{\substack{\text { eh } \\ D, c, c}}{\text { en }}} \leq 1$.

We finally consider the case where the polynomial is pertubed. In order to check that $\mathcal{V} \in C_{c}^{6}(A, R: B, D)$, since this space is obviously an algebra, it suffices to check $P_{t}(X)=\frac{1}{t \sqrt{-1}-X_{1}} \in C_{c}^{6}(A, R: B, D)$ for $t>0$. For $t$ large enough, a geometric series converging in $C_{c}^{6}(A, R: B, D)$ shows this. The set of such $t$ is thus non-empty, it is easy to check that $C_{c}^{6}(A, R: B, D)$ has an equivalent Banach algebra norm, then, a Neumann series gives the set of $t$ is open. It remains to see it is closed in $] 0, \infty[$ to get the result by connectivity. An easy computation shows that $\left\|P_{t}\right\|_{6,0, A_{R}^{n}} \leq \sum_{k=0}^{6} 1 / t^{k+1}$ as soon as we showed $P_{t}$ is in the space above, since $\partial_{(1, \ldots, 1)}^{k} P_{t}\left(X_{1}\right)=(k!) P_{t}\left(X_{1}\right)^{\otimes k+1}$. When $t_{n} \rightarrow t>0$, and using

$$
P_{t}\left(X_{1}\right)-P_{s}\left(X_{1}\right)=-P_{t}\left(X_{1}\right)(t-s) \sqrt{-1} P_{s}\left(X_{1}\right)
$$

one easily gets the convergence $\left\|P_{t_{n}}-P_{t}\right\|_{6,0, A_{R}^{n}} \rightarrow 0$ (in getting a Cauchy sequence and identifying the limit with $P_{t}$ ). It only remains to check the stated $h$-convexity. It suffices to take the coefficients of $P$ small enough so that $b=\left(\partial_{i} \mathscr{D}_{j}(\mathcal{V}-V)\right)_{j, i}$ has a norm $\|b\|:=\|b\|_{M_{n}(M \underset{D, c}{\text { eh }} M)}<c$ and in this case $c^{\prime}=c-\|b\|$ is appropriate. Indeed, let $a=\left(\partial_{i} \mathscr{D}_{j}(V)\right)_{j, i}$, we can use the Dyson series:
$e^{-t(a+b)}=e^{-t a}+\sum_{k=1}^{\infty} \int_{0}^{t} d s_{1} \int_{0}^{s_{1}} d s_{2} \cdots \int_{0}^{s_{k-1}} d s_{k} e^{-\left(t-s_{1}\right) a} b e^{-\left(s_{1}-s_{2}\right) a} \cdots b e^{-\left(s_{k-1}-s_{k}\right) a} b e^{-s_{k} a}$,
and one obtains:


It remains to check the other assumptions on $\mathcal{V}$. We need variants of results from [GMS06, Th 3.4] and [GS09].

Proposition B.46. Let $V$ be of the form of $\mathcal{V}$ in Lemma B.45, and $(c, R) h$ convex for all $R>0$. Consider the probability on $\left(M_{N}(\mathbb{C})_{\text {sa }}\right)^{n}$ given (for some normalization constant $Z_{V, N}$ ) by :

$$
\mu_{V, N}(d x)=\frac{1}{Z_{V, N}} e^{-N \operatorname{Tr}\left(V\left(X_{1}, . ., X_{n}\right)\right)} d \operatorname{Leb}_{\left(M_{N}(\mathbb{C})_{s a}\right)^{n}}(d X)
$$

Let $A_{1}^{N}, \ldots, A_{n}^{N}$ of law $\mu_{V, N}$ (on a same probability space), we have a constant $C>0$ such that almost surely:

$$
\limsup _{N \rightarrow \infty} \max _{i}\left\|A_{i}^{N}\right\|_{\infty} \leq C
$$

and for $K \in I N^{*}$

$$
\begin{equation*}
\limsup _{N \rightarrow \infty} E_{\mu_{V, N}}\left(1_{\left\{\left\|A_{i, l}^{N}\right\|_{\infty} \geq C\right\}} \frac{1}{N} \operatorname{Tr}\left(\left(A_{i, l}^{N}\right)^{2 K}\right)\right)=0 \tag{56}
\end{equation*}
$$

Moreover, for any non-commutative polynomial $P \in \mathbb{C}\langle X\rangle \otimes_{\text {alg }} \mathbb{C}\langle X\rangle$
$\lim _{N \rightarrow \infty} \left\lvert\, E_{\mu_{V, N}}\left(\left.\frac{1}{N^{2}}(\operatorname{Tr} \otimes \operatorname{Tr})\left(P\left(A_{1}, \ldots, A_{k}\right)\right)-\frac{1}{N^{2}}\left[\left(E_{\mu_{V, N}} \circ \operatorname{Tr}\right) \otimes\left(E_{\mu_{V, N}} \circ \operatorname{Tr}\right)\right](P) \right\rvert\,=0\right.\right.$.
Proof. The proof is identical to [GMS06, Th 3.4] since $X_{1}, \ldots, X_{n} \mapsto$ $\operatorname{Tr} V\left(X_{1}, \ldots, X_{n}\right)$ is convex, with Hessian bounded below by $c$, on the space of Hermitian matrices. In fact, one can check that any $h$-convex function $V$ satisfies this property.

Theorem B.47. Let $V$ be of the form of $\mathcal{V}$ in Lemma B.45, and $(0, R) h$-convex for all $R$. Consider, the law absolutely continuous with respect to the law $P_{G^{N}}$ of GUE $G^{N}$ :

$$
d \mu_{V, N}(X)=\frac{1}{Z_{V, N}} e^{-N T r\left(V\left(X_{1}, . ., X_{n}\right)\right)} d P_{G^{N}}(X)
$$

Then $E_{\mu_{V, N}} \circ \frac{1}{N} \operatorname{Tr}$ converges in law to a tracial state $\tau_{V}$ which is the law of selfadjoint variables $X(V)$ (of norm bounded by some $R$ ) and the unique solution with this property to the equation $\left(S D_{V}\right)$, for $G(X)=\tau_{X}(V)$ :

$$
\forall P \in \mathbb{C}\left\langle X_{1}, \ldots, X_{n}\right\rangle, \quad\left(\tau_{V} \otimes \tau_{V}\right)\left(\partial_{X_{i}}(P)\right)=\tau_{V}\left(X_{i} P\right)+\tau_{V}\left(\mathcal{D}_{i} V P\right)
$$

Moreover, there is a solution on $\mathbb{R}_{+}$given by Proposition 5 with potential $V_{0}+V$ and $\tau_{V}$ is the unique stationary $R^{\omega}$-embeddable trace for this free SDE.

Note that the $R^{\omega}$-embeddability assumption in the uniqueness is not really necessary, but we stick to that case in order to be consistent and to use our previous setting.

Proof. Step 1: Defining limit variables in a von Neumann algebra ultraproduct.
Consider a non-principal ultrafilter $\omega$ on $\mathbb{N}$ and the tracial von Neumann algebra ultraproducts $\mathcal{L}^{\omega}=L^{2}\left(M_{N}\left(L^{\infty}\left(\mu_{V, N}\right)\right)^{\omega}, \mathcal{M}^{\omega}=M_{N}\left(L^{\infty}\left(\mu_{V, N}\right)\right)^{\omega}\right.$. Considering $A_{1}^{N}, \ldots, A_{n}^{N}$ the canonical hermitian variables in $M_{N}\left(L^{\infty}\left(\mu_{V, N}\right)\right)$, we know from (56) that $\left\|A_{i}^{N} 1_{\left\{\left\|A_{i}^{N}\right\| \leq C\right\}}-A_{i}^{N}\right\|_{2} \rightarrow 0$ so that $X_{i}^{\omega}=\left(A_{i}^{N}\right)^{\omega}=\left(A_{i}^{N} 1_{\left\{\left\|A_{i}^{N}\right\| \leq C\right\}}\right)^{\omega} \in \mathcal{M}^{\omega}$. We thus also fix $B_{i}^{N}=A_{i}^{N} 1_{\left\{\left\|A_{i}^{N}\right\| \leq C\right\}}$.

This gives a tracial state $\tau_{X^{\omega}}$. Let us check that any such state satisfies $\left(S D_{V}\right)$.
Step 2: Showing $\left(S D_{V}\right)$.

As in [GMS06], we use an integration by parts formula on $\mu_{V, N}$ which gives $\forall P \in \mathbb{C}\left\langle X_{1}, \ldots, X_{m}\right\rangle:$

$$
\begin{aligned}
E_{\mu_{V, N}} & \left(\frac{1}{N} \operatorname{Tr}\left(A_{i}^{N} P\left(A_{1}^{N}, \ldots, A_{m}^{N}\right)\right)+\frac{1}{N} \operatorname{Tr}\left(N \nabla_{A_{i}^{N}} G\left(A_{1}^{N}, \ldots, A_{m}^{N}\right) P\left(A_{1}^{N}, \ldots, A_{m}^{N}\right)\right)\right) \\
& =E_{\mu_{V, N}}\left(\left(\frac{1}{N} \operatorname{Tr} \otimes \frac{1}{N} \operatorname{Tr}\right)\left(\partial_{X_{i}} P\right)\left(A_{1}^{N}, \ldots, A_{m}^{N}\right)\right)
\end{aligned}
$$

and the second concentration result in Proposition B. 46 implies that the right hand side converges when $N \rightarrow \omega$ to $\left(\tau_{X^{\omega}} \otimes \tau_{X^{\omega}}\right)\left(\partial_{i}(P)\right)$. One thus obtains the relation in taking of limit to $\omega$ of the integration by parts relation. Moreover, note that this implies $\tau_{X^{\omega}}$ has finite Fisher information.
Step 3: Properties and use of the SDE.
Let $X_{0}=X^{\omega}$ or a $R^{\omega}$-embeddable solution of $\left(S D_{V}\right)$, which ensures $X_{0} \in$ $A_{R / 3, A p p}^{n}$ in the scalar case $B=\mathbb{C}$. The application of our Proposition 5 thus gives a unique solution $X_{t}\left(X_{0}\right)$ on $[0, \infty[$ solving

$$
X_{t}\left(X_{0}\right)=X_{0}-\frac{1}{2} \int_{0}^{t} \mathcal{D} V\left(X_{s}\left(X_{0}\right)\right) d s-\frac{1}{2} \int_{0}^{t} X_{s}\left(X_{0}\right) d s+S_{t}
$$

Considering another solution starting at $Y_{0}$, one obtains:

$$
\left\|X_{t}\left(X_{0}\right)-X_{t}\left(Y_{0}\right)\right\|_{2}^{2} \leq e^{-c t}\left\|X_{0}-Y_{0}\right\|_{2}^{2}
$$

Then exponential decay implies that the laws $\tau_{X_{t}\left(X^{\omega}\right)}$ and $\tau_{X_{t}\left(X^{\left.\omega^{\prime}\right)}\right.}$ are arbitrarily close for $t \rightarrow \infty$ and since they are equal to $\tau_{X^{\omega}}$ and $\tau_{X^{\omega^{\prime}}}$ by stationarity, one deduces that $X^{\omega}$ have the same law for any ultrafilter. Similarly, $\left(S D_{V}\right)$ has a unique $R^{\omega}$-embeddable solution and the exponential decay implies a stationary state for the SDE is unique too.

Step 4: Conclusion on the limit of $E_{\mu_{V, N}} \circ \tau$.
The law $E_{\mu_{V, N}} \circ \frac{1}{N} \operatorname{Tr}$ is close to $E_{\mu_{V, N}} \circ \tau_{B^{N}}$ for $N$ large enough and this second law lies in the compact set $\mathcal{S}_{C}^{n}$ (tracial state space of the universal free product $C([-C, C])^{* n}$ with the weak-* topology) and from the result on ultrafilter limits the sequence has a unique limit point there (any such limit point being a $\tau_{X^{\omega}}$ ). We thus deduce by compactness the claimed convergence.

Corollary B.48. Let $V, V+W$ be of the form of $\mathcal{V}$ in Lemma B.45, and thus $(c, R)$ $h$-convex for all $R$ and some $c>0$. Then they satisfy Assumption 4.
Proof. The application of the previous Theorem gives existence of solution of $\left(S D_{V_{\alpha}}\right), \alpha \in[0,1]$ which is $R^{\omega}$-embeddable or equivalently $L\left(F_{\infty}\right)^{\omega}$-embeddable which is a reformulation of $A_{R, U_{\text {ltra } A p p}}^{n}$ in the case $B=\mathbb{C}$. Everything else comes from Lemma B. 45 and stability of $(c, R)$ h-convexity under taking convex combinations.

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Université de Lyon
Université Lyon 1
Institut Camille Jordan UMR 5208
43 blvd. du 11 novembre 1918
F-69622 Villeurbanne cedex
France
dabrowski@math.univ-lyon1.fr

Université de Lyon
Ecole Normale Superieure
46 allée d'Italie, 69007
Lyon
France
alice.guionnet@ens-lyon.fr

Department of Mathematics
UCLA
Los Angeles
CA 90095
USA
shlyakht@math.ucla.edu

